

# A High-Level Approach to the Synthesis of High-Performance Codes for Quantum Chemistry

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# Problem Domain: High-Accuracy Quantum Chemical Methods

- Coupled cluster methods are widely used for very high quality electronic structure calcs.
- Typical Laplace factorized CCSD(T) term:

$$A3A = \frac{1}{2} ( X_{ce,af} Y_{ae,cf} + X_{\bar{ce},\bar{af}} \bar{Y}_{\bar{ae},\bar{cf}} + X_{\bar{ce},\bar{af}} \bar{Y}_{\bar{ae},\bar{cf}} \\ + X_{\bar{ce},\bar{af}} \bar{Y}_{\bar{ae},\bar{cf}} + X_{\bar{ce},\bar{af}} \bar{Y}_{\bar{ae},\bar{cf}} + X_{\bar{ce},\bar{af}} \bar{Y}_{\bar{ae},\bar{cf}} )$$

$$X_{ce,af} = t_{ij}^{ce} t_{ij}^{af}$$

$$Y_{ae,cf} = \langle ab \| ek \rangle \langle cb \| fk \rangle$$

*Typical methods will have tens to hundreds of such terms*

- Indices  $i, j, k$   $O(O=100)$  values,  $a, b, c, e, f$   $O(V=3000)$
- Term costs  $O(OV^5) \approx 10^{19}$  FLOPs; Integrals  $\sim 1000$  FLOPs each
- $O(V^4)$  terms  $\sim 500$  TB memory each

# Problems

## Complexity of Methods

- Implementation takes months
- Experimentation required to develop new methods

## Complexity of Computers

- Different architectures have significantly different performance characteristics

## What's Novel?

## Code generation merely for productivity, historically

- Imitate what researcher would do – but quicker

## We treat as a computer science problem

- Like a compiler
- Algorithmic choices explored rigorously and exhaustively

# Our Solution

## "Tensor Contraction Engine"

- Tensor contraction expressions as input
- (Fortran) source code as output

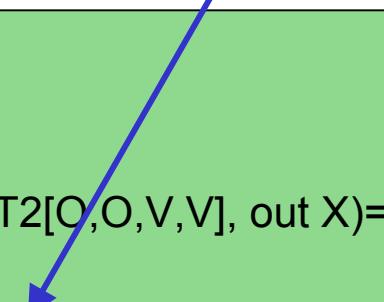
## Generated code increases productivity

Optimize generated code for target computer

# A High-Level Language for Tensor Contraction Expressions

```
range V = 3000;  
range O = 100;  
  
index a,b,c,d,e,f : V;  
index i,j,k : O;  
  
mlimit = 1000000000000;  
  
function F1(V,V,V,O);  
function F2(V,V,V,O);  
  
procedure P(in T1[O,O,V,V], in T2[O,O,V,V], out X)=  
begin  
    X == sum[ sum[F1(a,b,f,k) * F2(c,e,b,k), {b,k}]  
              * sum[T1[i,j,a,e] * T2[i,j,c,f], {i,j}],  
              {a,e,c,f}];  
end
```

$$\begin{aligned} A3A &= \frac{1}{2} (X_{ce,af} Y_{ae,cf} + X_{\bar{c}\bar{e},\bar{a}\bar{f}} Y_{\bar{a}\bar{e},\bar{c}\bar{f}} + X_{\bar{c}\bar{e},af} Y_{\bar{a}\bar{e},cf} \\ &\quad + X_{\bar{c}\bar{e},\bar{a}\bar{f}} Y_{\bar{a}\bar{e},\bar{c}\bar{f}} + X_{\bar{c}\bar{e},\bar{a}\bar{f}} Y_{\bar{a}\bar{e},\bar{c}f} + X_{\bar{c}\bar{e},\bar{a}\bar{f}} Y_{\bar{a}\bar{e},\bar{c}\bar{f}}) \\ X_{ce,af} &= t_{ij}^{ce} t_{ij}^{af} \quad Y_{ae,cf} = \langle ab \| ek \rangle \langle cb \| fk \rangle \end{aligned}$$



# CCSD Doubles Equation

```

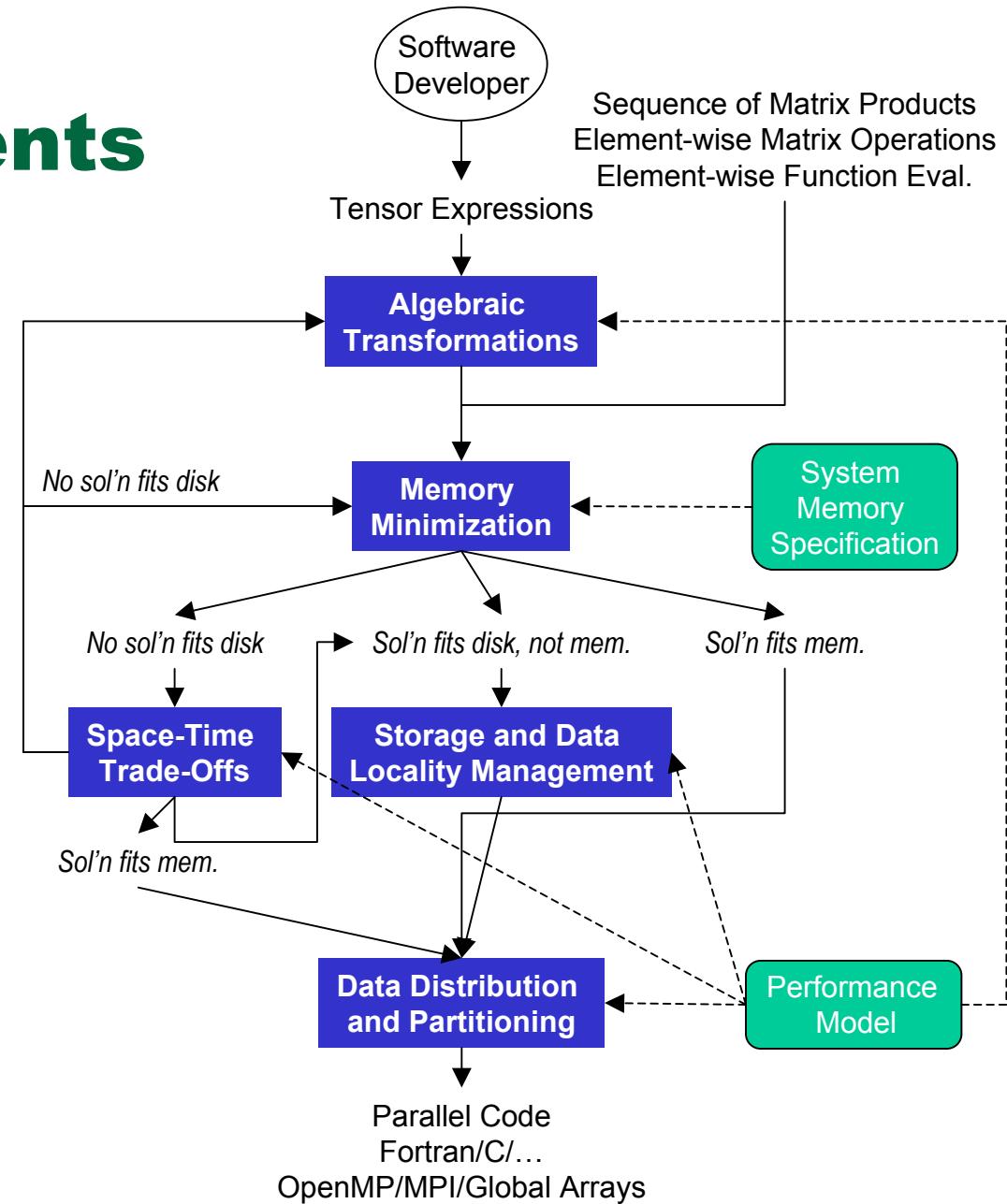
hbar[a,b,i,j] == sum[f[b,c]*t[i,j,a,c],{c}] -sum[f[k,c]*t[k,b]*t[i,j,a,c],{k,c}] +sum[f[a,c]*t[i,j,c,b],{c}] -sum[f[k,c]*t[k,a]*t[i,j,c,b],{k,c}] -
sum[f[k,j]*t[i,k,a,b],{k}] -sum[f[k,c]*t[j,c]*t[i,k,a,b],{k,c}] -sum[f[k,i]*t[j,k,b,a],{k}] -sum[f[k,c]*t[i,c]*t[j,k,b,a],{k,c}]
+sum[t[i,c]*t[j,d]*v[a,b,c,d],{c,d}] +sum[t[i,j,c,d]*v[a,b,c,d],{c,d}] +sum[t[j,c]*v[a,b,i,c],{c}] -sum[t[k,b]*v[a,k,i,j],{k}]
+sum[t[i,c]*v[b,a,j,c],{c}] -sum[t[k,a]*v[b,k,j,i],{k}] -sum[t[k,d]*t[i,j,c,b]*v[k,a,c,d],{k,c,d}] -sum[t[i,c]*t[j,k,b,d]*v[k,a,c,d],{k,c,d}] -
sum[t[j,c]*t[k,b]*v[k,a,c,i],{k,c}] +2*sum[t[j,k,b,c]*v[k,a,c,i],{k,c}] -sum[t[j,k,c,b]*v[k,a,c,i],{k,c}] -sum[t[i,c]*t[j,d]*t[k,b]*v[k,a,d,c],{k,c,d}]
+2*sum[t[k,d]*t[i,j,c,b]*v[k,a,d,c],{k,c,d}] -sum[t[k,b]*t[j,c,d]*v[k,a,d,c],{k,c,d}] -sum[t[i,c]*t[j,k,d,b]*v[k,a,d,c],{k,c,d}] -
sum[t[i,c]*t[k,b]*v[k,a,j,c],{k,c}] -sum[t[i,k,c,b]*v[k,a,j,c],{k,c}] -sum[t[i,c]*t[j,d]*t[k,a]*v[k,b,c,d],{k,c,d}] -
sum[t[k,d]*t[i,j,a,c]*v[k,b,c,d],{k,c,d}] -sum[t[k,a]*t[i,j,c,d]*v[k,b,c,d],{k,c,d}] +2*sum[t[j,d]*t[i,k,a,c]*v[k,b,c,d],{k,c,d}] -
sum[t[j,d]*t[i,k,c,a]*v[k,b,c,d],{k,c,d}] -sum[t[i,c]*t[j,k,d,a]*v[k,b,c,d],{k,c,d}] -sum[t[i,c]*t[k,a]*v[k,b,c,j],{k,c}]
+2*sum[t[i,k,a,c]*v[k,b,c,j],{k,c}] -sum[t[i,k,c,a]*v[k,b,c,j],{k,c}] +2*sum[t[k,d]*t[i,j,a,c]*v[k,b,d,c],{k,c,d}] -
sum[t[j,d]*t[i,k,a,c]*v[k,b,d,c],{k,c,d}] -sum[t[j,c]*t[k,a]*v[k,b,i,c],{k,c}] -sum[t[i,k,a,c]*v[k,b,j,c],{k,c}]
+sum[t[i,c]*t[j,d]*t[k,a]*t[j,b]*v[k,l,c,d],{k,l,c,d}] -2*sum[t[k,d]*t[i,j,c,b]*v[k,l,c,d],{k,l,c,d}] -
2*sum[t[k,a]*t[l,d]*t[i,j,c,b]*v[k,l,c,d],{k,l,c,d}] +sum[t[k,a]*t[l,b]*t[i,j,c,d]*v[k,l,c,d],{k,l,c,d}] -
2*sum[t[j,c]*t[l,d]*t[i,k,a,b]*v[k,l,c,d],{k,l,c,d}] -2*sum[t[j,d]*t[i,k,a,c]*v[k,l,c,d],{k,l,c,d}]
+sum[t[j,d]*t[i,b]*t[i,k,c,a]*v[k,l,c,d],{k,l,c,d}] -2*sum[t[i,c]*t[l,d]*t[j,k,b,a]*v[k,l,c,d],{k,l,c,d}] +sum[t[i,c]*t[l,a]*t[j,k,b,d]*v[k,l,c,d],{k,l,c,d}]
+sum[t[i,c]*t[l,b]*t[i,k,d,a]*v[k,l,c,d],{k,l,c,d}] +sum[t[i,k,c,d]*t[j,l,b,a]*v[k,l,c,d],{k,l,c,d}] +4*sum[t[i,k,a,c]*t[j,l,b,d]*v[k,l,c,d],{k,l,c,d}] -
2*sum[t[i,k,c,a]*t[j,l,b,d]*v[k,l,c,d],{k,l,c,d}] -2*sum[t[i,k,a,b]*t[j,l,c,d]*v[k,l,c,d],{k,l,c,d}] -2*sum[t[i,k,a,c]*t[j,l,d,b]*v[k,l,c,d],{k,l,c,d}]
+sum[t[i,k,c,a]*t[j,l,d,b]*v[k,l,c,d],{k,l,c,d}] +sum[t[i,c]*t[j,d]*t[k,l,a,b]*v[k,l,c,d],{k,l,c,d}] +sum[t[i,j,c,d]*t[k,l,a,b]*v[k,l,c,d],{k,l,c,d}] -
2*sum[t[i,j,c,b]*t[k,l,a,d]*v[k,l,c,d],{k,l,c,d}] -2*sum[t[i,j,a,c]*t[k,l,b,d]*v[k,l,c,d],{k,l,c,d}] +sum[t[j,c]*t[k,b]*t[l,a]*v[k,l,c,i],{k,l,c}]
+sum[t[l,c]*t[j,k,b,a]*v[k,l,c,i],{k,l,c}] -2*sum[t[l,a]*t[j,k,b,c]*v[k,l,c,i],{k,l,c}] +sum[t[l,a]*t[j,k,c,b]*v[k,l,c,i],{k,l,c}]
+sum[t[l,c]*t[j,k,b,a]*v[k,l,c,i],{k,l,c}] +sum[t[k,a]*t[j,l,b,c]*v[k,l,c,i],{k,l,c}] +sum[t[k,b]*t[j,l,c,a]*v[k,l,c,i],{k,l,c}]
+sum[t[j,c]*t[j,k,a,b]*v[k,l,c,i],{k,l,c}] +sum[t[i,c]*t[k,a]*t[l,b]*v[k,l,c,j],{k,l,c}] +sum[t[i,c]*t[k,a,b]*v[k,l,c,j],{k,l,c}] -
2*sum[t[l,b]*t[i,k,a,c]*v[k,l,c,i],{k,l,c}] +sum[t[l,b]*t[i,k,c,a]*v[k,l,c,j],{k,l,c}] +sum[t[i,c]*t[l,k,a,b]*v[k,l,c,j],{k,l,c}]
+sum[t[j,c]*t[l,d]*t[i,k,a,b]*v[k,l,d,c],{k,l,c,d}] +sum[t[j,d]*t[l,b]*t[i,k,a,c]*v[k,l,d,c],{k,l,c,d}] +sum[t[j,d]*t[l,a]*t[i,k,c,b]*v[k,l,d,c],{k,l,c,d}] -
2*sum[t[i,k,c,d]*t[j,l,b,a]*v[k,l,d,c],{k,l,c,d}] -2*sum[t[i,k,a,c]*t[j,l,b,d]*v[k,l,d,c],{k,l,c,d}] +sum[t[i,k,c,a]*t[j,l,b,d]*v[k,l,d,c],{k,l,c,d}] +
sum[t[i,k,a,b]*t[j,l,c,d]*v[k,l,d,c],{k,l,c,d}] +sum[t[i,k,c,b]*t[j,l,d,a]*v[k,l,d,c],{k,l,c,d}] +sum[t[i,k,a,c]*t[j,l,d,b]*v[k,l,d,c],{k,l,c,d}]
+sum[t[k,a]*t[l,b]*v[k,l,i,j],{k,l}] +sum[t[k,l,a,b]*v[k,l,i,j],{k,l}] +sum[t[k,b]*t[l,d]*t[i,j,a,c]*v[i,k,c,d],{k,l,c,d}]
+sum[t[k,a]*t[l,d]*t[i,j,c,b]*v[i,k,c,d],{k,l,c,d}] +sum[t[i,c]*t[l,d]*t[i,j,b,a]*v[i,k,c,d],{k,l,c,d}] -2*sum[t[i,c]*t[l,a]*t[j,k,b,d]*v[i,k,c,d],{k,l,c,d}]
+sum[t[i,c]*t[l,a]*t[j,k,d,b]*v[i,k,c,d],{k,l,c,d}] +sum[t[i,j,c,b]*t[k,l,a,d]*v[i,k,c,d],{k,l,c,d}] +sum[t[i,j,a,c]*t[k,l,b,d]*v[i,k,c,d],{k,l,c,d}] -
2*sum[t[i,c]*t[i,k,a,b]*v[i,k,c,j],{k,l,c}] +sum[t[i,b]*t[i,k,a,c]*v[i,k,c,j],{k,l,c}] +sum[t[i,k,c,b]*v[i,k,c,j],{k,l,c}] +v[a,b,i,j]

```

In the coupled cluster method with single and double excitations (CCSD) the “singles” and “doubles” equations are iterated until convergence and that solution is used to evaluate the molecular energy

# TCE Components

- Algebraic Transformations
  - Minimize operation count
- Memory Minimization
  - Reduce intermediate storage
- Space-Time Transformation
  - Trade-offs btw storage and recomputation
- Storage Management and Data Locality Optimization
  - Optimize use of storage hierarchy
- Data Distribution and Partitioning
  - Optimize parallel layout



# Algebraic Transformations: Operation Minimization

$$S(a,b,i,j) = \sum_{c,d,e,f,k,l} A(a,c,i,k)B(b,e,f,l)C(d,f,j,k)D(c,d,e,l)$$

- Requires  $4 * N^{10}$  operations if indices  $a-l$  have range  $N$
- Using associative, commutative, distributive laws acceptable
- Optimal formula sequence requires only  $6 * N^6$  operations

$$T1(b,c,d,f) = \sum_{e,l} B(b,e,f,l)D(c,d,e,l)$$

$$T2(b,c,j,k) = \sum_{d,f} T1(b,c,d,f)C(d,f,j,k)$$

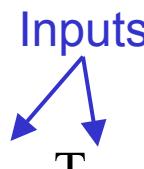
$$S(a,b,i,j) = \sum_{c,k} T2(b,c,j,k)A(a,c,i,k)$$

# Operation Minimal Form

for a, e, c, f

  [ for i, j

Inputs



    [ X<sub>aecf</sub> += T<sub>ijae</sub> T<sub>ijcf</sub>

for c, e, b, k

  [ T<sub>1cebk</sub> = f1(c, e, b, k)

for a, f, b, k

  [ T<sub>2afbk</sub> = f2(a, f, b, k)

for c, e, a, f

  [ for b, k

External  
function calls



    [ Y<sub>ceaf</sub> += T<sub>1cebk</sub> T<sub>2afbk</sub>

for c, e, a, f

Output



  [ E += X<sub>aecf</sub> Y<sub>ceaf</sub>

array	space	time
X	V <sup>4</sup>	V <sup>4</sup> O <sup>2</sup>
T1	V <sup>3</sup> O	C <sub>f1</sub> V <sup>3</sup> O
T2	V <sup>3</sup> O	C <sub>f2</sub> V <sup>3</sup> O
Y	V <sup>4</sup>	V <sup>5</sup> O
E	1	V <sup>4</sup>

a .. f: range V = 1000 .. 3000

i .. k: range O = 30 .. 100

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# Memory-Minimal Form

for a, f, b, k

$$\boxed{\quad \quad T2_{afbk} = f2(a, f, b, k)}$$

for c, e

for b, k

$$\boxed{\quad \quad \quad T1_{bk} = f1(c, e, b, k)}$$

for a, f

for i, j

$$\boxed{\quad \quad \quad \quad X += T_{ijae} T_{ijcf}}$$

for b, k

$$\boxed{\quad \quad \quad \quad Y += T1_{bk} T2_{afbk}}$$

$$\boxed{\quad \quad \quad E += X Y}$$

Fusion of loops allows reduction of rank of arrays

array	space	time
X	1	$V^4 O^2$
T1	$VO$	$C_{f1} V^3 O$
T2	$V^3 O$	$C_{f2} V^3 O$
Y	1	$V^5 O$
E	1	$V^4$

a .. f: range  $V = 3000$

i .. k: range  $O = 100$

# Redundant Computation Allows Full Fusion

for a, e, c, f

  for i, j

$X += T_{ijae} T_{ijcf}$

  for b, k

$T1 = f1(c, e, b, k)$

$T2 = f2(a, f, b, k)$

$Y += T1 T2$

$E += X Y$

array	space	time
X	1	$V^4 O^2$
T1	1	$C_{f1} V^5 O$
T2	1	$C_{f2} V^5 O$
Y	1	$V^5 O$
E	1	$V^4$

# Tiling to Reduce Recomputation

for  $a^t, e^t, c^t, f^t$

for  $a, e, c, f$

for  $i, j$

$$X_{aecf} += T_{ijae} T_{ijcf}$$

for  $b, k$

for  $c, e$

$$T1_{ce} = f1(c, e, b, k)$$

for  $a, f$

$$T2_{af} = f2(a, f, b, k)$$

for  $c, e, a, f$

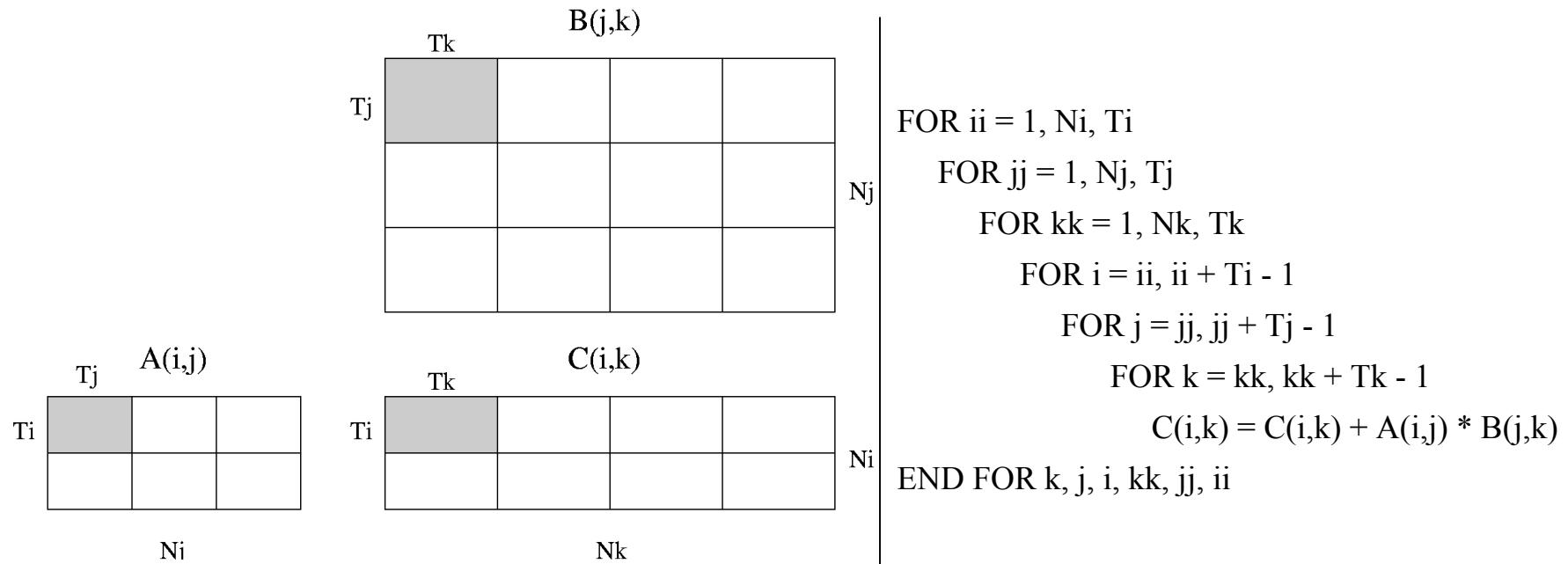
$$Y_{ceaf} += T1_{ce} T2_{af}$$

for  $c, e, a, f$

$$E += X_{aecf} Y_{ceaf}$$

array	space	time
X	$B^4$	$V^4 O^2$
T1	$B^2$	$C_{f1}(V/B)^2 V^3 O$
T2	$B^2$	$C_{f2}(V/B)^2 V^3 O$
Y	$B^4$	$V^5 O$
E	1	$V^4$

# Tiling to Minimize Memory Access Time



Choose  $T_i$ ,  $T_j$ , and  $T_k$  such that  $T_i * T_j + T_i * T_k + T_j * T_k < \text{cache size}$   
 Number of cache misses:

- $A(i,j)$ :  $N_i * N_j$
- $B(j,k)$ :  $N_j * N_k * N_i / T_i$
- $C(i,k)$ :  $N_i * N_k * N_j / T_j$

Same algorithm used to manage locality in disk-based algorithms

# The TCE in Operation

```

range V = 3000;
range O = 100;

index a,b,c,d,e,f : V;
index i,j,k : O;

mlimit = 1000000000000;

function F1(V,V,V,O);
function F2(V,V,V,O);

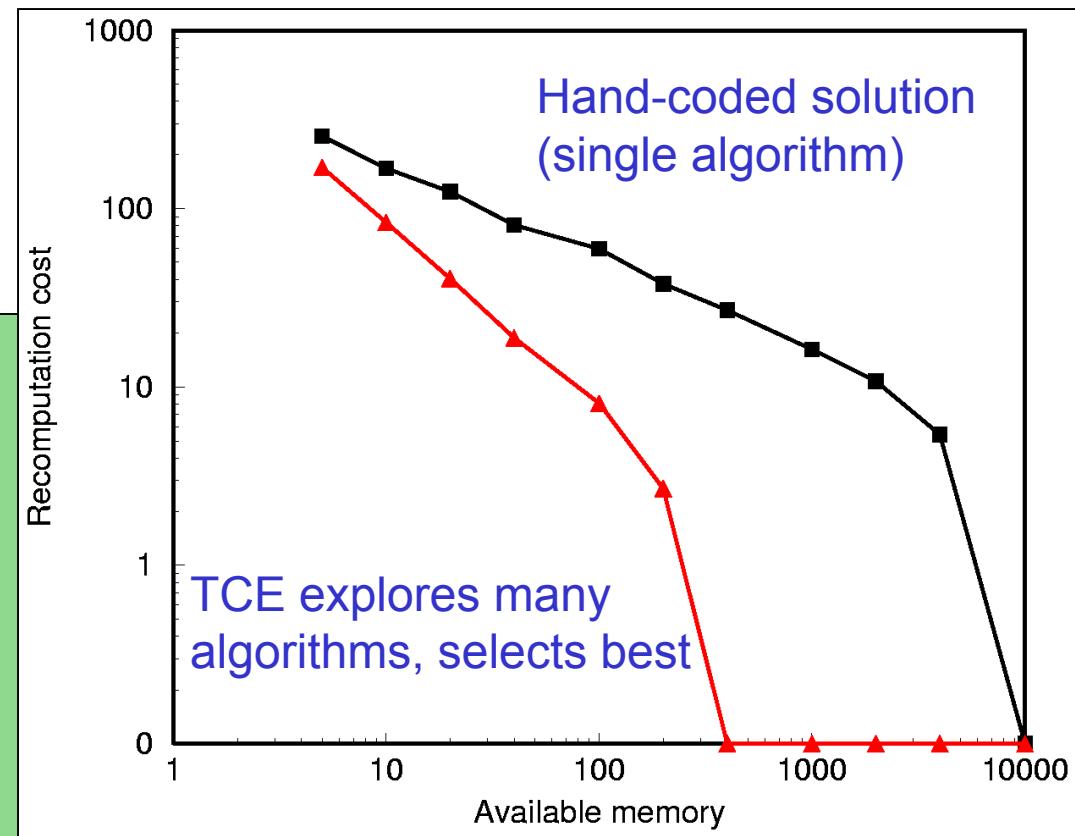
```

procedure P(in T1[O,O,V,V], in T2[O,O,V,V], out X)=

```

begin
  X == sum[ sum[ F1(a,b,f,k) * F2(c,e,b,k), {b,k}]
            * sum[ T1[i,j,a,e] * T2[i,j,c,f], {i,j}],
            {a,e,c,f}];
end

```



$$\begin{aligned}
 A3A &= \frac{1}{2} (X_{ce,af} Y_{ae,cf} + X_{ce,af} Y_{ae,cf} + X_{ce,af} Y_{ae,cf} \\
 &\quad + X_{ce,af} Y_{ae,cf} + X_{ce,af} Y_{ae,cf} + X_{ce,af} Y_{ae,cf}) \\
 X_{ce,af} &= t_{ij}^{ce} t_{ij}^{af} \qquad \qquad Y_{ae,cf} = \langle ab \| ek \rangle \langle cb \| fk \rangle
 \end{aligned}$$

# Work in Progress and Planned

- Parallel code generation
  - Data distribution interacts w/ memory minimization and are being combined
  - Multi-level parallelism
- More sophisticated performance models
- Common sub-expression elimination
  - Greatly increases complexity of operation min.
- Chemistry-specific optimizations
- Develop approximate algorithms for opt.
  - Address situations where exhaustive search too expensive
  - Deliver best result spending at most 15 min on code gen.
  - Deliver best result spending at most 3 days on code gen.

# Summary

- Automatic generation of code from high-level algebraic expressions
  - Approach problem like a compiler
  - Use of HLL allows automation of design decisions usually made by human software developer
- Addresses productivity, complexity, and performance
- Strong interdisciplinary collaboration between chemists and computer scientists
  - Problem from chemists, solutions from computer scientists (w/ significant help from chemists)

## For more information

<http://www.cis.ohio-state.edu/~gb/TCE>

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