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# FLANGE: A Computer Program for the Analysis of Flanged Joints with Ring-Type Gaskets

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FLANGE: A COMPUTER PROGRAM FOR THE ANALYSIS  
OF FLANGED JOINTS WITH RING-TYPE GASKETS

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## FOREWORD

The work reported here was performed at Oak Ridge National Laboratory and at Battelle-Columbus Laboratories under Union Carbide Corp., Nuclear Division, Subcontract No. 2913 as part of the ORNL Design Criteria for Piping and Nozzles Program, S. E. Moore, Manager. This program is funded by the Division of Reactor Safety Research (RSR) of the U.S. Nuclear Regulatory Commission as part of a cooperative effort with industry to develop and verify analytical methods for assessing the safety of pressure-vessel and piping-system design. The cognizant RSR project engineer is E. K. Lynn. The cooperative effort is coordinated through the Pressure Vessel Research Committee of the Welding Research Council under the Subcommittee on Piping, Pumps, and Valves.

The study described in this report was conducted under the general direction of W. L. Greenstreet and S. E. Moore, Solid Mechanics Department, Reactor Division, ORNL, and is a continuation of work supported in prior years by the Division of Reactor Research and Development, U.S. Energy Research and Development Administration (formerly the USAEC).

Prior reports and open-literature publications in this series are:

1. W. L. Greenstreet, S. E. Moore, and E. C. Rodabaugh, "Investigations of Piping Components, Valves, and Pumps to Provide Information for Code Writing Bodies," ASME Paper 68-WA/PTC-6, American Society of Mechanical Engineers, New York, Dec. 2, 1968.
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## 1. INTRODUCTION

### Purpose and Scope

The *ASME Boiler and Pressure Vessel Code*<sup>1</sup> gives rules for designing bolted flange connections with ring-type gaskets based on a stress analysis developed by Waters et al.<sup>2</sup> These rules give formulas and graphs for calculating stresses due to a moment applied to the flange ring. The Code rules, however, do not require that stresses due to internal pressure be taken into account, although Ref. 2 briefly discusses such stresses.

The computer program FLANGE was written to calculate not only the stresses due to moment loads on the flange ring but also stresses due to internal pressure; stresses due to a temperature difference between the hub and ring; and stresses due to the variations in bolt load that result from pressure, hub-ring temperature gradient, and/or bolt-ring temperature difference. The program FLANGE is applicable to tapered-hub, straight, and blind flanges. The analysis method is based on the differential equations for thin plates and shells rather than on the strain-energy method used by Waters et al.<sup>2</sup> The stresses due to moment loading calculated by the two methods are essentially identical for identical boundary conditions. The analysis provided herein also includes a different, and perhaps more realistic, set of boundary conditions than those used in Ref. 2.

The nomenclature used in this report is identified in the remainder of this chapter. In Chapter 2 a description of the general model of flanges used in the theoretical development of the computer code is provided. The actual mathematical expressions for calculating stresses and displacements due to moment and pressure loads are derived in Chapters 3, 4, and 5 for tapered-hub, straight hub, and blind flanges, respectively. In Chapters 6 and 7, these expressions are extended to include the effects of thermal gradients and variations in bolt loads. The computer program FLANGE is described in the last chapter of this report. Example calculations, listings, and flowcharts of the program and its subroutines are included as appendices.

Nomenclature

- $a$  = outside radius of ring  
 $A$  =  $2a$  = outside diameter of ring  
 $A_b$  = cross-sectional bolt area  
 $A_g$  = gasket area  
 $b$  = inside radius of ring and mean radius of pipe  
 $B$  =  $2b$  = inside diameter of ring  
 $b_n$  = Bessel function of  $n$   
 $c$  = bolt-circle radius  
 $C$  =  $2c$  = bolt-circle diameter  
 $C_i$  = constant of integration  
 $C'_i = C_i/b$   
 $D = Et^3/12(1 - \nu^2)$   
 $D_{ij}$  = constants of integration (blind-flange analysis)  
 $E = E_f$  = modulus of elasticity of flange material  
 $E_b$  = modulus of elasticity of bolt material  
 $E_g$  = modulus of elasticity of gasket material  
 $f$  = ASME Code design parameter  
 $F$  = ASME Code design parameter  
 $g_0$  = wall thickness of pipe  
 $g_1$  = wall thickness of hub at intersection with ring  
 $g$  = gasket centerline radius  
 $G = 2g$  = gasket centerline diameter  
 $h$  = length of tapered-wall hub  
 $K = a/b = A/B$   
 $l_0$  = bolt length  
 $M$  = total moment applied to ring, in.-lb  
 $M_i$  or  $M_{ij}$  = moment resultants, in.-lb/in.  
 $p$  = internal pressure  
 $P_i$  = shear resultants, lb/in.  
 $p^* = \frac{[1 - (\nu/2)]bp}{g_0E}$  = nondimensional pressure parameter  
 $r$  = radial coordinate, ring

$t$  = ring thickness  
 $t_x$  = hub thickness  
 $u$  = radial displacement, hub  
 $u_1$  = radial displacement, pipe  
 $u_r$  = radial displacement, ring  
 $V$  = ASME Code design parameter  
 $v_0$  = undeformed gasket thickness  
 $w$  = axial displacement, ring  
 $W_1$  = initial bolt load, lb  
 $W_2$  = residual bolt load, lb  
 $x$  = axial coordinate, hub  
 $x_1$  = axial coordinate, pipe  
 $\alpha = (g_1 - g_0)/g_0 = \rho - 1$  = nondimensional wall-thickness parameter  
 $\beta = [3(1 - \nu^2)/b^2g_0^2]^{1/4}$  = dimensional parameter used in the analysis  
 $\gamma = [12(1 - \nu^2)/b^2g_0^2]^{1/4}(h)$  = dimensional parameter used in the analysis  
 $\Delta$  = temperature difference between hub/pipe and ring  
 $\delta_i$  = axial displacement of ring  
 $\epsilon_f$  = coefficient of thermal expansion, flange material  
 $\epsilon_b$  = coefficient of thermal expansion, bolt material  
 $\epsilon_g$  = coefficient of thermal expansion, gasket material  
 $\eta = 2\gamma(\psi/\alpha)^{1/2}$  = nondimensional argument of the modified Bessel functions  
 $\nu$  = Poisson's ratio (0.3 used herein)  
 $\xi = x/h$  = nondimensional distance parameter  
 $\rho = g_1/g_0$  = nondimensional wall-thickness parameter  
 $\sigma$  = stress, with subscripts:  
 $\ell$  = longitudinal (pipe or hub)  
 $c$  = circumferential (pipe or hub)  
 $t$  = tangential (ring)  
 $r$  = radial (ring)  
 $b$  = bending  
 $m$  = membrane  
 $o$  = outside surface of the pipe or hub on the hub side of ring  
 $i$  = inside surface of the pipe or hub on the gasket-face side of ring  
 $\psi = \xi + (1/\alpha)$  = nondimensional parameter

## 2. GENERAL DESCRIPTION OF THE ANALYSIS

The model used for the analysis of tapered-hub flanges is shown in Fig. 1. The three parts involved are the pipe, hub, and ring, respectively. The analysis presented here is based on the theory of thin plates and shells. The pipe is considered to be a uniform-wall-thickness cylindrical shell with midsurface radius  $b$ . The hub is considered to be a linearly variable-wall-thickness cylindrical shell with midsurface radius  $b$ . The ring is considered to be a flat annular plate with constant thickness  $t$ , inside radius  $b$ , and outside radius  $a$ . The effects of the bolt holes are neglected.

Three different types of loadings on bolted flanges are considered:

1. Bolt load, represented by  $W$  in Fig. 1. In application, the moment  $M$  applied to the flange ring is converted into an equivalent bolt load by the relationship  $W(a - b) = M$ . This is the same approach used in the ASME Code calculation method.<sup>1</sup>

2. Internal pressure, acting radially on the pipe, hub, and ring and axially on an (assumed remote) end closure on the pipe.

3. A temperature difference between the pipe and the ring. The pipe and the hub are assumed to be at the same uniform temperature. The ring is also assumed to be at a uniform temperature, which may be different from that of the pipe or hub.

Upon integration of the shell and plate differential equations, algebraic equations in terms of dimensions, materials properties and loadings, and 12 integration constants are obtained, 4 for each part. These constants are evaluated by the usual discontinuity analysis method of writing continuity equations at the junctures of the parts and at the boundaries. After numerical values are determined for the constants, the algebraic equations provide the means for computing the stresses and deflections. In the development of the equations for stresses, the assumption is made that the bolt load  $W$  does not change with pressure or temperature. Later the analysis is modified to include changes in  $W$  as a function of these loadings. Because the relations are linear, it is possible to determine the stresses (or stress range) due to combinations

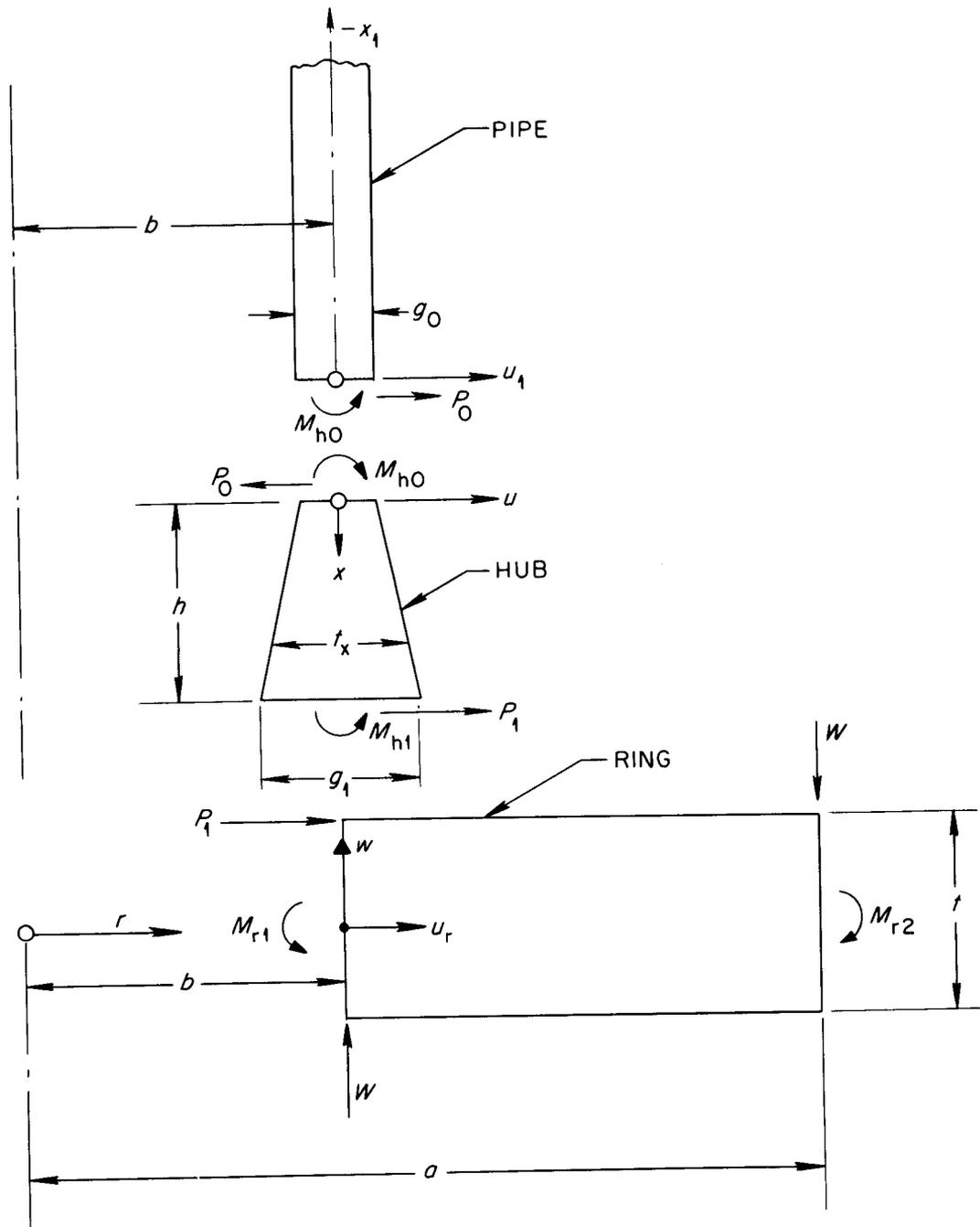


Fig. 1. Analysis model of a tapered-hub flange.

of initial bolt loading, pressure, and temperature change. The model used for straight-hub flanges is a simplification of the tapered-hub case in that only two parts are involved, the pipe and the ring.

In common with all shell-type analyses, the analysis gives anomalous results at points of abrupt thickness change or meridional direction change. In particular, the stresses at the juncture of the hub to the ring represent only the gross loading effect; detailed local stresses are not determined by the theory. Displacements, however, are represented fairly accurately.

### 3. FLANGE WITH A TAPERED-WALL HUB

The first step in deriving the stress equations is to state the basic shell/plate equations for the ring, the hub, and the pipe. We then inspect the boundary conditions, compute the constants, and calculate the stresses and displacements.

#### Equations for the Annular Ring

The basic differential equation for the displacement  $w$  of a circular plate given by Timoshenko<sup>3</sup> is

$$\frac{1}{r} \frac{d}{dr} \left\{ r \frac{d}{dr} \left[ \frac{1}{r} \frac{d}{dr} \left( r \frac{dw}{dr} \right) \right] \right\} = \frac{q}{D}, \quad (1)$$

where the coordinate  $r$  and displacement  $w$  are illustrated in Fig. 1 and  $q$  = a uniformly distributed lateral load on the plate,  $D = Et^3/12(1 - \nu^2)$  = the flexural rigidity of the plate,  $E$  = modulus of elasticity of the flange material,  $t$  = plate thickness, and  $\nu$  = Poisson's ratio. Equation (1) can be integrated to give a relation for the displacement in terms of arbitrary constants:

$$w = C_7 r^2 \ln r + C_8 r^2 + C_9 \ln r + C_{10} + \frac{r^4 q}{64D}, \quad (2)$$

where numerical values for the constants  $C_7, \dots, C_{10}$  are established from boundary conditions. Derivatives of  $w$ , required in the subsequent analysis, are:

$$\frac{dw}{dr} = C_7(2r \ln r + r) + 2C_8 r + \frac{C_9}{r} + \frac{r^3 q}{16D}, \quad (3)$$

$$\frac{d^2 w}{dr^2} = C_7(2 \ln r + 3) + 2C_8 - \frac{C_9}{r^2} + \frac{3r^2 q}{16D}, \quad (4)$$

and

$$\frac{d^3w}{dr^3} = C_7 \left( \frac{2}{r} \right) + \frac{2C_9}{r^3} + \frac{3rq}{8D} . \quad (5)$$

In the subsequent analysis the distributed load  $q$  is taken as zero.

The radial and tangential moments are given<sup>3</sup> by the equations:

$$M_r = -D \left( \frac{d^2w}{dr^2} + \frac{\nu}{r} \frac{dw}{dr} \right) \quad (6)$$

and

$$M_t = -D \left( \frac{1}{r} \frac{dw}{dr} + \nu \frac{d^2w}{dr^2} \right) . \quad (7)$$

Using Eqs. (3) and (4), these moments can be expressed as

$$M_r = -D \left\{ C_7[2(1 + \nu) \ln r + (3 + \nu)] + C_8[2(1 + \nu)] - C_9 \left( \frac{1 - \nu}{r^2} \right) \right\} \quad (8)$$

and

$$M_t = -D \left\{ C_7[2(1 + \nu) \ln r + (1 + 3\nu)] + C_8[2(1 + \nu)] + C_9 \left( \frac{1 - \nu}{r^2} \right) \right\} . \quad (9)$$

#### Equations for the Tapered Hub

The basic differential equation for the radial displacement  $u$  of a cylindrical shell with a linearly variable wall thickness  $t_x$  is given by Timoshenko<sup>3</sup> as

$$\frac{d^2}{dx^2} \left( t_x^3 \frac{d^2u}{dx^2} \right) + \frac{12(1 - \nu^2)t_x u}{b^2} - \frac{12(1 - \nu^2)[1 - (\nu/2)]p}{E} = 0 . \quad (10)$$

The solution of Eq. (10) can be shown\* to be:

$$u = \frac{b}{\psi^{1/2}} (C_1 b_1 + C_2 b_2 + C_3 b_3 + C_4 b_4) + \frac{bP^*}{1 + \alpha\xi} , \quad (11)$$

where  $P^* = [1 - (\nu/2)]bp/g_0E$ . Derivatives of  $u$ , required in the subsequent analysis, are

$$u' = \frac{du}{dx} = \frac{b}{2\psi^{3/2}h} (C_1 b_5 + C_2 b_6 + C_3 b_7 + C_4 b_8) - \frac{b\alpha P^*}{h(1 + \alpha\xi)^2} , \quad (12)$$

$$u'' = \frac{d^2u}{dx^2} = \frac{b}{4\psi^{5/2}h^2} (C_1 b_9 + C_2 b_{10} + C_3 b_{11} + C_4 b_{12}) + \frac{2b\alpha^2 P^*}{h^2(1 + \alpha\xi)^3} , \quad (13)$$

and

$$u''' = \frac{d^3u}{dx^3} = \frac{b}{8\psi^{7/2}h^3} (C_1 b_{13} + C_2 b_{14} + C_3 b_{15} + C_4 b_{16}) - \frac{6r\alpha^2 P^*}{h^3(1 + \alpha\xi)^4} . \quad (14)$$

The  $b_n$ 's used in Eqs. (11) through (14) are modified Bessel functions of argument  $\eta = 2\gamma(\psi/\alpha)^{1/2}$  defined in Table 1, which gives equations for  $n = 1$  through 20;  $\psi$ ,  $\alpha$ , and  $\xi$  are defined in the nomenclature.

---

\* A solution to an equation that is essentially the same as Eq. (10) is given by Timoshenko,<sup>3</sup> who credits the original solution to G. Kirchoff in 1879.

Table 1. Modified Bessel functions of argument  $\eta^\alpha$ 


---

$b_1 = \text{ber}' \eta$
$b_2 = \text{bei}' \eta$
$b_3 = \text{ker}' \eta$
$b_4 = \text{kei}' \eta$
$b_5 = -\eta \text{bei} \eta - 2 \text{ber}' \eta$
$b_6 = \eta \text{ber} \eta - 2 \text{bei}' \eta$
$b_7 = -\eta \text{kei} \eta - 2 \text{ker}' \eta$
$b_8 = \eta \text{ker} \eta - 2 \text{kei}' \eta$
$b_9 = 4\eta \text{bei} \eta + 8 \text{ber}' \eta - \eta^2 \text{bei}' \eta$
$b_{10} = -4\eta \text{ber} \eta + 8 \text{bei}' \eta + \eta^2 \text{ber}' \eta$
$b_{11} = 4\eta \text{kei} \eta + 8 \text{ker}' \eta - \eta^2 \text{kei}' \eta$
$b_{12} = -4\eta \text{ker} \eta + 8 \text{kei}' \eta + \eta^2 \text{ker}' \eta$
$b_{13} = -\eta^3 \text{ber} \eta - 24\eta \text{bei} \eta - 48 \text{ber}' \eta + 8\eta^2 \text{bei}' \eta$
$b_{14} = -\eta^3 \text{bei} \eta + 24\eta \text{ber} \eta - 48 \text{bei}' \eta - 8\eta^2 \text{ber}' \eta$
$b_{15} = -\eta^3 \text{ker} \eta - 24\eta \text{kei} \eta - 48 \text{ker}' \eta + 8\eta^2 \text{kei}' \eta$
$b_{16} = -\eta^3 \text{kei} \eta + 24\eta \text{ker} \eta - 48 \text{kei}' \eta - 8\eta^2 \text{ker}' \eta$
$b_{17} = -\eta \text{ber} \eta + 2 \text{bei}' \eta$
$b_{18} = -\eta \text{bei} \eta - 2 \text{ber}' \eta$
$b_{19} = -\eta \text{ker} \eta + 2 \text{kei}' \eta$
$b_{20} = -\eta \text{kei} \eta - 2 \text{ker}' \eta$

---

<sup>$\alpha$</sup> The argument  $\eta = 2\gamma(\psi/\alpha)^{1/2}$ , where  $\gamma = [12(1 - \nu^2)/b^2g_0^2]^{1/4}(h)$ ,  
 $\psi = \xi + (1/\alpha)$ ,  $\xi = x/h$ , and  $\alpha = (g_1 - g_0)/g_0$ .

Equations for the Pipe

The basic differential equation for the radial displacement  $u_1$  of a cylindrical shell with uniform wall thickness is:

$$g_0^3 \frac{d^4 u_1}{dx_1^4} + \frac{12(1 - \nu^2)g_0}{b^2} u_1 - \frac{12(1 - \nu^2)[1 - (\nu/2)]p}{E} = 0 . \quad (15)$$

The solution of Eq. (15) is:

$$u_1 = e^{-\beta x_1} (C_{11} \sin \beta x_1 + C_{12} \cos \beta x_1) + e^{\beta x_1} (C_5 \sin \beta x_1 + C_6 \cos \beta x_1) + bP^* . \quad (16)$$

For large negative values of  $x_1$ ,  $u_1 = bP^*$ . Hence,  $C_{11} = C_{12} = 0$ . Derivatives of  $u_1$  needed in the subsequent analysis are

$$u_1' = \frac{du_1}{dx_1} = \beta e^{\beta x_1} [C_5 (\sin \beta x_1 + \cos \beta x_1) + C_6 (\cos \beta x_1 - \sin \beta x_1)] , \quad (17)$$

$$u_1'' = \frac{d^2 u_1}{dx_1^2} = 2\beta^2 e^{\beta x_1} [C_5 \cos \beta x_1 - C_6 \sin \beta x_1] , \quad (18)$$

and

$$u_1''' = \frac{d^3 u_1}{dx_1^3} = -2\beta^3 e^{\beta x_1} [C_5 (\sin \beta x_1 - \cos \beta x_1) + C_6 (\sin \beta x_1 + \cos \beta x_1)] . \quad (19)$$

Boundary Conditions

The equations listed above involve ten unknown constants:  $C_1, C_2, \dots, C_{10}$ . These can be determined from the ten boundary-condition

equations shown in Table 2 [Eq. (20)]. The ASME Code stress-calculation method<sup>1</sup> is based on the assumption that the radial displacement at the hub-to-ring juncture is zero. A more realistic assumption (particularly for internal pressure loading) is that the displacement of the hub equals the displacement of the surface of the ring where it joins the hub. Boundary-condition equations for both of these alternatives are provided in Table 2. [See Eqs. (20-5).] In Eq. (20-5b) a positive  $dw/dr$  gives a negative radial displacement at the surface of the ring adjacent to the hub. Also in Eq. (20-5b),  $u_r$  is the radial expansion of the ring due to internal pressure as given by Lamé's equation:

$$u_r = \frac{b}{E} \left[ \frac{(1 + \nu)k^2 + (1 - \nu)}{k^2 - 1} \right] \left( p - \frac{P_1}{t} \right), \quad (21)$$

where  $k = a/b$ . In this expression, it is assumed that in addition to internal pressure  $p$ , the shear resultant  $P_1$  is uniformly distributed around the inner edge of the ring.

#### Boundary Equations

When the equations in Table 2 are satisfied simultaneously, they establish the values of the ten constants ( $C_1, C_2, \dots, C_{10}$ ) in terms of the dimensions, Poisson's ratio, and the loads (total bolt load  $W$  and internal pressure  $p$ ). After algebraic manipulation, the equations are reduced to the forms shown in Table 3. This table provides the elements for the matrix equation  $[A]|C| + |B| = 0$ , where the terms in the coefficient matrix  $[A]$  are given under the headings of the corresponding constants in the column matrix  $|C|$ . The loading parameters constitute the column matrix  $|B|$ .

To derive numerical values for the constants, three items should be noted.

1. It is convenient to define two new constants,  $C'_5 = C_5/b$  and  $C'_6 = C_6/b$ .
2. The radial expansion of the ring  $u_r$  is defined in Eq. (21).

Table 2. Equations for the boundary conditions for a tapered-hub flange

	Hub-to-pipe juncture		Hub-to-ring juncture		Ring	
	Equation	Eq. No.	Equation	Eq. No.	Equation	Eq. No.
Displacements <sup>a</sup>	$(u)_{x=0} = (u_1)_{x_1=0}$	(20-1)	$\begin{cases} (u)_{x=h} = 0 \\ (u)_{x=h} = \left( u_r - \frac{t}{2} \frac{dw}{dr} \right)_{r=b} \end{cases}$	(20-5a) (20-5b)	$(w)_{r=b} = 0$ (Footnote b)	(20-8)
Rotations	$(u')_{x=0} = (u'_1)_{x_1=0}$	(20-2)	$(u')_{x=h} = \left( \frac{dw}{dr} \right)_{r=b}$	(20-6)		
Moments <sup>c</sup>	$(u'')_{x=0} = (u''_1)_{x_1=0}$	(20-3)	$M_{h1} = -M_{r1} + \frac{1}{2} P_1 t$ (Footnote d)	(20-7)	$M_{r2} = 0$	(20-9)
Shears	$\left( \frac{3\alpha}{h} u''' + u'''' \right)_{x=0} = (u''''_1)_{x_1=0}$	(20-4)			$Q = -\frac{dM_r}{dr} + \frac{M_t}{r} - \frac{M_r}{r} = \frac{W}{2\pi r}$	(20-10)

<sup>a</sup>Radial for hub-to-pipe and hub-to-ring junctures and axial for the ring.

<sup>b</sup>Setting  $(w)_{r=b}$  equal to zero provides a reference point for all other axial displacements.

<sup>c</sup>Radial for ring.

<sup>d</sup>The assumption is that the shear  $P_1$  of the hub on the ring produces an additional moment on the ring.

Table 3. Matrix coefficients of the discontinuity equations<sup>a</sup> for a flange with a tapered-wall hub

Eq. No.	C <sub>1</sub>	C <sub>2</sub>	C <sub>3</sub>	C <sub>4</sub>	C <sub>5</sub> '	C <sub>6</sub> '	C <sub>7</sub>	C <sub>8</sub>	C <sub>9</sub>	C <sub>10</sub>	Loading parameters
(20-1) <sup>b</sup>	b <sub>1</sub> <sup>0</sup>	b <sub>2</sub> <sup>0</sup>	b <sub>3</sub> <sup>0</sup>	b <sub>4</sub> <sup>0</sup>	0	-ψ <sub>0</sub> <sup>1/2</sup>	0	0	0	0	0
(20-2)	b <sub>5</sub> <sup>0</sup>	b <sub>6</sub> <sup>0</sup>	b <sub>7</sub> <sup>0</sup>	b <sub>8</sub> <sup>0</sup>	$-\frac{\eta_0 \psi_0^{1/2}}{\sqrt{2}}$	$-\frac{\eta_0 \psi_0^{1/2}}{\sqrt{2}}$	0	0	0	0	-2ψ <sub>0</sub> <sup>1/2</sup> P*
(20-3)	b <sub>9</sub> <sup>0</sup>	b <sub>10</sub> <sup>0</sup>	b <sub>11</sub> <sup>0</sup>	b <sub>12</sub> <sup>0</sup>	-η <sub>0</sub> <sup>2</sup> ψ <sub>0</sub> <sup>1/2</sup>	0	0	0	0	0	8ψ <sub>0</sub> <sup>1/2</sup> P*
(20-4)	b <sub>17</sub> <sup>0</sup>	b <sub>18</sub> <sup>0</sup>	b <sub>19</sub> <sup>0</sup>	b <sub>20</sub> <sup>0</sup>	$-\frac{\eta_0 \psi_0^{1/2}}{\sqrt{2}}$	$\frac{\eta_0 \psi_0^{1/2}}{\sqrt{2}}$	0	0	0	0	0
(20-5a) <sup>c</sup>	b <sub>1</sub> '	b <sub>2</sub> '	b <sub>3</sub> '	b <sub>4</sub> '	0	0	0	0	0	0	(ψ <sub>1</sub> <sup>1/2</sup> /b) (bP*/ρ)
(20-5b) <sup>d</sup>	b <sub>1</sub> ' + U <sub>1</sub> b <sub>5</sub> ' - U <sub>2</sub> U <sub>3</sub> b <sub>17</sub> '	b <sub>2</sub> ' + U <sub>1</sub> b <sub>6</sub> ' - U <sub>2</sub> U <sub>3</sub> b <sub>18</sub> '	b <sub>3</sub> ' + U <sub>1</sub> b <sub>7</sub> ' - U <sub>2</sub> U <sub>3</sub> b <sub>19</sub> '	b <sub>4</sub> ' + U <sub>1</sub> b <sub>8</sub> ' - U <sub>2</sub> U <sub>3</sub> b <sub>20</sub> '	0	0	0	0	0	0	(ψ <sub>1</sub> <sup>1/2</sup> /b) (bP*/ρ) - U <sub>3</sub> P + U <sub>4</sub>
(20-6)	b <sub>5</sub> '	b <sub>6</sub> '	b <sub>7</sub> '	b <sub>8</sub> '	0	0	$-2\psi_1^{3/2} h \times$ (2 ln h + 1)	$-4\psi_1^{3/2} h$	$-2\psi_1^{3/2} h/b^2$	0	-2ψ <sub>1</sub> <sup>1/2</sup> P*/ρ
(20-7) <sup>d</sup>	b <sub>9</sub> ' + U <sub>5</sub> b <sub>17</sub> '	b <sub>10</sub> ' + U <sub>5</sub> b <sub>18</sub> '	b <sub>11</sub> ' + U <sub>5</sub> b <sub>19</sub> '	b <sub>12</sub> ' + U <sub>5</sub> b <sub>20</sub> '	0	0	U <sub>6</sub> [2(1 + ν) ln b + (3 + ν)]	U <sub>6</sub> [2(1 + ν)]	$-U_6 \frac{(1 - \nu^2)}{b^2}$	0	8ψ <sub>1</sub> <sup>1/2</sup> P*/ρ
(20-8)	0	0	0	0	0	0	b <sup>2</sup> ln b	b <sup>2</sup>	ln b	1.0	0
(20-9)	0	0	0	0	0	0	2(1 - ν) ln a + (3 + ν)	2(1 + ν)	-(1 - ν)/a <sup>2</sup>	0	0
(20-10)	0	0	0	0	0	0	1.0	0	0	0	$-\frac{3(1 - \nu^2)M}{2\pi Et^3(a - b)}$

<sup>a</sup>These equations are in the form [A]|C| + |B| = 0, where [A] is the coefficient matrix, |C| is the column matrix of unknown constants, and |B| is the column matrix of loading parameters.

<sup>b</sup>A superscript "0" on the b's indicates that the Bessel function is to be evaluated at x = 0, η = 2γ/α.

<sup>c</sup>A prime (') on the b's indicates that the Bessel function is to be evaluated at x = h, η = 2γρ<sup>1/2</sup>/α.

<sup>d</sup>U<sub>1</sub> = t/4ψ<sub>1</sub>h; U<sub>2</sub> = η<sub>1</sub><sup>2</sup>Eg<sub>1</sub><sup>3</sup>/96tψ<sub>1</sub><sup>3</sup>h<sup>3</sup>(1 - ν<sup>2</sup>); U<sub>3</sub> = (b/E)  $\left[ \frac{(1 + \nu)K^2 + (1 - \nu)}{K^2 - 1} \right]$ , where K = a/b; U<sub>4</sub> = tbaP\*/2h(1 + α)<sup>2</sup>; U<sub>5</sub> = γ<sup>2</sup>t/ha; U<sub>6</sub> = -4ψ<sub>1</sub><sup>5/2</sup>h<sup>2</sup>t<sup>3</sup>/bg<sub>1</sub><sup>3</sup>.

3. The ASME Code stress-calculation method uses a moment  $M$ , applied to the flange ring, rather than a bolt load  $W$ , where the correlation between  $M$  and  $W$  is  $M = W(a - b)$ . In the present analysis, however, Eq. (20-10) from Table 2 is used with the loading parameter  $M$ , rather than  $W$ .

### Stresses

After having solved the set of equations in Table 3 for the constants  $C_1, \dots, C_{10}$ , the stresses can be obtained anywhere in the structure. The equations for these stresses, used in other reports<sup>4,5</sup> in this series, are given in Table 4 [Eqs. (22)–(45)] for the same locations as those given by the ASME Code stress-calculation method; these are (1) at the hub-to-pipe juncture, (2) in the hub at the hub-to-ring juncture, and (3) at the inside edge of the ring ( $r = b$ ).

### Displacements

In Chapter 7 the displacements  $w$  of the flange ring are used. The equations for these displacements (with  $w$  arbitrarily set to zero at  $r = b$ ) are:

$$w_g = C_7 g^2 \ln g + C_8 g^2 + C_9 \ln g + C_{10} \quad (46)$$

at the gasket centerline radius,  $g = G/2$ ; and

$$w_c = C_7 c^2 \ln c + C_8 c^2 + C_9 \ln c + C_{10} \quad (47)$$

at the bolt-circle radius,  $c = C/2$ .

Table 4. Equations for the stresses in a tapered-hub flange

Type	Hub-to-pipe-juncture, longitudinal and circumferential		Hub-to-ring juncture, longitudinal and circumferential		Inside edges of ring, tangential and radial		
	Equation	Eq. No.	Equation	Eq. No.	Equation	Eq. No.	
Longitudinal or tangential	Bending	$(\sigma'_x)_b = \pm \frac{Eg_0}{2(1-\nu^2)} (2\beta^2)C'_5 b$	(22)	$(\sigma_x)_b = \pm \frac{Eg_1}{2(1-\nu^2)} \left[ \frac{b}{4\psi_1^5/2h^2} (C_1 b'_9 + C_2 b'_{10}) + C_3 b'_{11} + C_4 b'_{12} + \frac{2ba^2 P^*}{h^2(1+\alpha)^3} \right]$	(30)	$(\sigma_t)_b = \pm (6/t^2)(M_t)_{r=b} = \pm [Et/2(1-\nu^2)] \times [C_7(2.6 \ln b + 1.9) + 2.6C_8 + 0.7C_9/b^2]$	(38)
	Membrane	$(\sigma_x)_m = pb/2g_0$	(23)	$(\sigma_x)_m = pb/2g_1$	(31)	$(\sigma_t)_m = \frac{K^2 + 1}{K^2 - 1} \left( p - \frac{P_1}{t} \right)$	(39) <sup>a</sup>
	Outside	$(\sigma_x)_o = pb/2g_0 - 1.816C'_5$	(24)	$(\sigma_x)_o = pb/2g_1 - (\sigma_x)_b$	(32)	$(\sigma_t)_o = (\sigma_t)_m + (\sigma_t)_b$	(40) <sup>b</sup>
	Inside	$(\sigma_x)_i = pb/2g_0 + 1.816C'_5$	(25)	$(\sigma_x)_i = pb/2g_1 + (\sigma_x)_b$	(33)	$(\sigma_t)_i = (\sigma_t)_m - (\sigma_t)_b$	(41) <sup>c</sup>
	Circumferential or radial	Bending	$\pm(\sigma_c)_b = \pm\nu(\sigma'_x)_b$	(26)	$\pm(\sigma_c)_b = \pm(\sigma_x)_b$	(34)	$(\sigma_r)_b = \pm \frac{6M_{rk}}{t^2} = \pm \frac{Et}{2(1-\nu^2)} \times [C_7(2.6 \ln b + 3.3) + 2.6C_8 - 0.7C_9/b^2]$
	Membrane	$(\sigma_c)_m = (Eu_0/b) + \nu(pb/2g_0)$	(27) <sup>d</sup>	$(\sigma_c)_m = (Eu_h/b) + \nu(pb/2g_1)$	(35) <sup>e</sup>	$(\sigma_r)_m = -p + P_1/t$	(43)
	Outside	$(\sigma_c)_o = (Eu_0/b) + \nu(\sigma'_x)_o$	(28)	$(\sigma_c)_o = (Eu_h/b) + \nu(\sigma_x)_o$	(36)	$(\sigma_r)_o = (\sigma_r)_m + (\sigma_t)_b$	(44) <sup>b</sup>
	Inside	$(\sigma_c)_i = (Eu_0/b) + \nu(\sigma'_x)_i$	(29)	$(\sigma_c)_i = (Eu_h/b) + \nu(\sigma_x)_i$	(37)	$(\sigma_r)_i = (\sigma_r)_m - (\sigma_t)_b$	(45) <sup>c</sup>

<sup>a</sup>Here,  $K = a/b$ , and  $\frac{P_1}{t} = - \frac{Eg_1^3}{(1-\nu^2)} \frac{b\eta_1^2}{8h^3\psi_1^2/2} (C_1 b'_{17} + C_2 b'_{18} + C_3 b'_{19} + C_4 b'_{20})$ .

<sup>b</sup>Hub-side surface of ring.

<sup>c</sup>Gasket-side surface of ring.

<sup>d</sup> $u_0 = b(C'_6 + P^*)$ .

<sup>e</sup> $u_h = \frac{b}{\psi_1/2} (C_1 b'_1 + C_2 b'_2 + C_3 b'_3 + C_4 b'_4) + bP^*/(1+\alpha)$ .

## 4. FLANGE WITH A STRAIGHT HUB

Although the mathematical expressions for the straight hub can be obtained by letting  $g_0 = g_1$ , this would result in indeterminate quantities in the computer program. Therefore, the direct solution to the ring with a straight hub was obtained by using the previously given basic equations for only the pipe and the ring. There are six constants of integration to be established; the boundary-condition equations are displayed in Table 5 [Eq. (48)].

After algebraic manipulation, the equations displayed in Table 5 are reduced to the matrix-equation form  $[A]|C| + |B| = 0$ , where the terms in the coefficient matrix  $[A]$  are given in Table 6 under the headings of the corresponding constants in the column matrix  $|C|$ . Solving this set of equations for the six constants ( $C_5'$ ,  $C_6'$ ,  $C_7$ ,  $C_8$ ,  $C_9$ , and  $C_{10}$ ) allows calculation of the stresses in the structure. The equations for the stresses in the pipe at the pipe-to-ring juncture and in the ring at the inner edge ( $r = b$ ) are analogous to those previously derived for the flange with a tapered hub (see Table 4).

One can calculate the displacements  $w_g$  and  $w_c$  for a straight-hub flange from Eqs. (46) and (47), respectively, using the constants  $C_7, \dots, C_{10}$ , identified in Table 6.

Table 5. Equations for the boundary conditions for a straight-hub flange

	Hub-to-ring juncture		Ring	
	Equation	Eq. No.	Equation	Eq. No.
Displacements	$(u_1)_{x_1=0} = 0$	(48-1a) <sup>a,b</sup>	$(w)_{r=b} = 0$	(48-4) <sup>c</sup>
	$(u_1)_{x_1=0} = \left( u_r - \frac{t}{2} \frac{dw}{dr} \right)_{r=b}$	(48-1b) <sup>a,b</sup>		
Rotations	$(u_1')_{x_1=0} = \left( \frac{dw}{dr} \right)_{r=b}$	(48-2)		
Moments	$M_{r1} = -M_{ho} + \frac{1}{2} P_0 t$	(48-3)	$M_{r2} = 0$	(48-5) <sup>d</sup>
Shear along radius r			$Q = - \frac{dM_r}{dr} + \frac{M_t - M_r}{r} = \frac{W}{2\pi r}$	(48-6)

<sup>a</sup>Radial displacements.

<sup>b</sup>For an ASME-type calculation, Eq. (48-1a) is used.

<sup>c</sup>Axial displacements;  $(w)_{r=b} = 0$  is the reference point for all other axial displacements.

<sup>d</sup>Radial moment at outside edge of ring ( $r = a$ ).

Table 6. Matrix coefficients of the discontinuity equations<sup>a</sup> for a flange with a straight hub

Eq. No.	Coefficients of C <sub>n</sub>						Loading parameters
	C <sub>5</sub>	C <sub>6</sub>	C <sub>7</sub>	C <sub>8</sub>	C <sub>9</sub>	C <sub>10</sub>	
(48-1a)	0	1.0	0	0	0	0	bP* + bε <sub>f</sub> Δ - U <sub>3</sub> P
(48-1b) <sup>b</sup>	U <sub>34</sub> - U <sub>33</sub>	1 + U <sub>34</sub> + U <sub>33</sub>	0	0	0	0	0
(48-2)	β	β	-(2b ln b + b)	-2b		0	0
(48-3)	2β <sup>2</sup> + 2β <sup>3</sup> t/2	-2β <sub>1</sub> <sup>3</sup> t/2	-(2.6 ln b + 3.3) × (t/g <sub>0</sub> ) <sup>3</sup>	-2.6(t/g <sub>0</sub> ) <sup>3</sup>	(0.7/b <sup>2</sup> )(t/g <sub>0</sub> ) <sup>3</sup>	0	0
(48-4)	0	0	b <sup>2</sup> ln b	b <sup>2</sup>	ln b	1.0	0
(48-5)	0	0	2.6 ln a + 3.3	2.6	-0.7/a <sup>2</sup>	0	0
(48-6)	0	0	1.0	0	0	0	$\frac{-3(1 - \nu^2)M}{2\pi Et^3(a - b)}$

<sup>a</sup>These equations are in the form [a]|C| + |B| = 0, where [A] is the coefficient matrix, |C| is the column matrix of unknown constants, |B| is the column matrix of loading parameters.

$${}^bU_3 = (b/E) \left[ \frac{(1 + \nu)K^2 + (1 - \nu)}{K^2 - 1} \right], \text{ where } K = a/b; U_{33} = \frac{2U_3Eg_0^3\beta^3}{12(1 - \nu^2)t}; U_{34} = t\beta/2.$$

## 5. BLIND FLANGES

Analysis Method

Blind flanges (or flat heads) are modeled as shown in Fig. 2. The general equations for a circular flat plate are:<sup>3</sup>

$$w = D_1 r^2 \ln r + D_2 r^2 + D_3 \ln r + D_4 + r^4 p / 64D , \quad (49)$$

$$\frac{dw}{dr} = D_1 (2r \ln r + r) + D_2 (2r) + D_3 / r + r^3 p / 16D , \quad (50)$$

$$\frac{d^2 w}{dr^2} = D_1 (2 \ln r + 3) + D_2 (2) - D_3 / r^2 + 3r^2 p / 16D , \quad (51)$$

and

$$\frac{d^3 w}{dr^3} = D_1 (2/r) + D_3 (2/r^3) + 3rp / 8D . \quad (52)$$

The radial and tangential moments  $M_r$  and  $M_t$  (see Fig. 2) are given by

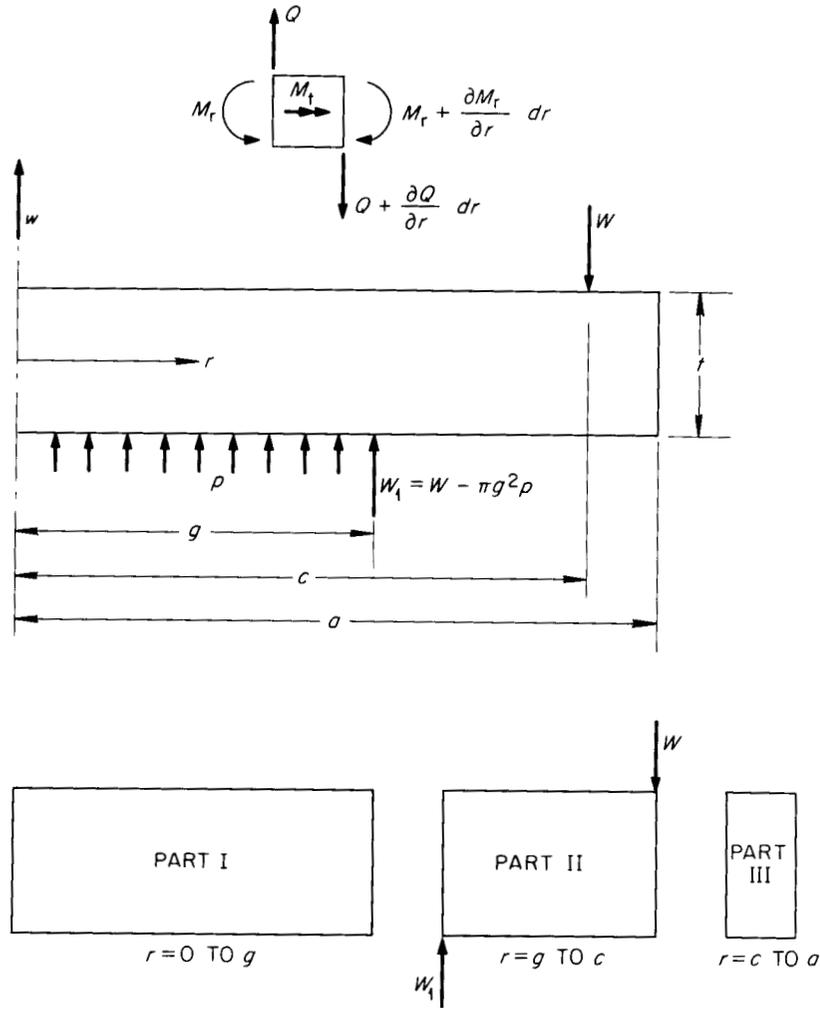
$$M_r = -D \left( \frac{d^2 w}{dr^2} + \frac{\nu}{r} \frac{dw}{dr} \right) \quad (53)$$

and

$$M_t = -D \left( \frac{1}{r} \frac{dw}{dr} + \nu \frac{d^2 w}{dr^2} \right) ; \quad (54)$$

and the shear is given by

$$Q = - \frac{dM_r}{dr} + \frac{M_t - M_r}{r} . \quad (55)$$



CONSTANTS:  
 $D_{11}, D_{12}, D_{13}, D_{14}$                        $D_{21}, D_{22}, D_{23}, D_{24}$        $D_{31}, D_{32}, D_{33}, D_{34}$

Fig. 2. Flat-plate analysis model of a blind flange or cover plate.

The moments and shears, in terms of the integration constants  $D_1$  through  $D_4$ , are:

$$M_r = -D\{D_1[2(1 + \nu) \ln r + (3 + \nu)] + D_2[2(1 + \nu)] - D_3[(1 - \nu)/r^2]\} - r^2p/16(3 + \nu) , \quad (56)$$

$$M_t = -D\{D_1[2(1 + \nu) \ln r + (1 + 3\nu)] + D_2[2(1 + \nu)] + D_3[(1 - \nu)/r^2]\} - r^2p/16(1 + 3\nu) , \quad (57)$$

and

$$Q = D \left( \frac{4D_1}{r} \right) + \frac{rp}{2} . \quad (58)$$

For analysis, the plate is divided into three parts as shown in Fig. 2. There are four integration constants for each segment. The boundary-condition equations used to evaluate these constants are shown in Table 7. These boundary conditions show that 3 of the 12 constants are zero. The set of simultaneous equations to be solved to establish the remaining 9 constants is shown in Table 8. Again, this table presents the elements of the matrix equation  $[A]|C| + |B| = 0$ .

Table 7. Boundary condition equations used for blind-flange analysis

Equation No.	Boundary condition
1	$2\pi rQ = \pi r^2p$ for all of Part I. This gives $D_{11} = 0$ .
2	$(dw/dr)_I = 0$ at $r = 0$ . This gives $D_{13} = 0$ .
3	$(w)_I = 0$ at $r = g$
4	$(dw/dr)_I = (dw/dr)_{II}$ at $r = g$
5	$(Q)_{II} = (W/2\pi r) - (\pi g^2p/2\pi g)$ at $r = g$ . This gives $D_{21} = W/8\pi D - g^2p/8D$ . (For pressure loading, $W = \pi g^2p$ ; hence $D_{21} = 0$ .)
6	$(w)_{II} = 0$ at $r = g$
7	$(M_r)_I = (M_r)_{II}$ at $r = g$
8	$(dw/dr)_I = (dw/dr)_{II}$ at $r = g$
9	$(Q)_{III} = 0$ . This gives $D_{31} = 0$ .
10	$(M_r)_{II} = (M_r)_{III}$ at $r = c$
11	$(M_r)_{III} = 0$ at $r = a$
12	$(w)_{II} = (w)_{III}$ at $r = c$

Table 8. Boundary equations<sup>a</sup> for a blind flange

No. <sup>b</sup>	Coefficients of $D_{ij}$									Loading parameter
	$D_{12}$	$D_{14}$	$D_{21}$	$D_{22}$	$D_{23}$	$D_{24}$	$D_{32}$	$D_{33}$	$D_{34}$	
3	$g^2$	1.0	0	0	0	0	0	0	0	$g^4 p / 64D$
4	$-2g$	0	$2g \ln g + g$	$2g$	$1/g$	0	0	0	0	$-g^3 p / 16D$
5	0	0	1.0	0	0	0	0	0	0	$-W / 8\pi D$
6	0	0	$g^2 \ln g$	$g^2$	$\ln g$	1.0	0	0	0	0
7	$-2.6$	0	$2.6 \ln g + 3.3$	$2.6$	$-0.7/g^2$	0	0	0	0	$-3.3g^2 p / 16D$
8	0	0	$2c \ln c + c$	$2c$	$1/c$	0	$-2c$	$-1/c$	0	0
10	0	0	$2.6 \ln c + 3.3$	$2.6$	$-0.7/c^2$	0	$-2.6$	$0.7/c^2$	0	0
11	0	0	0	0	0	0	$2.6$	$-0.7/a^2$	0	0
12	0	0	$c^2 \ln c$	$c^2$	$\ln c$	1.0	$-c^2$	$-\ln c$	$-1.0$	0

<sup>a</sup>These equations are in the form  $[A]|C| + |B| = 0$ , where  $[A]$  is the coefficient matrix,  $|C|$  is the column matrix of unknown constants, and  $|B|$  is the column matrix of loading parameters.

<sup>b</sup>Boundary condition number from Table 4.

Stresses

After having established values for the integration constants, the stresses at any point in the blind flange can be readily obtained. Equations for stresses at the center of the flange and at  $r = g$  and  $r = c$  are given by

$$\sigma_t = \pm 6M_t/t^2 = \pm EtM_t/[2(1 - \nu^2)]D \quad (59a)$$

and

$$\sigma_r = \pm 6M_r/t^2 = \pm EtM_r/[2(1 - \nu^2)]D . \quad (59b)$$

At the center of the flange ( $r = 0$ ),

$$M_t = M_r = -D\{D_{12}[2(1 + \nu)]\} . \quad (60)$$

At the gasket ( $r = g$ ),

$$M_r = -D\{D_{12}[2(1 + \nu)] + g^2p(3 + \nu)/16D\} , \quad (61)$$

and

$$M_t = -D\{D_{12}[2(1 + \nu)] + g^2p(1 + 3\nu)/16D\} . \quad (62)$$

At the bolt circle ( $r = c$ ),

$$M_r = -D\{D_{32}[2(1 + \nu)] - D_{33}(1 - \nu)/c^2\} , \quad (63)$$

and

$$M_t = -D\{D_{32}[2(1 + \nu)] + D_{33}(1 - \nu)/c^2\} . \quad (64)$$

In all of the above, a positive moment produces a tensile stress on the back of the flange (positive  $w$  side of Fig. 2).

Displacements

In the third and sixth boundary conditions listed in Table 7, the axial displacement at the gasket has been arbitrarily set equal to zero. The relative displacement of the bolt circle to the gasket is therefore

$$w_c = D_{32}c^2 + D_{33} \ln c + D_{34} . \quad (65)$$

## 6. THERMAL GRADIENTS

Two kinds of thermal gradients are included in the analysis: (1) a constant temperature in the pipe and hub that may be different from the assumed constant temperature in the ring and (2) a constant temperature in the bolts that may be different from the assumed constant temperature in the ring.

The significance of the bolt-to-ring thermal gradients is dependent upon the dimensional and material characteristics of the flanged joint and is covered later in Chapter 7.

The pipe/hub-to-ring temperature gradient is included in the analysis by an appropriate change in the "loading parameters" shown in Table 3. We define  $\Delta$  as the difference in temperature between the pipe/hub and the ring;  $\Delta$  is positive if the pipe/hub is hotter than the ring. The radial expansion of the tapered hub at its juncture with the ring is then:

$$u = \frac{b}{\sqrt{\psi_1}} (C_1 b_1' + C_2 b_2' + C_3 b_3' + C_4 b_4') + b \epsilon_f \Delta, \quad (66)$$

where  $b$  is the pipe radius;  $b_i'$  terms are the Bessel functions defined in Table 1 evaluated at  $x = h$ ,  $\eta = 2\gamma\rho^{1/2}/\alpha$ , as indicated in footnote *c* of Table 3; and  $\epsilon_f$  is the coefficient of thermal expansion of the flange material.

The effects of such a thermal gradient are taken into account by adding  $(\sqrt{\psi_1}/b)(b\epsilon_f\Delta)$  to the existing terms in the loading-parameter column in Table 3 [Eqs. (20-5a) and (20-5b)]. The analogous term is already included in Table 6.

## 7. CHANGE IN BOLT LOAD WITH PRESSURE, TEMPERATURE, AND EXTERNAL MOMENTS

A flanged joint is a statically indeterminate structure. Thus, in order to determine the residual bolt load in the joint, it is necessary to calculate the relative displacements of the parts when the joint is subjected to (1) initial bolt loading, (2) moment loading, (3) internal pressure, and (4) thermal gradients.

The object of the analysis is to determine the residual bolt load  $W_2$  in terms of (1) the loadings  $W_1$ ,  $p$ ,  $\Delta$ , and  $\Delta'$ ; (2) the component temperatures  $T_b$ ,  $T_g$ ,  $T_f$ , and  $T'_f$ ; (3) the flanged-joint dimensions; and (4) the material properties.

The basic analysis is given by Wesstrom and Bergh,<sup>6</sup> and we follow their nomenclature, with additions as necessary. Reference 6 covers only the effect of initial bolt loading and part of the influence of internal pressure; the remaining influence from the internal pressure is discussed by Rodabaugh.<sup>7</sup> The extension of the analysis to cover thermal gradients is relatively simple and is covered below.

The nomenclature used in this development is:

- A = cross-sectional area of bolts or gasket
- B = inside diameter of ring
- C = bolt-circle diameter
- E = modulus of elasticity
- $g_0$  = wall thickness of pipe
- G = gasket centerline diameter
- $l$  = bolt length
- $p$  = internal pressure
- $p^*$  = equivalent pressure for external moment loading
- $q$  = elastic deformation coefficients
- $t$  = ring thickness
- T = final-state temperature (initial-state temperature is defined as zero)
- $v$  = gasket thickness
- W = bolt load

$\delta$  = relative axial displacement between the gasket centerline and the bolt circle

$\epsilon$  = coefficient of thermal expansion

$\Delta$  = temperature between hub/pipe and ring

The subscripts 0, 1, and 2 refer to the undeformed, initial deformed, and final deformed states, respectively; subscripts b, g, and f refer to the bolts, gasket, and flange, respectively. Quantities with a prime (') are for one of the flanges in a pair (e.g.,  $T_f'$  refers to the temperature of the right-hand flange in Fig. 3); quantities without a prime are for the other flange.

### Analysis

Figure 3 shows a schematic illustration of the general case of two dissimilar flanges and their mode of deformation. When the bolts are initially tightened to make up the joint, the resulting initial deformed bolt length is

$$l_1 = v_1 + t_1 + t_1' - \delta_1 - \delta_1' . \quad (67)$$

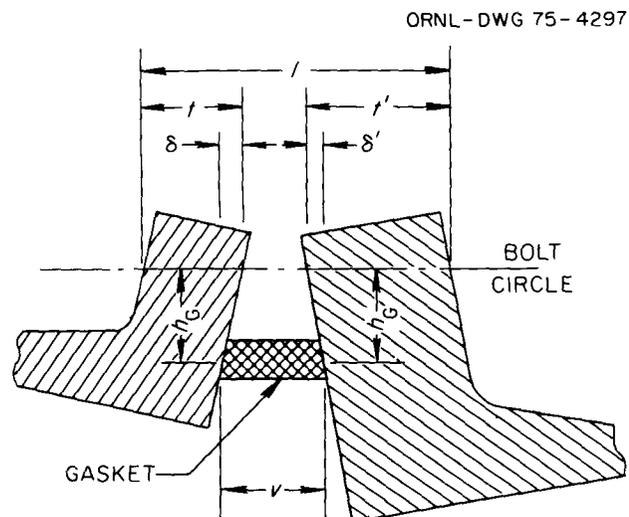


Fig. 3. General case of two dissimilar flanges and their mode of deformation.

After application of loadings, the bolt length becomes

$$l_2 = v_2 + t_2 + t'_2 - \delta_2 - \delta'_2 . \quad (68)$$

The basic displacement relationship is thus

$$l_2 - l_1 = (v_2 - v_1) + (t_2 - t_1) + (t'_2 - t'_1) \\ - (\delta_2 - \delta_1) - (\delta'_2 - \delta'_1) . \quad (69)$$

We also use the following relationships:

$$l_2 = l_0 + T_b \epsilon_b l_0 + q_{b2} W_2 , \quad (a)$$

$$v_2 = v_0 + T_g \epsilon_g v_0 - q_{g2} (W_2 - H_{D2} - H_{T2}) , \quad (b)$$

$$t_2 = t_0 + T_f \epsilon_f t_0 , \quad (c)$$

$$t'_2 = t'_0 + T'_f \epsilon'_f t'_0 , \quad (d)$$

$$\delta_2 = q_{f2} M_2 h_G + q_p \text{ph}_G + q_t \Delta h_g , \quad (e)$$

$$\delta'_2 = q'_{f2} M'_2 h_G + q'_p \text{ph}_G + q'_t \Delta' h_G , \quad (f)$$

$$l_1 = l_0 + q_{b1} W_1 , \quad (g) \quad (70)$$

$$v_1 = v_0 - q_{g1} W_1 , \quad (h)$$

$$t_1 = t_0 , \quad (i)$$

$$t'_1 = t'_0 , \quad (j)$$

$$\delta_1 = q_{f1} M_1 h_G , \quad (k)$$

$$\delta'_1 = q'_{f1} M'_1 h_G . \quad (l)$$

The elastic deformation coefficients  $q_{b1}$ ,  $q_{g1}$ ,  $q_{b2}$ , and  $q_{g2}$  in Eqs. (70a-ℓ) are further defined as

$$q_{b1} = \frac{\lambda_0}{A_b E_{b1}}, \quad (71a)$$

$$q_{g1} = \frac{v_0}{A_g E_{g1}}, \quad (71b)$$

$$q_{b2} = \frac{\lambda_0}{A_b E_{b2}}, \quad (71c)$$

$$q_{g2} = \frac{v_0}{A_g E_{g2}}. \quad (71d)$$

In Eqs. (70a-ℓ), the term  $q_{f1}$  is a rotation of the flange due to a unit moment load,  $q_p$  is a rotation of the flange due to a unit internal pressure, and  $q_t$  is a rotation of the flange due to a unit temperature gradient between the hub and the ring. The quantities  $q_{f1}$ ,  $q_p$ , and  $q_t$  are obtained from the functional expression

$$q(L) = \frac{-w_c(L) + w_g(L)}{h_G}, \quad (72)$$

where  $h_G = (C - G)/2$ ,  $C$  is the bolt-circle diameter, and  $G$  is the gasket-centerline diameter. Values for the displacements  $w_c(L)$  and  $w_g(L)$  are obtained from Eqs. (46) and (47) with the appropriate unit values for the loads  $\Delta$ ,  $P$ , and  $M$ .

For  $q_{f1}$  the modulus of elasticity used is that for the initial condition. For  $q_p$  and  $q_t$ , the moduli used are those for the final condition. The term  $q_{f2}$  is obtained from  $q_{f1}$  and the ratio of the initial and final elastic moduli; thus:

$$q_{f2} = q_{f1} \frac{E_1}{E_2}.$$

The moments and loads are defined by Eqs. (73a-n). The nomenclature used in these equations is analogous to that used in the ASME Code.<sup>1</sup> The symbol  $H$  represents a load,  $h$  represents a lever arm, and  $M$  represents a moment. The term  $H_D$  is the hydrostatic end force (in pounds) on the area inside the flange,  $H_G$  is the gasket load in pounds,  $H_T$  is the difference between the total hydrostatic end force and the hydrostatic end force on the area inside the flange,  $h_D$  is the radial distance in inches from the bolt circle to the circle on which  $H_D$  acts (as prescribed in Table UA-50 of the Code),  $h_G$  is the radial distance in inches from the gasket-load reaction to the bolt circle, and  $h_T$  is the radial distance in inches from the bolt circle to the circle on which  $H_T$  acts (as prescribed in Table UA-50). Symbols,  $C$ ,  $B$ ,  $G$ ,  $g_0$ , and  $p$  are defined earlier in this chapter. Again, a subscript 1 refers to the initial deformed state, a subscript 2 refers to the final deformed state, and primed quantities refer to the mating flange.

$$h_D = (C - B - g_0)/2 , \quad (a)$$

$$h'_D = (C - B' - g'_0)/2 , \quad (b)$$

$$h_T = [C - (G + B)/2]/2 , \quad (c)$$

$$h'_T = [C - (G + B')/2]/2 , \quad (d)$$

$$h_G = (C - G)/2 , \quad (e)$$

$$H_{D2} = \frac{\pi}{4} B^2 p , \quad (f)$$

$$H'_{D2} = \frac{\pi}{4} (B')^2 p , \quad (g) \quad (73)$$

$$H_{T2} = \frac{\pi}{4} (G^2 - B^2) p , \quad (h)$$

$$H'_{T2} = \frac{\pi}{4} [G^2 - (B')^2] p , \quad (i)$$

$$H_{G2} = W_2 - H_{D2} - H_{T2} , \quad (j)$$

$$H'_{G2} = W_2 - H'_{D2} - H'_{T2} , \quad (k)$$

$$M_1 = W_1 h_G = H_{G1} h_G , \quad (\ell)$$

$$M_2 = H_{D2} h_D + H_{T2} h_T + H_{G2} h_G , \quad (m)$$

and

$$M'_2 = H'_{D2} h'_D + H'_{T2} h'_T + H_{G2} h_G . \quad (n)$$

Substituting Eqs. (70a-ℓ) into Eq. (69) gives

$$\begin{aligned} T_b \varepsilon_b \ell_0 + q_{b2} W_2 - q_{b1} W_1 = & T_g \varepsilon_g v_0 - q_{g2} (W_2 - H_{D2} - H_{T2}) \\ & + q_{g1} W_1 + T_f \varepsilon_f t_0 + T'_f \varepsilon'_f t'_0 - h_G (q_{f2} M_2 + q_p p + q_t \Delta - q_{f1} M_1) \\ & - h_G (q'_{f2} M'_2 + q'_p p + q'_t \Delta' - q'_{f1} M_1) . \end{aligned} \quad (74)$$

In order to eliminate  $M_1$  and  $M_2$  from Eq. (74), Eqs. (73ℓ and m) are used; the sixth term on the right-hand side of Eq. (74) then becomes

$$-h_G \{ q_{f2} [H_{D2} h_D + H_{T2} h_T + (W_2 - H_{D2} - H_{T2}) h_G] + q_p p + q_t \Delta - q_{f1} W_1 h_G \} .$$

The last term in Eq. (74) is treated similarly. Collecting terms containing  $W_2$  on the left gives:

$$\begin{aligned} (q_{b2} + q_{g2} + h_G^2 q_{f2} + h_G^2 q'_{f2}) W_2 = & (q_{b1} + q_{g1} + h_G^2 q_{f1} + h_G^2 q'_{f1}) W_1 \\ & + T_g \varepsilon_g v_0 + T_f \varepsilon_f t_0 + T'_f \varepsilon'_f t'_0 - T_b \varepsilon_b \ell_0 + q_{g2} (H_{D2} + H_{T2}) \\ & - h_G q_{f2} [H_{D2} (h_D - h_G) + H_{T2} (h_T - h_G)] \\ & - h_G q'_{f2} [H'_{D2} (h'_D - h_G) + H'_{T2} (h'_T - h_G)] \\ & - h_G (q_p + q'_p) p - h_G (q_t \Delta + q'_t \Delta') . \end{aligned} \quad (75)$$

Defining

$$Q_1 = q_{b1} + q_{g1} + h_G^2 q_{f1} + h_G^2 q'_{f1}$$

and

$$Q_2 = q_{b2} + q_{g2} + h_G^2 q_{f2} + h_G^2 q'_{f2}$$

and using the given definitions of  $H_D$ ,  $H'_D$ ,  $H_T$ , and  $H'_T$ , Eq. (75) becomes

$$\begin{aligned} W_2 = & \frac{Q_1}{Q_2} W_1 + \frac{1}{Q_2} (T_g \varepsilon_g v_0 + T_f \varepsilon_f t_0 + T'_f \varepsilon'_f t'_0 - T_b \varepsilon_b l_0) \\ & + \frac{\pi h_G}{4Q_2} \left\{ \left[ \frac{q_{g2}}{h_G} - q_{f2} (h_T - h_G) - q'_{f2} (h_T - h_G) - q'_{f2} (h'_T - h_G) \right] G^2 \right. \\ & \quad \left. - [q_{f2} B^2 (h_D - h_T) + q'_{f2} (B')^2 (h'_D - h'_T)] \right\} p \\ & - \frac{h_G}{Q_2} (q_p + q'_p) p - \frac{h_G}{Q_2} (q_t \Delta + q'_t \Delta') . \quad (76) \end{aligned}$$

In order to compute the flange stresses under the various loading conditions, it is necessary to compute the flange moment  $M_2$  or  $M'_2$ . From Eq. (73m) and the definitions in Eqs. (73a-k),

$$M_2 = \frac{\pi}{4} p [B^2 h_D + (G^2 - B^2) h_T - G^2 h_G] + W_2 h_G . \quad (77a)$$

And similarly for the mating flange,

$$M'_2 = \frac{\pi}{4} p \left\{ (B')^2 h'_D + [G^2 - (B')^2] h'_T - G^2 h_G \right\} + W_2 h_G . \quad (77b)$$

The computer program was written to separately evaluate the various effects involved in bolt-load changes. The residual bolt load due to

temperature differences that produce differential axial strain is

$$W_{2a} = W_1 + \frac{1}{Q_1} (T_g \varepsilon_g v_0 + T_f \varepsilon_f t_0 + T'_f \varepsilon'_f t'_0 - T_b \varepsilon_b \ell_0) . \quad (78)$$

The residual bolt load, after internal pressure (acting in an axial direction) has transferred the bolt load on the gasket to a tensile load on the attached pipes due to a shift in lever arms, is given by:

$$W_{2b} = W_1 + \frac{\pi h_G}{4 Q_1} \left\{ \left[ \frac{q_{g1}}{h_G} - q_{f1} (h_T - h_G) - q'_{f1} (h'_T - h_G) \right] G^2 - [q_{f1} B^2 (h_D - h_T) + q'_{f1} (B')^2 (h'_D - h'_T)] \right\} p . \quad (79)$$

The total effect of internal pressure due to both the shift in the lever arms and the radial effect of pressure acting on the integral flange(s) and/or on the inside surface of a blind flange is given by:

$$W_{2c} = W_{2b} - \frac{h_G}{Q_1} (q_p + q'_p) p . \quad (80)$$

The residual bolt load due to a temperature difference between the hub and the ring is given by:

$$W_{2d} = W_1 - \frac{h_G}{Q_1} (q_t \Delta + q'_t \Delta') . \quad (81)$$

A slight modification of the above is required for the case of a blind flange. If we designate the blind flange as that with the "primed" nomenclature, then all\* of Eqs. (70a-l) are valid except Eqs. (70f and l) for  $\delta'_1$  and  $\delta'_2$ .

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\* For  $v_2$  it should be noted that  $H_{D2} - H_{T2} = \pi G^2 p / 4$ ; hence, this equation is valid for blind flanges.

For blind flanges,  $W$  is used rather than  $M$  as the loading parameter because the relationship  $M = W(a - b)$  is not valid for the blind-flange analysis. For blind-flange analysis, Eq. (65) gives a value of  $w_c$ ; here  $-w_c$  is the equivalent of  $-w_c + w_g$  in Eq. (72) because  $w_g \equiv 0$  in the blind-flange analysis. For blind flanges we define

$$q'_f = \frac{(-w_c)W}{h_G^2}, \quad (82)$$

where  $(-w_c)_W$  is the axial displacement per unit total bolt load  $W$ . The equation for  $W_2$  for a blind flanged joint is then:

$$\begin{aligned} W_2 = & \frac{Q_1}{Q_2} W_1 + \frac{1}{Q_2} (T_g \epsilon_g v_0 + T_f \epsilon_f t_0 + T'_f \epsilon'_f t'_0 - T_b \epsilon_b l_0) \\ & + \frac{\pi}{4} \frac{h_G}{Q_2} \left\{ \left[ \frac{q_{g2}}{h_G} - q_{f2} (h_T - h_G) \right] G^2 - q_{f2} B^2 (h_D - h_T) \right\} p \\ & - \frac{h_G}{Q_2} (q_p + q'_p) p - \frac{h_G}{Q_2} q_t \Delta. \quad (83) \end{aligned}$$

In Eq. (83) the primed values refer to properties of the blind flange.

After the internal pressure has transferred the bolt load on the gasket to a tensile load on the attached pipe due to a shift in the lever arms, the residual bolt load for the case where a blind flange is used is

$$W_{2b} = W_1 + \frac{\pi}{4} \frac{h_G}{Q_1} \left\{ \left[ \frac{q_{g1}}{h_G} - q_{f1} (h_T - h_G) \right] G^2 - q_{f1} B^2 (h_D - h_T) \right\} p. \quad (84)$$

It should be noted that  $q'_t \Delta$  does not exist for an integral flange mated to a blind flange.

The combined effect of all of the above is also obtained from the computer program by calculating  $W_2$  from Eqs. (76) and (83).

External Moment Loading

Up to this point, all loads considered have been axisymmetric. For flanged joints in pipe lines, there is one other significant loading; that is, the bending moment imposed on the flanged joint by the attached pipe. To distinguish this from the local moments applied to the flange ring, the bending moment will be designated as an "external" moment. The external moment can be represented by a distributed axial edge force acting on the attached pipe:

$$F_M(\theta) = F_m \cos \theta , \quad (85)$$

where  $\theta$  = angle around the circumference ( $\theta = 0$  at the point of maximum tensile stress in the pipe due to the external moment). Since this report deals only with cases in which all contact occurs within the bolt-hole circle, a reasonably good first approximation for the effects of the external moment loading can be obtained by replacing the distributed axial force  $F_M(\theta)$  with the axisymmetric tensile force  $F_m = F_M(\max)$ . Then, since  $F_m$  is axisymmetric, there is some pressure  $p^*$  that will produce the same axial force in the pipe; or alternately, there is an equivalent pressure  $p^*$  that will produce an axial stress in the pipe which is equal to the maximum tensile stress  $S_b$  produced by an external moment. The relation between  $p^*$  and  $S_b$  is given by

$$p^* = 4S_b g_0 / D_o , \quad (86)$$

where  $S_b$  is the bending stress in the attached pipe due to the external moment. The change in bolt load  $W_{2b}$  is then obtained by replacing  $p$  with  $p + p^*$  in Eqs. (79) and (84). It should be noted that this equivalent pressure is included only in Eqs. (79) and (84) and not in Eq. (80).

## 8. COMPUTER PROGRAM

A Fortran computer program named FLANGE has been written to carry out the calculations according to the analyses described in this report. The program calculates appropriate loads, stresses, and displacements for the flanges, bolts, and gaskets when the flanged joint is subjected to internal pressure, moment, and/or thermal gradient loadings; thus, the program is much more general than that needed only to determine compliance with the ASME Boiler and Pressure Vessel Code. The program also has the advantage of internally computing the values of the Code variables  $F$ ,  $V$ , and  $f$  that must otherwise be extracted manually from the curves given in Code Figs. UA-51.2, UA-51.3, and UA-51.6. Loose hubbed flanges, which are covered by the Code, however, are not covered by the computer program.

The main function of this chapter is to describe the input and output for the various computational options available to the user. For more detailed information, the reader is urged to carefully study the examples given in Appendix A where a flanged joint, selected from API Standard 605 (Ref. 8), is analyzed. Several sample problems are worked, and the data input and program output are given for the various program options along with a discussion of the results. Flowcharts and listings of the program and its subroutines are given in Appendix B. In the following sections, the input data for option control and the input data and program output for Code compliance calculations and for more general calculations are discussed.

Option Control Data Card

The first card of each data set, herein called the option control card, contains control information for execution of the various program options. It contains information specifying the type of flange being analyzed, the boundary condition placed on the displacement  $(u_r)_{x=h}$ , the stresses and other variables to be calculated, and the joint configuration and which flange (of the pair) is to be analyzed. These specifications are under control of the four variables ITYPE, IBOND,

ICØDE, and MATE. The admissible values and their significance are as follows.

ITYPE (indicates the type of flange being analyzed)

- 1 for a tapered-hub flange
- 2 for a straight-hub flange
- 3 for a blind hub

IBØND (specifies the displacement  $u_r$  at  $x = h$ )

- 0 for  $(u_r)_{x=h} = 0$  to conform with the ASME Code basis
- 1 (see footnote)\*
- 2 for  $(u_r)_{x=h} \neq 0$  [see Eq. (20-6) of this report]

ICØDE (controls the amount of output data)

- 0 for a wide variety of stresses, moments, and loads for specified moment, pressure, and  $\Delta T$
- 1 (see footnote)\*
- 2 for a select list for checking Code compliance in accordance with Section VIII, Div. 1 of the ASME Code

MATE (specifies the joint configuration and the flange to be analyzed)

- 1 for only one flange to be analyzed (This is the situation for ASME-Code related calculations.)
- 2 for two identical flanges mated together
- 3 for the first of two flanges that are not identical, neither of which is a blind flange
- 4 for the second of two flanges that are not identical, neither of which is a blind flange
- 5 for a blind flange
- 6 for a flange that is mated with a blind flange.

The data card with the above information is followed by other data cards containing physical-property data, etc., for the particular flange being analyzed. Since the program can be used to analyze any number of flanges

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\* In the original conception of the program, IBØND and ICØDE were envisioned as controlling additional calculations that were not implemented in the present version. As it is now written, the program does not distinguish between values of 0 or 1 nor between 2 and numbers greater than 2 for either IBØND or ICØDE.

or flanged joints sequentially (as done in the examples of Appendix A), the data card set for each flange must start with an option-control data card.

Different types of flanges and different types of calculations have different input data requirements. These data and their formats are discussed in the following sections.

### Input for Code-Compliance Calculations

Since the ASME Code calculation procedures consider only one flange at a time, the input data requirements for the computer program are quite simple and straightforward. Input data are completely prescribed by the three data cards illustrated in Table 9. The nomenclature is the same as that used in the Code.

The first card is the option control card discussed in the previous sections. The first variable ITYPE may be equal to 1, 2, or 3, depending on the type of flange being analyzed. The next variable IBOND will always be 0, in which case the displacement  $u_r$  will be equal to zero at  $x = h$ , as specified by the Code. The third variable ICODE will always be 2 and will therefore cause the program to compute the stresses in accordance with Code paragraph UA-50 for straight or tapered-hub flanges or paragraph UG-34(c)(2) for blind flanges. The last variable MATE will always be 1 for Code-compliance calculations. This variable essentially controls the bolt-load-change calculations made by the program. Since the ASME Code does not consider bolt-load changes in determining compliance, when MATE = 1 these calculations are not performed.

The second card in the data set enters the physical dimensions of the flange being analyzed, as shown in Table 9. These dimensions are the outside and inside diameters of the flange ring A and B, the ring thickness  $t$ , the pipe-wall thickness  $g_0$ , the hub thickness at the hub-to-ring juncture  $g_1$ , the hub length  $h$ , the bolt-circle diameter  $C$ , and the internal pressure. All dimensions are expressed in inches; the pressure is in pounds per square inch.

Table 9. Input data for ASME bolt and flange stress calculation, using symbols defined in ASME Code, Section VIII, Division 1, Appendix II

Option-Control Card (Read-in in FLANGE)

Column number	5	10	15	20
Variable	ITYPE <sup>a</sup>	IBØND	ICØDE	MATE
Value	1, 2, or 3	0	2	1

Second Card (Read-in in TAPHUB, STHUB, or BLIND)<sup>b,c</sup>

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70	71-80
Quantity	Flange outer diameter A	Flange inner diameter B	Ring thickness t	Pipe-wall thickness g <sub>0</sub>	Hub thickness g <sub>1</sub>	Hub length h	Bolt-circle diameter c	Pressure p
Variable	XA	XB	TH	G0	G1	HL	C	PRESS

Third Card (Read-in in ASMEIN)<sup>d</sup>

Column number	0-10	11-20	21-30	31-40 <sup>d</sup>	41-50	51-60	61-70 <sup>e</sup>	72 <sup>d</sup>	73-80 <sup>d</sup>
Quantity	Gasket factor m	Minimum design seating stress y	Gasket outer diameter G <sub>0</sub>	Gasket inner diameter G <sub>i</sub>	Allowable bolt stress at design temperature S <sub>b</sub>	Allowable bolt stress at atmospheric temperature S <sub>a</sub>	Bolt cross-sectional area A <sub>b</sub>	Option I	Basic gasket seat width b <sub>0</sub>
Variable	XM	Y	GOUT	GIN	SB	SA	AB	INBO	BO

<sup>a</sup>When ITYPE = 2 for a ring flange, g<sub>0</sub>, on the second card, should be a suitably small value, but not zero (e.g., 0.01).

<sup>b</sup>Subroutines TAPHUB and STHUB call both ASMEIN and FLGDW; BLIND calls ASMEIN.

<sup>c</sup>For ITYPE = 2, g<sub>0</sub> must be entered; g<sub>1</sub> and h are not used. For ITYPE = 3, B, g<sub>0</sub>, g<sub>1</sub>, and h are not used.

<sup>d</sup>If I (Column 72) is 0, the program computes b, b<sub>0</sub>, and G for the particular case of b<sub>0</sub> = N/2 = 1/2(G<sub>0</sub> - G<sub>i</sub>)/2 as defined in Table UA-49.2 sketches (1a) and (1b) of the Code. Columns 73-80 may then be left blank. For other values of b<sub>0</sub>, enter I = 2. In this case, the value of G<sub>i</sub> is not used and thus columns 31-40 may be left blank.

<sup>e</sup>Column 71 is blank.

The third card inputs other physical data, including the gasket factor  $m$ , the minimum-design seating stress  $y$ , the outside diameter of the gasket  $G_o$ , the inside diameter of the gasket  $G_i$ , the allowable bolt stress at design temperature  $S_b$ , the allowable bolt stress at ambient temperature  $S_a$ , the total cross-sectional area of the bolts  $A_b$ , an option-selecting variable  $I$ , and the basic gasket-seating width  $b_o$ . The option variable  $I$  controls the calculation of  $b$  and  $G$ .

#### Output for Code-Compliance Calculations

For Code-compliance calculations, all of the output for each flange being analyzed is printed on a single page (e.g., see examples 1 and 2 of Appendix A). The program prints the input data followed by the effective gasket seating width  $b_o$  and the loads, bolt stresses, and moments identified under the headings shown in Table 10. For compliance with Code criteria, the value of SB1 must not exceed the allowable bolt stress at design temperature, and the value of SB2 must not exceed the allowable bolt stress at atmospheric\* temperature.

Immediately below, the program prints the flange stresses needed for comparison with the ASME Code criteria. For tapered-hub and straight-hub flanges ( $I\text{TYPE} = 1$  or  $2$ ), the program prints five stresses under the two headings "ASME FLANGE STRESSES AT OPERATING MOMENT, MOP" and "ASME FLANGE STRESSES AT GASKET SEATING MOMENT." The stresses are identified as follows:

$2/3(\text{SH})$  = two-thirds of the longitudinal stress on the outside surface at the small end of the hub,  
 $\text{ST}$  = the tangential stress on the hub side of the ring,  
 $\text{SR}$  = the radial stress on the hub side of the ring,  
 $(\text{SH} + \text{ST})/2$  = the average of SH and ST, and  
 $(\text{SR} + \text{ST})/2$  = the average of SR and ST.

---

\* Although "ambient" would probably be a better term here, the word "atmospheric" is used as it is used in the Code.

Table 10. Output data identification, ICØDE = 2,  
(ASME Code stresses)

ASME Code symbol <sup>a</sup>	Program symbol	Description <sup>a</sup>	
b <sub>o</sub>	BO	See ASME Code, Table UA-49.2. (This will be input data for I = 2.) <sup>b</sup>	
H	WM11	$\pi G^2 p / 4$	
	WM12	$2\pi b G m p$	
W <sub>m1</sub>	WM1	$\pi G^2 p / 4 + 2\pi b G m p$	
	SB1	Bolt stress, $W_{m1} / A_b$	
W <sub>m2</sub>	WM2	$\pi b G y$	
	SB2	Bolt stress, $W_{m2} / A_b$	
(e)	MOP	$H_G h_G + H_T h_T + H_D h_D$	
(d)	MGS	$[(A_m + A_b) S_a / 2] \times [(C - G) / 2]$	Except for ITYPE = 3 (Blind flanges)
	MGS1	$W_{m2} \times [(C - G) / 2]$	

<sup>a</sup>All symbols are defined in the ASME Boiler Code, Section VIII, Div. 1 (1971), Appendix II.

<sup>b</sup>See Footnote *d* of Table 9.

<sup>e</sup>MOP is the operating moment as defined by the ASME Code.

<sup>d</sup>MGS is the gasket seating moment as defined by the ASME Code.

For compliance with the Code Criteria, each of the above values printed under the first heading must not exceed the allowable stress for the flange material at the design temperature. The values printed under the second heading must not exceed the allowable stress for the flange material at atmospheric temperature.

For blind flanges (ITYPE = 3), the program prints the following five quantities under the heading "ASME CODE STRESSES FOR BLIND FLANGE":

SP = the stress due to pressure loading only,

SW1 = the stress due to the bolt load  $W_{m1}$  only, where  $W_{m1} = \pi G^2 p / 4 + 2\pi b G m p$ ,

SOP = the stress at operating conditions,

SW2 = the stress due to the bolt load  $W_{m2}$ , where  $W_{m2} = \pi b G y$ , and

SGS = the stress at gasket-seating conditions.

For Code compliance, SOP must not exceed the allowable stress for the flange material at design temperature, and SGS must not exceed the allowable stress at atmospheric temperature.

### Input for General Purpose Calculations

When the computer program is used for general purpose calculations, (i.e., when it is used for calculating displacements and stresses other than those needed specifically for checking Code compliance), the user may select almost any combination of admissible values for the four variables ITYPE, IBØND, ICØDE, and MATE coded in the option control data card. The only specific requirement is that the variable ICØDE must be less than two for other than Code-compliance calculations. In this case the input data are structured somewhat differently than those described in the previous section.

When ICØDE = 0 and MATE = 1, (i.e., only one flange is to be analyzed and the user does not wish to obtain bolt load changes), three data cards are needed as shown in Table 11. These are the option-control card (for which ITYPE may be 1, 2, or 3 and IBØND may be 0 or 2) and two physical-property data cards.

When ICØDE = 0 and MATE = 2, 3, ... 6, the program will analyze a pair of flanges mated together and give bolt load changes. If MATE = 2, the program performs the calculations for a pair of identical flanges mated together. The input data requirements include the data cards shown in Table 11 plus the three cards shown in Table 12. These last three cards contain data on the physical properties of the bolts and gasket, supplemental data on the initial and final state of the flange, and other conditions. For this case, the six cards listed below complete the input data set when MATE = 2.

Table 11. Input data for the general purpose analysis of a single flange and partial data for paired flanges

Option-Control Card: [FØRMT (4I5) read-in in FLANGE]

Column number	5	10	15	20
Variable	ITYPE <sup>a,b</sup>	IBØND	ICØDE	MATE <sup>c</sup>
Value	1, 2, or 3	0 to 2	0	1 or (2)

Second Card: [FØRMT (8E10.5); read-in in TAPHUB, STHUB, or BLIND]

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70	71-80
Quantity	Flange outer diameter A	Flange inner diameter B	Ring thickness t	Pipe-wall thickness g <sub>0</sub>	Hub thickness g <sub>1</sub>	Hub length h	Bolt-circle diameter C	Pressure p
Variable	XA	XB <sup>b</sup>	TH	GO <sup>a,b</sup>	G1 <sup>a,b</sup>	HL <sup>a,b</sup>	C	PRESS

Third Card: [FØRMT (5E10.5); read-in in TAPHUB, STHUB, or BLIND]

Column number	0-10	11-20	21-30	31-40	41-50
Quantity	Moment applied to flange ring M	Coefficient of thermal expansion ε <sub>f</sub>	Thermal gradient pipe or hub to ring Δ	Modulus of elasticity flange E	Gasket centerline diameter 2g
Variable	XMOA <sup>b</sup>	EF <sup>b</sup>	DELTA <sup>b</sup>	YM	G

<sup>a</sup>When ITYPE = 2, GO must be entered; G1 and HL are not used.

<sup>b</sup>When ITYPE = 3, XB, GO, G1, HL, EF, and DELTA are not used; the value for XMOA is the total bolt load W.

<sup>c</sup>When MATE = 2, additional data as described in Table 12 are also required.

Table 12. Last three input data cards for the general purpose analysis of paired flanges

Card No. 4 or 7:<sup>a</sup> [FØRMT (7E10.5); read-in in FLGDW]

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70
Quantity	Nominal bolt diameter	Initial state; bolt modulus of elasticity $E_b$	Bolt coefficient of thermal expansion $\epsilon_b$	Final state; bolt temperature $T_b$	Outside diameter of gasket	Inside diameter of gasket	Cross-sectional root area of all bolts
Variable	BSIZE <sup>b</sup>	YB	EB	TB	XG0 <sup>c</sup>	XG1 <sup>c</sup>	AB

Card No. 5 or 8:<sup>a</sup> [FØRMT (6E10.5); read-in in FLGDW]

Column number	0-10	11-20	21-30	31-40	41-50	51-60
Quantity	Gasket thickness $v_o$	Initial state; gasket modulus of elasticity $E_g$	Gasket coefficient of thermal expansion $\epsilon_g$	Final state; gasket temperature $T_g$	A free bolt length variable	Equivalent pressure see Eq. (86) of text $p^*$
Variable	VO	YG	EG	TG <sup>d</sup>	FACE <sup>b</sup>	PBE

Card No. 6 or 9:<sup>a</sup> [FØRMT (7E10.5); read-in in FLGDW]

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70
Quantity	Initial bolt load $W_1$	Final state temperature of flange, side one $T_{f2}$	Final state temperature of flange, side two $T'_{f2}$	Final state flange modulus of elasticity, side one $E_{f2}$	Final state flange modulus of elasticity, side two $E'_{f2}$	Final state bolt modulus of elasticity $E_{b2}$	Final state gasket modulus of elasticity $E_{g2}$
Variable	W1	TF <sup>d</sup>	TFP <sup>d</sup>	YF2	YFP2	YB2	YG2

<sup>a</sup>First card number applies when MATE = 2; second number applies when MATE = 3 and 4 or 5 and 6.

<sup>b</sup>The effective bolt load is calculated as  $W_0 = XLB = TH + THP + VO + BSIZE + FACE$ .

<sup>c</sup>Values for  $G_1$  and  $A_g$  are calculated using input variables XG0 and XG1.

<sup>d</sup>Initial-state temperatures are defined as zero.

<u>Card No.</u>	<u>Identification</u>
1	Option control card with MATE = 2
2 } 3 }	Data cards per Table 11
4 } 5 } 6 }	Data cards per Table 12

When ICØDE = 0 and MATE = 3, the program performs the calculations for a pair of nonidentical flanges, neither of which, however, is blind (i.e., ITYPE = 1 or 2  $\neq$  3 on the option-control card). Data for the first flange of the pair follows the option-control card. Data for the second flange in the pair will follow an option-control card with MATE = 4. The three cards described in Table 12 will then complete the data requirements. The complete input data set for analyzing a pair of nonidentical flanges (neither of which is blind) consists of the following nine cards.

<u>Card No.</u>	<u>Identification</u>
1	Option-control card, ITYPE $\neq$ 3, ICØDE = 0, MATE = 3
2 } 3 }	Data cards per Table 11 for first flange of pair
4	Option-control card, ITYPE $\neq$ 3, ICØDE = 0, MATE = 4
5 } 6 }	Data cards per Table 11 for second flange of pair
7 } 8 } 9 }	Data cards per Table 12

When ICØDE = 0 and MATE = 5, the program performs the calculations for a flanged joint that is closed with a blind flange. For this option,

the blind flange is designated as the first flange and the mating flange is designated as the second with MATE = 6. As before, the input data set is completed by using the data cards described in Table 12. The complete input data set for this case consists of the following nine cards.

<u>Card No.</u>	<u>Identification</u>
1	Option-control card, ITYPE = 3, ICØDE = 0, MATE = 5
2 } 3 }	Data cards per Table 11 for blind flange
4	Option-control card, ITYPE = 1 or 2, ICØDE = 0, MATE = 6
5 } 6 }	Data cards per Table 11 for second flange
7 } 8 } 9 }	Data cards per Table 12

#### Output from General Purpose Calculations

The amount and format of the data printed out are determined predominantly by the number and types of flanges being analyzed, which in turn are determined by the value of the option-control variable MATE. When MATE = 1, the output consists of one page of printout, which gives (1) the input data; (2) the three sets of stresses for moment loading only (the bolt load for blind flanges), pressure loading only, and temperature-gradient (hub to ring) loading only (except for blind flanges); and (3) the displacements produced by the calculated stresses. The symbols used on the printout are explained in Tables 13 and 14.

When MATE = 2, the output consists of three pages of printout. The first page gives (1) the input data and (2) the parameters involved in the bolt-load-change calculations. The second page gives (1) the loadings, (2) the residual bolt loads, and (3) the initial and residual moments. The symbols used in the first and second page of printout are explained in Tables 15 and 16. The third page gives the stresses and

Table 13. Output data identification, stresses, displacements, and rotation

Theory Symbol	Program symbol	Description
$(\sigma_l)_o$	SLSO <sup>a</sup>	Stress, longitudinal, small end of hub, outside surface
$(\sigma_l)_i$	SLSI <sup>a</sup>	Stress longitudinal, small end of hub, inside surface
$(\sigma_c)_o$	SCSO <sup>a</sup>	Stress, circumferential, small end of hub, outside surface
$(\sigma_c)_i$	SCSI <sup>a</sup>	Stress, circumferential, small end of hub, inside surface
$(\sigma_l)_o$	LLLO	Stress, longitudinal, large end of hub, outside surface
$(\sigma_l)_i$	LLLI	Stress, longitudinal, large end of hub, inside surface
$(\sigma_c)_o$	SCLO	Stress, circumferential, large end of hub, outside surface
$(\sigma_c)_i$	SCLI	Stress, circumferential, large end of hub, inside surface
$(\sigma_t)_o$	STH	Stress, tangential, hub side of ring, at $r = b$
$(\sigma_t)_i$	STF	Stress, tangential, face side of ring, at $r = b$
$(\sigma_r)_o$	SRH	Stress, radial, hub side of ring, at $r = b$
$(\sigma_r)_i$	SRF	Stress, radial, face side of ring, at $r = b$
$\delta_g$	ZG	Axial displacement at $r = g$ } ( $\delta \equiv 0$ at $r = b$ )
$\delta_c$	ZC	Axial displacement at $r = c$ }
$q_f^{hG}$	QFHG	$-\delta_c + \delta_g$
$y_0$	YO	Radial displacement, small end of hub
$y_1$	Y1	Radial displacement, large end of hub
	THETA	Rotation of ring at $r = b$
		For blind flanges <sup>b</sup>
$\sigma_r, \sigma_t, r = o$	SORT	Stress, $r = o$ , radial and tangential
$\sigma_r, r = g$	SGR	Stress, $r = g$ radial
$\sigma_t, r = g$	SGT	Stress, $r = g$ , tangential
$\sigma_r, r = c$	SCR	Stress, $r = c$ , radial
$\sigma_t, r = c$	SCT	Stress, $r = c$ , tangential
$\sigma_t, r = a$	SAT	Stress, $r = a$ , tangential
$\delta_c$	ZC	Axial displacement at $r = c$ ( $\delta \equiv 0$ at $r = g$ )

<sup>a</sup>For "Straight Hub Flange," these are at juncture of hub with ring.

<sup>b</sup>All stresses are for the side of the flange opposite the pressure-bearing side. Stresses on the pressurized side of the flange have reversed signs.

Table 14. Output data identification when MATE = 2, 3 and 4, or 5 and 6

Theory symbol	Program symbol	Description
$q_{f1} h_G$	QFHG	Axial displacement from C to G, unit moment load
$q_{p1} h_G$	QPHG	Axial displacement from C to G, unit pressure load
$q_{t1} h_G$	QTHG <sup>a</sup>	Axial displacement from C to G, unit DELTA
2b	XB <sup>a,b</sup>	Inside diameter
$g_0$	GO <sup>a,b</sup>	Pipe wall thickness
t	TH	Ring thickness
$E_{f1}$	YM <sup>b</sup>	Modulus of elasticity of flange material, initial state
$E_{f2}$	YF2 <sup>c</sup>	Modulus of elasticity of flange material, final state
$\epsilon_f$	EF <sup>b</sup>	Coefficient of thermal expansion of flange material
( )'	( )P	The above nine symbols with a prime mark (') on the theory symbols are for the mating flange. The program symbol has the added final letter "p."

<sup>a</sup>For blind flanges, these values are not significant; an artificial value of -1.0000 is printed out.

<sup>b</sup>These values are input data for flange side one, input cards 2 and 3 (see Table 11). For MATE = 2, these values, along with calculated values of QFHG, QPHG, and QTHG, are used for side one and side two (i.e., an identical pair). If MATE = 3 or 5, the primed values are stored; the unprimed values are read in by input cards 5 and 6, and values of QFHGP, QPHGP, and QTHGP are calculated.

<sup>c</sup>Input from card 6 for MATE = 2, card 9 for MATE = 3 and 4 or 5 and 6 (see Table 11).

Table 15. Output data identification, MATE = 2, 3 and 4, or 5 and 6, bolts, gasket, and loadings data

Theory symbol	Program symbol	Description <sup>a</sup>
$\ell$	XLB	Effective bolt length
$A_b$	AB	Cross-sectional root area of all bolts
C	C	Bolt-circle diameter
$E_{b1}$	YB	Modulus of elasticity, bolts, initial state
$E_{b2}$	YB2	Modulus of elasticity, bolts, final state
$\epsilon_b$	EB	Coefficient of thermal expansion, bolts
$v_0$	VO	Gasket thickness
	XGO	Outside diameter of gasket
	XGI	Inside diameter of gasket
$E_{g1}$	YG	Modulus of elasticity of gasket, initial state
$E_{g2}$	YG2	Modulus of elasticity of gasket, final state
$\epsilon_g$	EG	Coefficient of thermal expansion, gaskets
$W_1$	W1	Initial total bolt load
$T_b$	TB	Temperature of bolts, final state
$T_{f2}$	TF	Temperature of flange ring, side one, final state
$T'_{f2}$	TFP	Temperature of flange ring, side two, final state
$T_g$	TG	Temperature of gasket, final state
$\Delta$	DELTA	Thermal gradient, pipe/hub to ring, side one
$\Delta'$	DELTAP	Thermal gradient, pipe/hub to ring, side two
P	PRESS	Internal pressure

<sup>a</sup>All values are input data, except XLB which is calculated by the equation:  $XLB = TH + THP + VO + BSIZE + FACE$ .

Table 16. Output data identification, MATE 2, 3 and 4, or 5 and 6, residual bolt loads and moments

Theory symbol	Program <sup>a</sup> symbol	Effect included
$W_{2a}$	W2A	Relative change in temperature of bolts, gasket, flange (AXIAL THERMAL)
$W_{2b}$	W2B	Change in moment arms (MOMENT SHIFT)
$W_{2c}$	W2C	Total pressure
$W_{2d}$	W2D	Thermal gradient, pipe/hub to ring (DELTA THERMAL)
$W_2$	W2	All of the above, plus change in modulus of elasticity (COMBINED)

<sup>a</sup>The change in bolt load (e.g.,  $W_1 - W_{2A}$ ) and ratio of residual to initial bolt load (e.g.,  $W_{2A}/W_1$ ) are also printed out, along with the corresponding values of the initial moment ( $M_1$ ) and residual moments,  $M_{2A}$ , ...,  $M_{2P}$ . The residual moment identifiers with final letter P (for prime) are for the first entered of a pair of nonidentical flanges. If the pair of flanges are identical, then  $M_{2B} = M_{2BP}$ , etc. The residual moment values are not significant for blind flanges, ITYPE = 3; therefore, residual bolt loads are used for blind flanges.

displacements as for the case when MATE = 1 plus the stresses and displacements for combined loading. The heading includes the value of the residual moments  $M_2 = M_{2P}$  used for the combined-loading calculations.

When MATE = 3 and 4 or 5 and 6, the output consists of four pages of printout. The first two pages have the same format as for the case when MATE = 2, except input data for both of the (nonidentical) flanges are printed. The residual moments on the last line of page 2 apply to flange one; those on the preceding line apply to flange two. The last two pages of printout are for flange one and flange two, respectively, and are identical in format to the third page of the printout for the case when MATE = 2.

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APPENDIX A

EXAMPLES OF APPLICATION OF COMPUTER PROGRAM FLANGE



## APPENDIX A

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## INTRODUCTION

Several examples have been selected to illustrate the input/output data of the computer program FLANGE and the significance of the results. The flange selected for analysis is one included in API Standard 605.\* The particular size and rating selected was the 60-in., 300-lb tapered-hub flange. This particular flange represents a design in which the bolt stresses and flange stresses are close to the upper limits set in API-605.

Six examples are included:

1. A Code stress calculation is performed for a tapered-hub flange at its rated pressure of 720 psi at 100°F. The results show that this particular flange does indeed meet the criteria given in API-605 at 720 psi and 100°F.
2. A Code stress calculation is performed for a blind flange to match the 60-in., 300-lb API-605 tapered-hub flange. The thickness of the blind flange was selected so that its maximum stress was the allowable flange stress of 17,500 psi used in API-605.
3. A blind flange bolted to a tapered-hub flange under pressure loading only is analyzed.
  - (a) For an initial bolt stress equal to the API-605 allowable stress for the bolting material of 20,000 psi, the results indicate that the flanged joint will probably leak at its rated pressure of 720 psi at 100°F.
  - (b) For an initial bolt stress of 44,300 psi, the results indicate that the flanged joint will pass a hydrostatic test of  $1.5 \times 720$  psi at ambient temperature.
4. A tapered-hub flange bolted to an identical tapered-hub flange with an initial bolt stress of 46,100 psi is analyzed.

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\* *Large-Diameter Carbon Steel Flanges (Size: 26 Inches to 30 Inches, Inclusive, Nominal Pressure Rating: 75, 150, and 300 lb)*, API Standard 605, 1st Ed., American Petroleum Inst., New York, 1967.

- (a) For pressure loading only, the results indicate that the flanged joint will hold a hydrostatic test pressure of  $1.5 \times 720$  psi.
- (b) For pressure loading of 300 psi (API-605 rated pressure at 850°F) plus an external bending moment that produces an axial stress in the attached pipe of 7500 psi, the results indicate that the flanged joint is adequate to carry these loads.

DETAILS OF THE FLANGE USED IN THE EXAMPLES

A sketch of the tapered-hub flange is shown in Fig. A.1. The dimensions are as specified in API-605. The inside diameter and dimensions B (and therefore  $g_0$  and  $g_1$ ) are not specified in API-605. For the purpose of checking ratings, the following equation given in API-605 was used to establish B:

$$B = D_o - 2t_p , \quad (A.1)$$

where

- $D_o$  = nominal outside diameter of pipe, in.;
- $t_p = p_1 D_o / 2(0.875)S$  (but not less than 0.25), in.;
- $p_1$  = rated pressure at 100°F, psi;
- 0.875 = assumed pipe-wall tolerance; and
- $S = 20,000$  psi, the allowable stress at 100°F.

The definition of  $t_p$ , with  $D_o = 60$  in. and  $p_1 = 720$  psi, leads to  $t_p = g_0 = 1.2343$  in. Equation (A.1) gives  $B = 57.5314$  in. and  $g_1 = (X-B)/2 = 2.7030$  in.

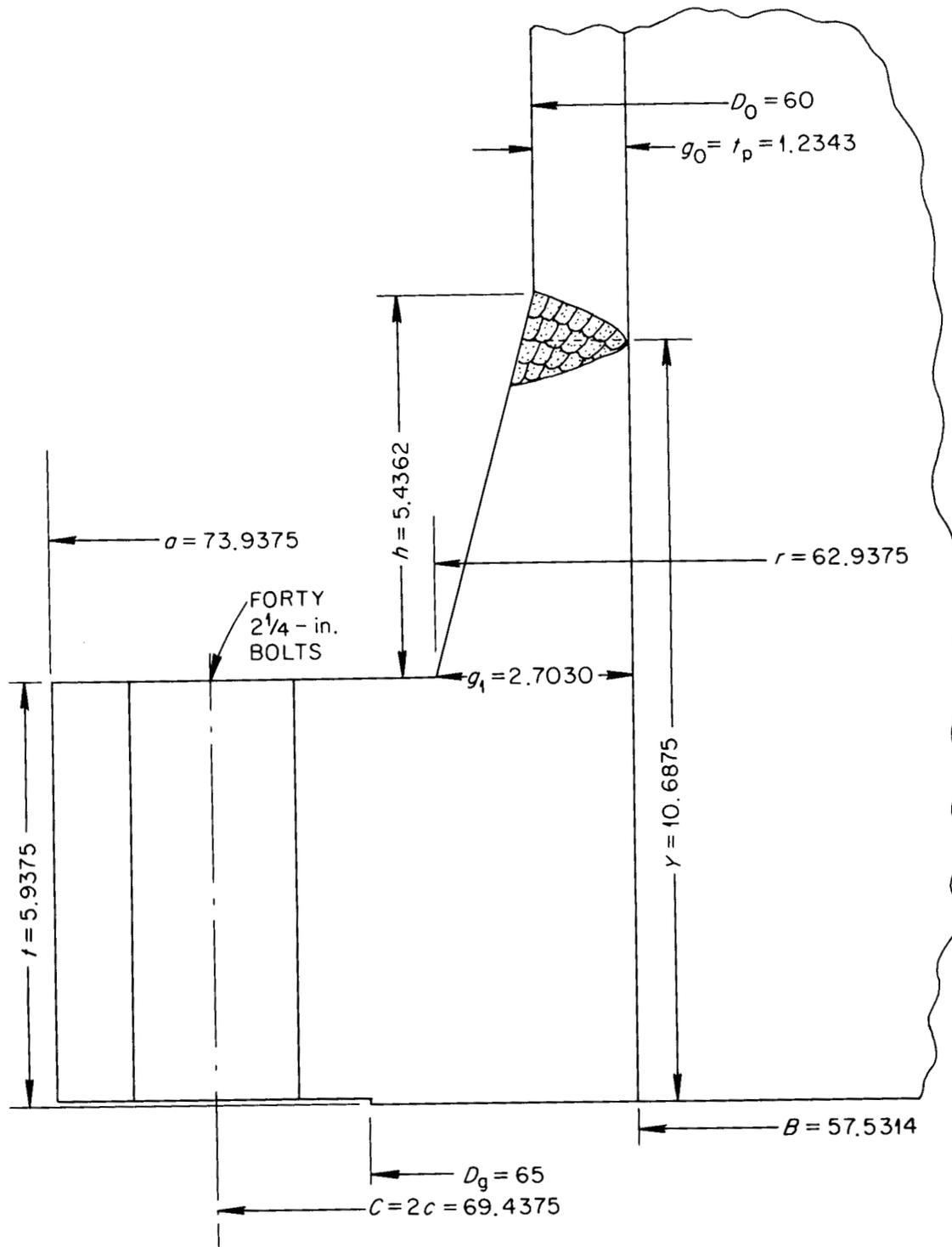
For the purpose of checking ratings, the hub length  $h$  was calculated by the equation given in API-605:

$$h = Y - t + 0.176g_0 + 0.469 .$$

Dimensions  $Y$  and  $t$  are shown in Fig. A.1. For this flange:

$$h = 10.6875 - 5.9375 + 0.176(1.2343) + 0.469 = 5.4362 \text{ in.}$$

The API-605 standard states that flange ratings were based on use of a 1/16-in.-thick, compressed-asbestos, flat ring-shaped gasket, with an inside diameter 1/4 in. larger than the outside diameter of the pipe and with an outside diameter equal to the raised-face diameter. For the 60-in., 300-lb flange, the gasket inside diameter is 60.25 in.; its



DIMENSIONS IN INCHES

Fig. A.1. Dimensions (in inches) of 60-in., 300-lb API-605 tapered-hub flange. The terms B, R, C,  $D_0$ , X, and A are diameters expressed in inches.

outside diameter is 65 in. According to the ASME Code, for a 1/16-in.-thick asbestos gasket,  $m = 2.75$ , and  $y = 3700$  psi.

The 60-in., 300-lb flange has forty 2-1/4-in.-diam. bolts. For an 8-pitch thread, the root area per bolt is  $3.423 \text{ in.}^2$ , giving a total bolt root area of  $136.92 \text{ in.}^2$ .

## ASME CODE CALCULATIONS, EXAMPLES 1 AND 2

The input data for examples 1 and 2 are shown in Table A.1. The source of all input for Cards 2 and 3 are contained in the previous section on flange details, except that the thickness of the blind flange was selected\* so that the controlling flange stress is 17,500 psi. Note that Card 2 is identical for examples 1 and 2 except for the value of  $t$ ; however,  $B$ ,  $g_0$ ,  $g_1$ , and  $h$  are not used for example 2 (blind flange), and any number (including zero) can be entered for these dimensions.

Example 1 is a Code stress calculation for the 60-in., 300-lb API-605 tapered-hub flange at its rated pressure of 720 psi at 100°F. The output data are shown in Table A.2. The value of  $SB1 = 20,033$  psi is the controlling bolt stress, which essentially meets the API criterion value of a bolt stress not greater than 20,000 psi. The value of  $(SH + ST)/2 = 17,293$  psi under the heading "ASME FLANGE STRESSES AT OPERATING MOMENT, MOP" is the controlling flange stress and meets the API-605 criterion of a controlling flange stress not greater than 17,500 psi. The results, therefore, confirm that the 60-in., 300-lb API-605 tapered-hub flange meets the stated criteria.

The reader who is accustomed to using hand calculations for checking flange designs according to Code rules will note that the program input does not require either the factors  $T$ ,  $U$ ,  $Y$ ,  $Z$  from Code Fig. UA-51.1, or  $F$ ,  $V$ , and  $f$  from Code Figs. UA-51.2, UA-51.3, and UA-51.6, respectively. These factors are calculated by the computer program. In addition to simplifying the input, the program accurately calculates  $F$ ,  $V$ , and  $f$  values for any values of  $h/h_0$  and  $g_1/g_0$ , including those beyond the range of the Code figures.

Example 2 is a Code stress calculation for a blind flange to match the 60-in., 300-lb API-605 tapered-hub flange. The calculation method is that given in UG-34 [Eq. (2)], with  $C = 0.3$ . The output data are shown in Table A.3. The controlling flange stress is  $SOP = 17,500$  psi;

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\* API-605 does not give blind-flange thicknesses.

Table A.1. Input data for ASME Code stress calculations, examples 1 and 2

First card

Column number	5	10	15	20
Variable	ITYPE	IBOND	ICODE	MATE
Example 1	1	0	2	1
Example 2	3	0	2	1

Second card

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70	71-80
Variable	A	B	t	$g_0$	$g_1$	h	C	P
Example 1	73.9375	57.5314	5.9375	1.2343	2.7030	5.4362	69.4375	720.
Example 2	73.9375	57.5314 <sup>a</sup>	7.9044	1.2343 <sup>a</sup>	2.7030 <sup>a</sup>	5.4362 <sup>a</sup>	69.4375	720.

Third card

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70 <sup>b</sup>	72	73-80
Variable	m	y	$G_o$	$G_i$	$S_b$	$S_a$	$A_b$	I	$b_o$
Example 1	2.75	3700.	65.	60.25	20000.	20000.	136.92	0	0
Example 2	2.75	3700.	65.	60.25	20000.	20000.	136.92	0	0

<sup>a</sup>Not used in calculations for a blind flange.

<sup>b</sup>Column 71 is blank.

Table A.2. Output data for example 1, ASME Code analysis of a tapered-hub flange

FLANGE O.D.,A	FLANGE I.D.,B	FLANGE THICK.,T	PIPE WALL,G0	HUB AT BASE,G1	HUB LENGTH,H	EOLT CIRCLE,C	PRESSURE, P
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	720.000
M	Y	GOUT	GIN	SB	SA	AB	
2.75000	3700.00000	65.00000	60.25000	20000.00000	20000.00000	136.92000	
BO	WM11	WM12	WM1	SB1	WM2	SB2	
1.1875D 00	2.3097D 06	4.3322D 05	2.7430D 06	2.0033D 04	4.0477D 05	2.9563D 03	
MOP	MGS	MGS1					
1.1719D 07	7.5742D 06	1.1186D 06					

ASME FLANGE STRESSES AT OPERATING MOMENT, MOP

(2/3)\*SH= 1.5608D 04 ST = 1.1174D 04 SR = 8.4442D 03 (SH+ST)/2= 1.7293D 04 (SH+SR)/2= 1.5928D 04

ASME FLANGE STRESSES AT GASKET SEATING MOMENT, MGS

(2/3)\*SH= 1.0087D 04 ST = 7.2216D 03 SR = 5.4576D 03 (SH+ST)/2= 1.1176D 04 (SH+SR)/2= 1.0294D 04

Table A.3. Output data for example 2, ASME Code analysis of a blind flange

FLANGE O.D.,A	FLANGE I.D.,B	FLANGE THICK.,T	PIPE WALL,G0	HUB AT BASE,G1	HUB LENGTH,H	BCLT CIRCLE,C	PRESSURE, P
73.93750	0.0	7.90440	0.0	0.0	0.0	69.43750	720.000
M	Y	GOUT	GIN	SB	SA	AB	
2.75000	3700.00000	65.00000	60.25000	20000.00000	20000.00000	136.92000	
BO	WM11	WM12	WM1	SB1	WM2	SB2	
1.1875D 00	2.3097D 06	4.3322D 05	2.7430D 06	2.0033D 04	4.0477D 05	2.9563D 03	
ASME CODE STRESSES FOR BLIND FLANGE							
SP	SW1	SOP	SW2	SGS			
1.4121D 04	3.3792D 03	1.7500D 04	4.9865D 02	3.3763D 03			

the flange thickness of 7.9044 in. was selected to obtain this result. This example was included to illustrate that a blind flange may have to be considerably thicker than a mating flange in order for both to meet the Code stress limitations.

## BLIND-TO-TAPERED-HUB FLANGED JOINT, EXAMPLES 3(a) AND 3(b)

Input Data

The input data for examples 3(a) and 3(b) are shown in Table A.4. In addition to the basic purpose of illustrating input/output data for the program FLANGE, this pair of examples was selected to show how the program can be used to estimate required initial bolt stresses. In addition, example 3(a) shows how the general purpose option (ICODE  $\neq$  2) gives stresses as obtained from Code calculations plus deformation data and additional stresses.

Examples 3(a) and (b) do not involve temperature gradients or temperatures other than ambient; hence, the modulus of elasticity is the same for the initial and final states. Values of temperatures for the flanges, bolts, and gaskets in the final state have been entered as zero. The initial-state reference temperature is zero; hence, a zero in the final state denotes a zero thermal gradient. However, the value of DELTA (the hub-to-ring thermal gradient) cannot be entered as zero without causing a divide-check error, so a value of 0.01 was used. A smaller value could be used (e.g., 0.001 or 0.0001), but the output data shows that DELTA = 0.01 is sufficiently small so that its influence is negligible. A coefficient of thermal expansion of  $6 \times 10^{-6}$  has been entered but is not significant in these examples.

The value of FACE, which is intended to permit use of a bolt length other than  $l_0 = TH + THP + VO + BSIZE$ , was entered as zero. The modulus of elasticity for both the flanges and the bolts was assumed to be  $3 \times 10^7$  psi. The modulus of elasticity for the 1/16-in.-thick asbestos gasket was assumed to be  $3 \times 10^6$  psi.

Some comments on the use of a modulus of elasticity of  $3 \times 10^6$  for a 1/16-in. asbestos gasket may be appropriate. The stress-strain relationship for such a gasket, which is confined between the two rigid flange faces, is highly nonlinear and both time and history dependent. Starting out with a new gasket, the first increment of bolt stress to produce a gasket stress of 1000 psi might decrease the gasket thickness

Table A.4. Input data for blind-to-tapered-hub flanged joint, examples<sup>a</sup> 3a and 3b

Card No.	Variables and numerical values								Read format
1	ITYPE	IBOND	ICODE	MATE					
	3	0	0	5					415
2	A	B	t	g <sub>0</sub>	g <sub>1</sub>	h	C	P	
	73.9375	57.5314	7.9044	1.2343	2.7030	5.4362	69.4375	720.	8E10.5 (1080.)
3	XMOA <sup>b</sup>	EF	DELTA <sup>c</sup>	YM	G				
	2.7430D+6 (6.0656D+6)	6. D-6	.01	3. D+7	62.625				5E10.5
4	ITYPE	IBOND	ICODE	MATE					
	1	0	0	6					415
5	A	B	t	g <sub>0</sub>	g <sub>1</sub>	h	C	P	
	73.9375	57.5314	5.9375	1.2343	2.7030	5.4362	69.4375	720.	8E10.5 (1080.)
6	XMOA	EF	DELTA <sup>c</sup>	YM	G				
	1.1719D+7 (2.0661D+7)	6. D-6	.01	3. D+7	62.625				5E10.5
7	BSIZE	YB	EB	TB	XG0	XGI	AB		
	2.25	3. D+7	6. D-6	0	65.	60.25	136.92		7E10.5
8	VO	YG	EG	TG	FACE	PBE			
	.0625	3. D+6	6. D-6	0	0	0			6E10.5
9	W1	TF	TFB	YF2	YFP2	YB2	YG2		
	2.7430D+6 (6.0656D+6)	0	0	3. D+7	3. D+7	3. D+7	3. D+6		7E10.5

<sup>a</sup>Values in parentheses are for example 3b.

<sup>b</sup>Initial bolt load is used here since ITYPE = 3; see footnote *b* to Table 11 in the text.

<sup>c</sup>Since DELTA cannot be entered as zero, 0.01 was used as a satisfactorily small value.

by 20%, so that the modulus would be  $1000/(0.2 \times 0.0625) = 8 \times 10^4$  psi. Crude observations indicate that, at a bolt stress that produces a gasket stress of 40,000 psi, the gasket thickness is about one-half of its original thickness, so that the average modulus up to this stress is  $40,000/0.03125 = 1.28 \times 10^6$  psi. These numbers are dependent upon the ratio of width to thickness of the gasket and the time under stress, particularly for low gasket stress. However, for the flanged-joint analysis, we are not interested in the gasket stress-strain characteristics when the bolt load is applied but rather in the gasket stress-strain characteristics when the gasket stress is decreased after the gasket has been under bolt load for several days or many months. No data on the "spring-back" of asbestos gaskets are available, but in most flanged joints using 1/16-in.-thick asbestos gaskets, the assumed modulus of elasticity of the gasket is not very significant provided it is not unrealistically low. This can be shown for example 3 by noting that the change in the bolt load depends upon the sum of the load-displacement characteristics of the bolts, the flanges, and the gasket. The displacements for a unit bolt load are -

$$\text{for bolts: } \frac{l_0}{A_b E_b} = \frac{16.15}{136.92 \times 3 \times 10^7} = 3.93 \times 10^{-9} ,$$

$$\text{for flanges: } 2 \times QFHG = 2(1.197 \times 10^{-9}) = 2.40 \times 10^{-9} ,$$

and

$$\text{for gasket: } \frac{V_0}{A_G E_G} = \frac{0.0625}{467.26 \times E_G} = \frac{1.34 \times 10^{-4}}{E_G} .$$

As  $E_G$  varies from  $10^5$  to  $10^7$ , the sum of these three displacements varies as follows:

$E_G$	$10^5$	$3 \times 10^5$	$10^6$	$3 \times 10^6$	$10^7$
Sum of displacements ( $\times 10^9$ in.)	7.67	6.78	6.46	6.37	6.34

From the above, it can be seen that changing the gasket modulus by two orders of magnitude changes the sum of the displacement by only 17%.

The initial bolt stress used in example 3(a) is 20,033 psi, giving an initial bolt load of  $W1 = S_b A_b = 20,033 \times 136.92 = 2.743 \times 10^6$  lb;  $W1$  is entered in place of  $XMOA$  on card 6 (see footnote *b* to Table 11 of text). The initial moment,  $XMOA$ , used in example 3(a) is  $1.1719 \times 10^7$  in.-lb. The initial bolt stress used in example 3(b) is 44,300 psi, giving an initial bolt load of  $W1 = 6.0656 \times 10^6$  lb. The initial moment,  $XMOA$ , used in example 3(b) is  $2.0661 \times 10^7$  in.-lb. The reasons for using these particular values of  $W1$  and  $XMOA$  are discussed in connection with the output data for these examples.

### Output Data

#### Residual Bolt Loads

The output data for example 3(a) are shown in Table A.5. The output starts with a printout of all input data on the first page (Table A.5a).<sup>\*</sup> The parameters involved in the bolt-load-change calculations are then printed, followed by residual bolt loads and moments, all on the second page (Table A.5b). The initial bolt load under "LOADINGS" is  $2.743 \times 10^6$  lb; the residual bolt load after application of the pressure of 720 psi is given following "COMBINED" as  $W2 = 1.0948 \times 10^6$  lb. The loss in bolt load is given by  $W1 - W2 = 1.6482 \times 10^6$  lb, and the ratio of residual to initial bolt load is given by  $W2/W1 = 0.39911$ . Calculated stresses for the blind flange and for the tapered-hub flange are printed on the third and fourth pages (Tables A.5c and A.5d, respectively). These are discussed later.

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<sup>\*</sup> For convenience in referring to specific pages of multipage tables, we have used alphabetic suffixes on table numbers. For example, the first page of Table A.5 is designated Table A.5a; the second page is Table A.5b, the third is Table A.5c, etc.

Table A.5a. Output data for example 3(a), blind flange bolted to a tapered-hub flange, with initial bolt stress = 20,033 psi\*

FLANGE O.D.,A	FLANGE I.D.,B	FLANGE THICK.,T	PIPE WALL,GO	HUB AT BASE,G1	HUB LENGTH,H	BCLT CIRCLE,C	PRESSURE,P				
73.93750	57.53140	7.90440	1.23430	2.70300	5.43620	69.43750	720.000				
BOLT LOAD	COEFF. OF THERMAL EXP.	DELTA	MOD. OF ELASTICITY	MEAN DIAMETER	GASKET	ITYPE	IECND	ICODE	MATE		
2.743D	06	6.000D-06	1.000D-02	3.000D	07	6.263D	01	3	0	0	5
FLANGE O.D.,A	FLANGE I.D.,E	FLANGE THICK.,T	PIPE WALL,GO	HUB AT BASE,G1	HUB LENGTH,H	BCLT CIRCLE,C	PRESSURE,P				
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	720.000				
MOMENT LOAD	COEFF. OF THERMAL EXP.	DELTA	MOD. OF ELASTICITY	MEAN DIAMETER	GASKET	ITYPE	IECND	ICODE	MATE		
1.172D	07	6.000D-06	1.000D-02	3.000D	07	6.263D	01	1	0	0	6
BSIZE	YB	EB	TB	XGO	XGI	AB					
2.2500D 00	3.0000D 07	6.0000D-06	0.0	6.5000D 01	6.0250D 01	1.3692D 02					
VO	YG	EG	TG	FACE	PBE						
6.2500D-02	3.0000D 06	6.0000D-06	0.0	0.0	0.0						
W1	TF	TFP	YF2	YFP2	YB2	YG2					
2.7430D 06	0.0	0.0	3.0000D 07	3.0000D 07	3.0000D 07	3.0000D 06					

FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOADS, BLIND TO INTEGER PAIR

FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)

QPHG= 9.4994D-10 QPHG= 6.5350D-06 QTHG= -1.0000D 00 XB = -1.0000D 00 GO= -1.0000D 00 TH = 7.9044D 00  
YM = 3.0000D 07 YF2 = 3.0000D 07 EF = 6.0000D-06

FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)

QPHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00  
YM = 3.0000D 07 YF2 = 3.0000D 07 EF = 6.0000D-06

BOLTING

BOLT LENGTH= 1.6154D 01 BCLT AREA= 1.3692D 02 BOLT CIRCLE= 6.9438D 01  
YB = 3.0000D 07 YB2 = 3.0000D 07 EE = 6.0000D-06

GASKET

VO = 6.2500D-02 XGO = 6.5000D 01 XGI = 6.0250D 01  
YG = 3.0000D 06 YG2 = 3.0000D 06 EG = 6.0000D-06

\*For the convenience of the user, the first page of Table A.5 is designated Table A.5a, the second page is Table A.5b, the third is Table A.5c, etc. This convention is also used in the following tables.

Table A.5b (continued)

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LOADINGS

INITIAL BOLT LOAD= 2.7430D 06 BOLT TEMP.= 0.0 FLANGE ONE TEMP.= 0.0 FLANGE TWO TEMP.= 0.0  
GASKET TEMP.= 0.0 DELTA= 1.0000D-02 DELTAP= 1.00C0D-02 PRESSURE= 7.2000D 02

RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS

AXIAL THERMAL,W2A= 2.7430D 06 MOMENT SHIPT,W2B= 2.2294D 06

TOTAL PRESSURE,W2C= 1.0949D 06 DELTA THERMAL,W2D= 2.7429D 06

COMBINED,W2= 1.0948D 06

W1-W2A= 0.0 W1-W2B= 5.1359D 05 W1-W2C= 1.6481D 06 W1-W2D= 1.0333D 02 W1-W2= 1.6482D 06  
W2A/W1= 1.0000D 00 W2B/W1= 8.1276D-01 W2C/W1= 3.9915D-01 W2D/W1= 9.9996D-01 W2/W1= 3.9911D-01

INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE LOADS.

M1= 9.3433D 06 M2A= 9.3433D 06 M2B= 1.1646D 07 M2C= 7.7818D 06 M2D= 9.3430D 06 M2= 7.7814D 06  
M2BP= 4.2880D 07 M2CP= 3.9015D 07 M2P= 3.9C15D 07

Table A.5c (continued)

---

BLIND FLANGE											
CALCULATIONS FOR BOLT LOADING											
SORT=	4.0213D 03	SGR=	4.0213D 03	SGT=	4.0213D 03	SCR= -1.6157D 02	SCT=	2.5764D 03	SAT=	2.4148D 03	
ZC=	-2.6057D-03										
CALCULATIONS FOR PRESSURE LOADING											
SORT=	1.3144D 04	SGR=	-8.3815D 02	SGT=	5.0937D 03	SCR= -2.8472D 02	SCT=	4.5403D 03	SAT=	4.2555D 03	
ZC=	-4.7052D-03										
CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, =							1.0948D 06				
SORT=	1.4749D 04	SGR=	7.6681D 02	SGT=	6.6987D 03	SCR= -3.4921D 02	SCT=	5.5685D 03	SAT=	5.2193D 03	
ZC=	-5.7452D-03										

Table A.5d (continued)

---

TAPERED HUB FLANGE

CALCULATIONS FOR MOMENT LOADING

SLSO= 2.3042D 04 SLSI= -2.3042D 04 SCSO= 1.9763D 04 SCSI= 5.9379D 03  
 SLLO= 2.3411D 04 SLLI= -2.3411D 04 SCLO= 7.0234D 03 SCLI= -7.0234D 03  
 STH= 1.1173D 04 STF= -1.8482D 04 SRH= 8.4441D 03 SRF= -6.6480D 03  
 ZG= -1.0421D-02 ZC= -2.4446D-02 QFHG= 1.4026D-02 Y0= 1.2322D-02 Y1= 1.0058D-18 THETA= -4.0579D-03

CALCULATIONS FOR PRESSURE LOADING

SLSO= 1.4194D 04 SLSI= 2.5863D 03 SCSO= 1.4398D 04 SCSI= 1.0915D 04  
 SLLO= 1.8645D 03 SLLI= 5.7979D 03 SCLO= 5.5935D 02 SCLI= 1.7394D 03  
 STH= 9.3311D 03 STF= -1.1002D 03 SRH= -2.2932D 03 SRF= 2.7038D 02  
 ZG= -4.5114D-03 ZC= -1.0302D-02 QFHG= 5.7904D-03 Y0= 9.7224D-03 Y1= 6.0715D-18 THETA= -1.8088D-03

CALCULATIONS FOR TEMPERATURE LOADING

SLSO= 1.2228D 00 SLSI= -1.2228D 00 SCSO= 1.0649D-01 SCSI= -6.2722D-01  
 SLLO= -1.3977D-01 SLLI= 1.3977D-01 SCLO= -1.8419D 00 SCLI= -1.7581D 00  
 STH= 1.1087D 00 STF= -6.1330D-01 SRH= -2.7247D-01 SRF= 1.5072D-01  
 ZG= -7.4476D-07 ZC= -1.7007D-06 QFHG= 9.5590D-07 Y0= -2.4965D-07 Y1= -1.7259D-06 THETA= -2.9860D-07

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 7.7814D 06

SLSO= 3.3385D 04 SLSI= -1.6605D 04 SCSO= 3.0857D 04 SCSI= 1.5860D 04  
 SLLO= 2.1362D 04 SLLI= -1.3700D 04 SCLO= 6.4068D 03 SCLI= -4.1117D 03  
 STH= 1.8638D 04 STF= -1.6493D 04 SRH= 4.7391D 03 SRF= -5.2661D 03  
 ZG= -1.3191D-02 ZC= -3.0663D-02 QFHG= 1.7472D-02 Y0= 1.9984D-02 Y1= -1.7259D-06 THETA= -5.1886D-03

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To avoid leakage,\* the residual bolt load must not be less than the critical value  $W_c$ , which may be obtained from simple equilibrium considerations; thus,

$$W_c = \frac{\pi}{4} G_0^2 p, \quad (\text{A.2})$$

where

$W_c$  = "critical" bolt load,  
 $G_0$  = outside diameter of gasket (65 in. in this example), and  
 $p$  = pressure (720 psi in this example).

In this example, the value of  $W_c$  is

$$W_c = \frac{\pi}{4} \times 65^2 \times 720 = 2.389 \times 10^6 \text{ lb}.$$

Because  $W_c$  is significantly greater than  $W_2 = 1.0948 \times 10^6$  lb, the results for example 3(a) indicate that the joint will leak at the rated pressure with the initial bolt stress of 20,033 psi. The results illustrate an aspect of ASME-designed flanges that is well known to many users; that is, the joints often cannot be made leaktight (especially in order to pass the hydrostatic test) by applying an initial bolt stress equal to the Code-allowable bolt stress.

The output data for example 3(b) are shown in Table A.6. Example 3(b) is the same as 3(a), except that the initial bolt stress has been increased from 20,033 psi to 44,300 psi ( $W_1$  input under XMOA increased to  $2.0661 \times 10^7$ ); the initial moment has been correspondingly increased; and the pressure has been increased from 720 psi to 1080 psi, the latter being the hydrostatic-test pressure of 1.5 times the cold rating pressure. It can be seen in Table A.6 (on the second page, Table A.6b) that the

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\* Leakage is defined as the gross type of leakage that occurs when the load on the gasket is reduced to zero. Slow, diffusion-type leakage may occur at lower pressures.

Table A.6a. Output data for example 3(b), blind flange bolted to a tapered-hub flange, with initial bolt stress = 44,300 psi

FLANGE O.D.,A	FLANGE I.D.,B	FLANGE THICK.,T	PIPE WALL,G0	HUB AT BASE,G1	HUB LENGTH,H	BOLT CIRCLE,C	PRESSURE, P		
73.93750	57.53140	7.90440	1.23430	2.70300	5.43620	69.43750	1080.000		
BOLT LOAD	COEFF. OF THERMAL EXP.	DELTA	MOD. OF ELASTICITY	MEAN DIAMETER	GASKET DIA	ITYPE	IBOND	ICODE	MATE
6.066D 06	6.000D-06	1.000D-02	3.000D 07	6.263D 01		3	0	0	5
FLANGE O.D.,A	FLANGE I.D.,B	FLANGE THICK.,T	PIPE WALL,G0	HUB AT BASE,G1	HUB LENGTH,H	BOLT CIRCLE,C	PRESSURE, P		
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	1080.000		
MOMENT LOAD	COEFF. OF THERMAL EXP.	DELTA	MOD. OF ELASTICITY	MEAN DIAMETER	GASKET DIA	ITYPE	IBOND	ICODE	MATE
2.066D 07	6.000D-06	1.000D-02	3.000D 07	6.263D 01		1	0	0	6
B SIZE	YB	EB	TB	XGO	XGI	AB			
2.2500D 00	3.0000D 07	6.0000D-06	0.0	6.5000D 01	6.0250D 01	1.3692D 02			
VO	YG	EG	TG	FACE	PBE				
6.2500D-02	3.0000D 06	6.0000D-06	0.0	0.0	0.0				
W1	TF	TFP	YF2	YFP2	YB2	YG2			
6.0656D 06	0.0	0.0	3.0000D 07	3.0000D 07	3.0000D 07	3.0000D 06			

FLANGE JCINT BOLT LOAD CHANGE DUE TO APPLIED LOADS, BLIND IC INTEGER PAIR

FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)

QFHG= 9.4994D-10 QPHG= 6.5350D-06 QTHG= -1.0000D 00 XB = -1.0000D 00 GO= -1.0000D 00 TH = 7.9044D 00  
 YM = 3.0000D 07 YF2 = 3.0000D 07 EF = 6.0000D-06

FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)

QPHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00  
 YM = 3.0000D 07 YF2 = 3.0000D 07 EF = 6.0000D-06

BOLTING

BOLT LENGTH= 1.6154D 01 BOLT AREA= 1.3692D 02 BOLT CIRCLE= 6.9438D 01  
 YB = 3.0000D 07 YB2 = 3.0000D 07 EB = 6.0000D-06

GASKET

VO = 6.2500D-02 XGO = 6.5000D 01 XGI = 6.0250D 01  
 YG = 3.0000D 06 YG2 = 3.0000D 06 EG = 6.0000D-06

Table A.6b (continued)

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LOADINGS

INITIAL BOLT LOAD= 6.0656D 06 BOLT TEMP.= 0.0 FLANGE ONE TEMP.= 0.0 FLANGE TWO TEMP.= 0.0  
GASKET TEMP.= 0.0 DELTA= 1.0000D-02 DELTAP= 1.0000D-02 PRESSURE= 1.0800D 03

RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS

AXIAL THERMAL,W2A= 6.0656D 06 MOMENT SHIFT,W2E= 5.2952D 06

TOTAL PRESSURE,W2C= 3.5934D 06 DELTA THERMAL,W2D= 6.0655D 06

COMBINED,W2= 3.5933D 06

W1-W2A= 0.0 W1-W2B= 7.7038D 05 W1-W2C= 2.4722D 06 W1-W2D= 1.0333D 02 W1-W2= 2.4723D 06  
W2A/W1= 1.0000D 00 W2B/W1= 8.7299D-01 W2C/W1= 5.9242D-01 W2D/W1= 9.9998D-01 W2/W1= 5.9240D-01

INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE LOADS.

M1= 2.0661D 07 M2A= 2.0661D 07 M2B= 2.4115D 07 M2C= 1.8319D 07 M2D= 2.0661D 07 M2= 1.8318D 07  
M2BP= 7.0966D 07 M2CP= 6.5169D 07 M2P= 6.5168D 07

Table A.6c (continued)

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BLIND FLANGE  
CALCULATIONS FOR BOLT LOADING

SORT= 8.8924D 03    SGR= 8.8924D 03    SGT= 8.8924D 03    SCR= -3.5727D 02    SCT= 5.6971D 03    SAT= 5.3399D 03  
ZC= -5.7620D-03

CALCULATIONS FOR PRESSURE LOADING

SORT= 1.9716D 04    SGR= -1.2572D 03    SGT= 7.6405D 03    SCR= -4.2709D 02    SCT= 6.8104D 03    SAT= 6.3833D 03  
ZC= -7.0578D-03

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 3.5933D 06

SORT= 2.4984D 04    SGR= 4.0107D 03    SGT= 1.2908D 04    SCR= -6.3873D 02    SCT= 1.0185D 04    SAT= 9.5467D 03  
ZC= -1.0471D-02

Table A.6d (continued)

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TAPERED HUB FLANGE

CALCULATIONS FOR MOMENT LOADING

SLSO= 4.0624D 04 SLSI= -4.0624D 04 SCSO= 3.4843D 04 SCSI= 1.0469D 04  
 SLLO= 4.1275D 04 SLLI= -4.1275D 04 SCLO= 1.2382D 04 SCLI= -1.2382D 04  
 STH= 1.9699D 04 STF= -3.2584D 04 SRH= 1.4887D 04 SRF= -1.1721D 04  
 ZG= -1.8372D-02 ZC= -4.3100D-02 QPHG= 2.4728D-02 Y0= 2.1724D-02 Y1= 2.1553D-19 THETA= -7.1542D-03

CALCULATIONS FOR PRESSURE LOADING

SLSO= 2.1290D 04 SLSI= 3.8794D 03 SCSO= 2.1596D 04 SCSI= 1.6373D 04  
 SLLO= 2.7967D 03 SLLI= 8.6968D 03 SCLO= 8.3902D 02 SCLI= 2.6090D 03  
 STH= 1.3997D 04 STF= -1.6503D 03 SRH= -3.4397D 03 SRF= 4.0556D 02  
 ZG= -6.7671D-03 ZC= -1.5453D-02 QPHG= 8.6856D-03 Y0= 1.4584D-02 Y1= 6.0715D-18 THETA= -2.7132D-03

CALCULATIONS FOR TEMPERATURE LOADING

SLSO= 1.2228D 00 SLSI= -1.2228D 00 SCSO= 1.0649D-01 SCSI= -6.2722D-01  
 SLLO= -1.3977D-01 SLLI= 1.3977D-01 SCLO= -1.8419D 00 SCLI= -1.7581D 00  
 STH= 1.1087D 00 STF= -6.1330D-01 SRH= -2.7247D-01 SRF= 1.5072D-01  
 ZG= -7.4476D-07 ZC= -1.7007D-06 QPHG= 9.5590D-07 Y0= -2.4965D-07 Y1= -1.7259D-06 THETA= -2.9860D-07

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 1.8318D 07

SLSO= 5.7309D 04 SLSI= -3.2139D 04 SCSO= 5.2489D 04 SCSI= 2.5654D 04  
 SLLO= 3.9392D 04 SLLI= -2.7898D 04 SCLO= 1.1816D 04 SCLI= -8.3712D 03  
 STH= 3.1463D 04 STF= -3.0541D 04 SRH= 9.7592D 03 SRF= -9.9860D 03  
 ZG= -2.3057D-02 ZC= -5.3667D-02 QPHG= 3.0610D-02 Y0= 3.3844D-02 Y1= -1.7259D-06 THETA= -9.0565D-03

---

residual bolt load after application of a pressure of 1080 psi is  $W_2 = 3.5933 \times 10^6$  lb. The value of the critical bolt load to prevent gross leakage is

$$W_c = \frac{\pi}{4} \times 65^2 \times 1080 = 3.584 \times 10^6 \text{ lb} .$$

With an initial bolt stress of 44,300 psi, the residual bolt load is now greater than  $W_c$ . Accordingly, the results of example 3(b) indicate that an initial bolt stress of 44,300 psi is sufficient for the joint to pass a hydrostatic test to 1080 psi, albeit with no margin of safety. As the reader may have surmised, the initial bolt stress of 44,300 psi was preselected for example 3(b) to achieve this final result. It is pertinent to note that, because of the linear nature of the calculations, it is not necessary to iterate in order to find a value for the initial bolt stress that would make  $W_2 = W_c$ . Note that  $(W_1 - W_2) = 1.648 \times 10^6$  in example 3(a) and that  $(W_1 - W_2)$  varies linearly with pressure. To find the required value of  $W_1$  to make  $W_2 = W_c$  at an arbitrary pressure  $p$ , we need only solve the equation:

$$W_1 = \frac{\pi}{4} G_0^2 p + \frac{P}{720} (1.648 \times 10^6) . \quad (\text{A.3})$$

For  $p = 1080$ , Eq. (A.3) gives  $W_1 = 6.056 \times 10^6$ , and the corresponding initial bolt stress is  $W_1/A_b = 6.056 \times 10^6/136.92 = 44,228$  psi, which was rounded off to 44,300 psi for Example 3(b).

#### Blind Flange Stresses, Example 3(a)

Example 3(a) was run with an initial bolt stress of 20,033 psi to permit direct comparison of the blind-flange stresses with the stresses calculated in example 2, where the controlling bolt stress was  $S_{B1} = 20,033$  psi.

Stresses for the blind flange are shown in Table A.5c. The maximum stress due to initial bolt loading only is  $S_{ORT} = 4021.3$  psi. A comparable stress from the Code calculation (Table A.3), is  $S_{GS} = 3376.3$  psi.

This also represents a stress at the center of the blind flange due to bolt loading only. The maximum stress due to pressure loading only of the blind flange (Table A.5c) is SORT = 13,144 psi. A Comparable stress from the Code calculation (Table A.3) is SP = 14,121 psi.

The maximum stress due to combined bolt loading and pressure loading (Table A.5c) is SORT = 14,749 psi. Note that this combined stress is not the sum of the stress due to the initial bolt load and the stress due to pressure. Rather, the program recognizes that the pressure changes the bolt load – in this example, from  $2.743 \times 10^6$  lb down to  $1.0948 \times 10^6$  (Table A.5b). Stresses for combined loadings are related to stresses for initial bolt loading only and pressure only by the equation

$$\sigma_c = \sigma_b \cdot \frac{W2}{W1} + \sigma_p , \quad (A.4)$$

where  $\sigma_c$  = combined stress,  $\sigma_b$  = stress due to initial bolt load only, W2 = bolt load at pressure, W1 = initial bolt load, and  $\sigma_p$  = stress due to pressure only.

The Code equation for combined stresses [i.e.,  $S = (d/t)^2(0.3p + 1.78Wh_G)$  from paragraph UG-34 and Figs. UG-34 (j) and (k)] can be derived by assuming that the blind flange is a flat circular plate of outside diameter equal to the effective gasket diameter d. The metal outside the diameter d is ignored. The plate is simply supported along d and loaded by edge moment  $Wh_G$  and pressure p.  $Wh_G$  is either the operating moment or the gasket-seating moment, as obtained in Appendix II of the Code. The method used in this report is theoretically more accurate than that used in the Code, and the relatively good agreement between stresses in Table A.5c and those in Table A.3 is, in part, coincidental. Large differences can exist, particularly when there is a significant amount of flange material outside the gasket diameter d.

#### Tapered-Hub Flange Stresses, Example 3(a)

Example 3(a) was run with an initial moment of  $1.1719 \times 10^7$  in.-lb to permit direct comparison with the stresses given for example 1 in

Table A.2 under the heading "ASME FLANGE STRESSES AT OPERATING MOMENT, MOP." In example 1, the value for MOP was determined to be  $1.1719 \times 10^7$  in.-lb. To be consistent with the Code calculations in this example [3(a)], we chose  $IBOND = 0$ .

Calculated stresses for the tapered-hub flange are shown in Table A.5d. The Code method covers only moment loading. The stresses in Table A.5d for initial moment loading only are the same as those in Table A.2 for operating moment, MOP:

<u>Stress values from Table A.5d</u>	<u>Stress values from Table A.2</u>
SLLO = 23,411 psi	SH = 23,412 psi
STH = 11,173 psi	ST = 11,174 psi
SRH = 8,444 psi	SR = 8,444 psi

The Code method gives stresses at the small end of the hub if the Code factor  $f$  is greater than 1.0; otherwise, it gives stresses for the large end of the hub. The Code method calculates radial and tangential stresses on the hub side of the flange only. Usually these are higher than the corresponding stresses on the face side of the flange, but in this example,  $STH = 11,173$  psi is less than  $STF = -18,482$  psi in absolute magnitude. The Code method does not give circumferential stresses in the hub.

Stresses for pressure loading only, temperature loading only, and combined loadings are shown as the 2nd, 3rd, and 4th groups of stresses in Table A.5d. The small values under the heading "CALCULATIONS FOR TEMPERATURE LOADINGS" come from using  $DELTA = 0.01$ , since  $DELTA = 0$  is not a permissible input value.

Combined stresses are not the sum of the stresses due to the three individual loads. Rather, the program recognizes that pressure and temperature change the moment from  $M1 = 9.3433 \times 10^6$  in.-lb to  $M2 = 7.7814 \times 10^6$  in.-lb in this example\* (Table A.5b). The maximum stress

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\* It should be noted that  $M1$  is not the same as the input moment XMOA. The program will accept any value for calculating stresses but, for calculating bolt load changes, it assumes that the moment is equal to  $W(C-G)/2$ .

under combined loads (in this example, residual moment and pressure) is  $SLSO = 33,385$  psi. Under initial moment only, the maximum stress is  $SLLO = 23,411$  psi.

#### Blind and Tapered-Hub Flange Stresses, Example 3(b)

Stresses are shown in Table A.6c and A.6d for blind and tapered-hub flanges, respectively. It can be seen that maximum stresses are quite high for the realistic initial bolt stress of 44,300 psi needed to pass the hydrostatic test pressure of 1080 psi [i.e.,  $SORT = 24,984$  psi for the blind flange (Table A.6c) and  $SLSO = 57,309$  psi for the tapered-hub flange (Table A.6d)]. Comments on the significance of these high calculated stresses are included later in the discussion of examples 4a and 4b.

#### Displacements

Tables A.5 and A.6 include, along with stresses, the displacements  $ZC$  for the blind flange or  $ZG$ ,  $ZC$ ,  $QFHG$ ,  $Y0$ ,  $Y1$ , and  $THETA$  for the tapered-hub flange. One potential application for these displacements is discussed later in connection with examples 4(a) and 4(b).

## IDENTICAL PAIR OF TAPERED-HUB FLANGES, EXAMPLES 4(a) AND 4(b)

Input Data

The input data for Examples 4(a) and 4(b) are shown in Table A.7. The initial bolt stress of 46,100 psi and corresponding  $W_1 = 6.312 \times 10^6$  lb were selected by a preliminary calculation so that  $W_2$  would equal  $W_c$  at the hydrostatic-test pressure of 1080 psi. The value of  $W_1 = 6.312 \times 10^6$  lb leads to initial moment  $XMOA = W_1(C-G)/2 = 2.1500 \times 10^7$  in.-lb. Example 4(a) is for hydrostatic test conditions at atmospheric temperature. Example 4(b) is for steady-state operating conditions at the rated pressure of 300 psi and corresponding API-605 temperature of 850°F.

The modulus of elasticity of the flange, bolt, and gasket materials was assumed to be  $2.25 \times 10^7$  psi at 800°F, as compared with  $3.0 \times 10^7$  at atmospheric temperature. It is assumed that at steady-state operating conditions there is an external bending moment such that the axial stress in the attached pipe is 7500 psi. This axial stress gives 617 psi as the input value for PBE for example 4(b), as shown below:

$$PBE = 4 S_b g_0 / D_o = 4 \times 7500 \times 1.2343 / 60 = 617 \text{ psi} .$$

Output DataResidual Bolt Loads

The output data for example 4(a) are shown in Table A.8. The output data starts with a printout of all input data. The parameters involved in the bolt-load-change calculations are then printed, followed by residual bolt loads and moments (Table A.8b).

The residual bolt load is given by  $W_2 = 3.585 \times 10^6$  lb. The critical bolt load, derived from Eq. (A.2), is  $W_c = \pi G_0^2 p / 4 = 3.584 \times 10^6$  lb. Accordingly, the results of example 4(a) indicate that an initial bolt stress of 46,100 psi is sufficient for the joint to pass a hydrostatic test to 1080 psi, albeit with no margin of safety.

Table A.7. Input data for tapered-hub-to-tapered-hub flanged joint, examples<sup>a</sup> 4a and 4b

Card No.	Variables and numerical values								Read format
1	ITYPE	IBOND	ICODE	MATE					
	1	0	0	2					4I5
2	A	B	t	g <sub>0</sub>	g <sub>1</sub>	h	C	P	
	73.9375	57.5314	5.9375	1.2343	2.7030	5.4362	69.4375	1080. (300.)	8E10.5
3	XMOA	EF	DELTA <sup>b</sup>	YM	G				
	2.1500D+7	6. D-6	.01	3. D+7	62.625				5E10.5
4	BSIZE	YB	EB	TB	XG0	XGI	AB		
	2.25	3. D+7	6. D-6	0	65.	60.25	136.92		7E10.5
5	VO	YG	EG	TG	FACE	PBE			
	.0625	3. D+6	6. D-6	0	0	0			6E10.5
									(617.)
6	W1	TF	TFP	YF2	YFP2	YB2	YG2		
	6.3120D+6	0	0	3. D+7 (2.25D+7)	3. D+7 (2.25D+7)	3. D+7 (2.25D+7)	3. D+6 (2.25D+6)		7E10.5

<sup>a</sup>Values in parentheses are for example 4b.

<sup>b</sup>Since DELTA cannot be entered as zero, 0.01 was used as a satisfactorily small value.

Table A.8a. Output data for example 4(a), identical pair of tapered-hub flanges, with initial bolt stress of 46,100 psi

FLANGE O.D.,A	FLANGE I.D.,B	FLANGE THICK.,T	PIPE WALL,GO	HUB AT BASE,G1	HUB LENGTH,H	BOLT CIRCLE,C	PRESSURE,P																																																														
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	1080.000																																																														
MOMENT	COEFF. OF THERMAL EXP.	DELTA	MOD. OF ELASTICITY	MEAN DIAMETER	GASKET	ITYPE	IBOND	ICODE	MATE																																																												
2.150D	07	6.000D-06	1.000D-02	3.000D	07	6.263D	01	1	0	0	2																																																										
<table border="0"> <tr> <td>B SIZE</td> <td>YB</td> <td>EB</td> <td>TB</td> <td>XGO</td> <td>XGI</td> <td>AB</td> <td colspan="3"></td> </tr> <tr> <td>2.2500D 00</td> <td>3.0000D 07</td> <td>6.0000D-06</td> <td>0.0</td> <td>6.5000D 01</td> <td>6.0250D 01</td> <td>1.3692D 02</td> <td colspan="3"></td> </tr> <tr> <td>VO</td> <td>YG</td> <td>EG</td> <td>TG</td> <td>FACE</td> <td>PBE</td> <td colspan="4"></td> </tr> <tr> <td>6.2500D-02</td> <td>3.0000D 06</td> <td>6.0000D-06</td> <td>0.0</td> <td>0.0</td> <td>0.0</td> <td colspan="4"></td> </tr> <tr> <td>W1</td> <td>TF</td> <td>TFP</td> <td>YF2</td> <td>YFP2</td> <td>YB2</td> <td>YG2</td> <td colspan="3"></td> </tr> <tr> <td>6.3120D 06</td> <td>0.0</td> <td>0.0</td> <td>3.0000D 07</td> <td>3.0000D 07</td> <td>3.0000D 07</td> <td>3.0000D 06</td> <td colspan="3"></td> </tr> </table>										B SIZE	YB	EB	TB	XGO	XGI	AB				2.2500D 00	3.0000D 07	6.0000D-06	0.0	6.5000D 01	6.0250D 01	1.3692D 02				VO	YG	EG	TG	FACE	PBE					6.2500D-02	3.0000D 06	6.0000D-06	0.0	0.0	0.0					W1	TF	TFP	YF2	YFP2	YB2	YG2				6.3120D 06	0.0	0.0	3.0000D 07	3.0000D 07	3.0000D 07	3.0000D 06			
B SIZE	YB	EB	TB	XGO	XGI	AB																																																															
2.2500D 00	3.0000D 07	6.0000D-06	0.0	6.5000D 01	6.0250D 01	1.3692D 02																																																															
VO	YG	EG	TG	FACE	PBE																																																																
6.2500D-02	3.0000D 06	6.0000D-06	0.0	0.0	0.0																																																																
W1	TF	TFP	YF2	YFP2	YB2	YG2																																																															
6.3120D 06	0.0	0.0	3.0000D 07	3.0000D 07	3.0000D 07	3.0000D 06																																																															
FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOADS, IDENTICAL PAIR																																																																					
FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)																																																																					
QPHG=	1.1968D-09	QPHG=	8.0422D-06	QTHG=	9.5590D-05	XB =	5.7531D 01	GO=	1.2343D 00	TH =	5.9375D 00																																																										
YM =	3.0000D 07	YF2 =	3.0000D 07	EF =	6.0000D-06																																																																
FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)																																																																					
QPHG=	1.1968D-09	QPHG=	8.0422D-06	QTHG=	9.5590D-05	XB =	5.7531D 01	GO=	1.2343D 00	TH =	5.9375D 00																																																										
YM =	3.0000D 07	YF2 =	3.0000D 07	EF =	6.0000D-06																																																																
BOLTING																																																																					
BOLT LENGTH=	1.4188D 01	BOLT AREA=	1.3692D 02	BOLT CIRCLE=	6.9438D 01																																																																
YB =	3.0000D 07	YB2 =	3.0000D 07	EB =	6.0000D-06																																																																
GASKET																																																																					
VO =	6.2500D-02	XGO =	6.5000D 01	XGI =	6.0250D 01																																																																
YG =	3.0000D 06	YG2 =	3.0000D 06	EG =	6.0000D-06																																																																

Table A.8b (continued)

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LOADINGS

INITIAL BOLT LOAD= 6.3120D 06 BOLT TEMP.= 0.0 FLANGE ONE TEMP.= 0.0 FLANGE TWO TEMP.= 0.0  
GASKET TEMP.= 0.0 DELTA= 1.0000D-02 DELTAP= 1.0000D-02 PRESSURE= 1.0800D 03

RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS

AXIAL THERMAL,W2A= 6.3120D 06 MOMENT SHIFT,W2E= 5.0760D 06

TOTAL PRESSURE,W2C= 3.5852D 06 DELTA THERMAL,W2D= 6.3118D 06

COMBINED,W2= 3.5850D 06

W1-W2A= 0.0 W1-W2B= 1.2360D 06 W1-W2C= 2.7268D 06 W1-W2D= 1.6408D 02 W1-W2= 2.7270D 06  
W2A/W1= 1.0000D 00 W2B/W1= 8.0418D-01 W2C/W1= 5.6799D-01 W2D/W1= 9.9997D-01 W2/W1= 5.6796D-01

INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE LOADS.

M1= 2.1500D 07 M2A= 2.1500D 07 M2B= 2.3369D 07 M2C= 1.8291D 07 M2D= 2.1500D 07 M2= 1.8290D 07  
M2BP= 2.3369D 07 M2CP= 1.8291D 07 M2P= 1.8290D 07

Table A.8c (continued)

TAPERED HUB FLANGE

CALCULATIONS FOR MOMENT LOADING

SLSO= 4.2273D 04 SLSI= -4.2273D 04 SCSO= 3.6258D 04 SCSI= 1.0894D 04  
 SLLO= 4.2951D 04 SLLI= -4.2951D 04 SCLO= 1.2885D 04 SCLI= -1.2885D 04  
 STH= 2.0499D 04 STP= -3.3907D 04 SRH= 1.5492D 04 SRF= -1.2197D 04  
 ZG= -1.9118D-02 ZC= -4.4850D-02 QFHG= 2.5732D-02 Y0= 2.2606D-02 Y1= 1.6524D-18 THETA= -7.4448D-03

CALCULATIONS FOR PRESSURE LOADING

SLSO= 2.1290D 04 SLSI= 3.8794D 03 SCSO= 2.1596D 04 SCSI= 1.6373D 04  
 SLLO= 2.7967D 03 SLLI= 8.6968D 03 SCLO= 8.3902D 02 SCLI= 2.6090D 03  
 STH= 1.3997D 04 STP= -1.6503D 03 SRH= -3.4397D 03 SRF= 4.0556D 02  
 ZG= -6.7671D-03 ZC= -1.5453D-02 QFHG= 8.6856D-03 Y0= 1.4584D-02 Y1= 6.0715D-18 THETA= -2.7132D-03

CALCULATIONS FOR TEMPERATURE LOADING

SLSO= 1.2228D 00 SLSI= -1.2228D 00 SCSO= 1.0649D-01 SCSI= -6.2722D-01  
 SLLO= -1.3977D-01 SLLI= 1.3977D-01 SCLO= -1.8419D 00 SCLI= -1.7581D 00  
 STH= 1.1087D 00 STP= -6.1330D-01 SRH= -2.7247D-01 SRF= 1.5072D-01  
 ZG= -7.4476D-07 ZC= -1.7007D-06 QFHG= 9.5590D-07 Y0= -2.4965D-07 Y1= -1.7259D-06 THETA= -2.9860D-07

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 1.8290D 07

SLSO= 5.7253D 04 SLSI= -3.2083D 04 SCSO= 5.2441D 04 SCSI= 2.5640D 04  
 SLLO= 3.9335D 04 SLLI= -2.7841D 04 SCLO= 1.1799D 04 SCLI= -8.3541D 03  
 STH= 3.1436D 04 STP= -3.0496D 04 SRH= 9.7386D 03 SRF= -9.9698D 03  
 ZG= -2.3032D-02 ZC= -5.3608D-02 QFHG= 3.0576D-02 Y0= 3.3814D-02 Y1= -1.7259D-06 THETA= -9.0466D-03

The output data for example 4(b) are shown in Table A.9, which is identical in format to Table A.8 for example 4(a). The residual bolt load for example 4(b) is given by  $W_2 = 3.2718 \times 10^6$  lb. The pressure is lower in example 4(b) than in 4(a), but there is a modulus-of-elasticity decrease which, by itself, makes  $W_2 = W_1 \times 2.25 \times 10^7 / (3 \times 10^7)$  and makes the effect of the equivalent pressure correspond to the external moment PBE. We can check to see if the residual bolt load is sufficient to prevent leakage by an extension of the concept of the initial bolt load  $W_c$ , which was discussed in the previous section. We made the conservative assumption that the maximum tensile stress due to the external bending moment (which exists only at one point on the pipe circumference) acts around the complete circumference of the pipe. The value of  $W_c$ , the critical bolt load to prevent gross leakage, is then the sum of Eq. (A.2) and the axial load due to the bending moment; thus

$$W_c = \frac{\pi}{4} G_0^2 p + A_p S_b , \quad (\text{A.5})$$

where

$$A_p = \pi(B + g_0) g_0 = \text{cross-sectional area of attached pipe, and}$$

$$S_b = \text{axial stress in attached pipe due to an external moment.}$$

For example 4(b), Eq. (A.5) gives:

$$\begin{aligned} W_c &= \left( \frac{\pi}{4} \times 65^2 \times 300 \right) + (\pi \times 58.7657 \times 1.2343 \times 7500) \\ &= 2.7045 \times 10^6 \text{ lb} . \end{aligned}$$

Because  $W_2 = 3.2718 \times 10^6$  lb is greater than  $W_c = 2.7045 \times 10^6$  lb, the results indicate that the flanged joint with an initial bolt stress of 46,100 psi can carry, at least for a short time at 850°F, an external moment giving both an axial bending stress of 7500 psi in the attached pipe of 1.2343-in. wall thickness and an internal pressure of 300 psi.

At 850°F, the carbon-steel flanges and bolts would be expected to undergo significant relaxation due to creep in the flanges and bolts,

Table A.9a. Output data for example 4(b), identical pair of tapered-hub flanges, steady-state operation at 300 psi and 850°F

FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, G0	HUB AT BASE, G1	HUB LENGTH, H	BOLT CIRCLE, C	PRESSURE, P	
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	300.000	
MOMENT	COEFF. OF THERMAL EXP.	DELTA	MOD. OF ELASTICITY	MEAN GASKET DIAMETER	ITYPE	IBOND	ICODE	MATE
2.150D 07	6.000D-06	1.000D-02	3.000D 07	6.263D 01	1	0	0	2
B SIZE	YB	EB	TB	XGO	XGI	AB		
2.2500D 00	3.0000D 07	6.0000D-06	0.0	6.5000D 01	6.0250D 01	1.3692D 02		
VO	YG	EG	TG	FACE	PBE			
6.2500D-02	3.0000D 06	6.0000D-06	0.0	0.0	6.1700D 02			
W1	TF	TFP	YF2	YFP2	YB2	YG2		
6.3120D 06	0.0	0.0	2.2500D 07	2.2500D 07	2.2500D 07	2.2500D 07		

FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOADS, IDENTICAL PAIR

FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)

QPHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00  
YM = 3.0000D 07 YF2 = 2.2500D 07 EF = 6.0000D-06

FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)

QPHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00  
YM = 3.0000D 07 YF2 = 2.2500D 07 EF = 6.0000D-06

BOLTING

BOLT LENGTH= 1.4188D 01 BOLT AREA= 1.3692D 02 BOLT CIRCLE= 6.9438D 01  
YB = 3.0000D 07 YB2 = 2.2500D 07 EB = 6.0000D-06

GASKET

VO = 6.2500D-02 XGO = 6.5000D 01 XGI = 6.0250D 01  
YG = 3.0000D 06 YG2 = 2.2500D 07 EG = 6.0000D-06

Table A.9b (continued)

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LOADINGS

INITIAL BOLT LOAD= 6.3120D 06 BOLT TEMP.= 0.0 FLANGE ONE TEMP.= 0.0 FLANGE TWO TEMP.= 0.0  
 GASKET TEMP.= 0.0 DELTA= 1.0000D-02 DELTAP= 1.0000D-02 PRESSURE= 3.0000D 02

RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS

AXIAL THERMAL,W2A= 6.3120D 06 MOMENT SHIFT,W2B= 5.2625D 06  
 TOTAL PRESSURE,W2C= 4.8484D 06 DELTA THERMAL,W2D= 6.3118D 06  
 COMBINED,W2= 3.2718D 06

W1-W2A= 0.0 W1-W2B= 1.0495D 06 W1-W2C= 1.4636D 06 W1-W2D= 1.6408D 02 W1-W2= 3.0402D 06  
 W2A/W1= 1.0000D 00 W2B/W1= 8.3374D-01 W2C/W1= 7.6813D-01 W2D/W1= 9.9997D-01 W2/W1= 5.1835D-01

INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE LOADS.

M1= 2.1500D 07 M2A= 2.1500D 07 M2B= 1.9614D 07 M2C= 1.8203D 07 M2D= 2.1500D 07 M2= 1.2833D 07  
 M2BP= 1.9614D 07 M2CP= 1.8203D 07 M2P= 1.2833D 07

Table A.9c (continued)

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TAPERED HUB FLANGE

CALCULATIONS FOR MOMENT LOADING

SLSO= 4.2273D 04 SLSI= -4.2273D 04 SCSO= 3.6258D 04 SCSI= 1.0894D 04  
 SLLO= 4.2951D 04 SLLI= -4.2951D 04 SCLO= 1.2885D 04 SCLI= -1.2885D 04  
 STH= 2.0499D 04 STF= -3.3907D 04 SRH= 1.5492D 04 SRF= -1.2197D 04  
 ZG= -1.9118D-02 ZC= -4.4850D-02 QPHG= 2.5732D-02 Y0= 2.2606D-02 Y1= 1.6524D-18 THETA= -7.4448D-03

CALCULATIONS FOR PRESSURE LOADING

SLSO= 5.9140D 03 SLSI= 1.0776D 03 SCSO= 5.9990D 03 SCSI= 4.5481D 03  
 SLLO= 7.7687D 02 SLLI= 2.4158D 03 SCLO= 2.3306D 02 SCLI= 7.2473D 02  
 STH= 3.8880D 03 STF= -4.5841D 02 SRH= -9.5549D 02 SRF= 1.1266D 02  
 ZG= -1.8798D-03 ZC= -4.2924D-03 QPHG= 2.4127D-03 Y0= 4.0510D-03 Y1= 8.6736D-19 THETA= -7.5365D-04

CALCULATIONS FOR TEMPERATURE LOADING

SLSO= 1.2228D 00 SLSI= -1.2228D 00 SCSO= 1.0649D-01 SCSI= -6.2722D-01  
 SLLO= -1.3977D-01 SLLI= 1.3977D-01 SCLO= -1.8419D 00 SCLI= -1.7581D 00  
 STH= 1.1087D 00 STF= -6.1330D-01 SRH= -2.7247D-01 SRF= 1.5072D-01  
 ZG= -7.4476D-07 ZC= -1.7007D-06 QPHG= 9.5590D-07 Y0= -2.4965D-07 Y1= -1.7259D-06 THETA= -2.9860D-07

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 1.2833D 07

SLSO= 3.1147D 04 SLSI= -2.4156D 04 SCSO= 2.7641D 04 SCSI= 1.1050D 04  
 SLLO= 2.6413D 04 SLLI= -2.3221D 04 SCLO= 7.9222D 03 SCLI= -6.9680D 03  
 STH= 1.6125D 04 STF= -2.0698D 04 SRH= 8.2910D 03 SRF= -7.1671D 03  
 ZG= -1.3292D-02 ZC= -3.1064D-02 QPHG= 1.7772D-02 Y0= 1.7544D-02 Y1= -1.7259D-06 THETA= -5.1976D-03

---

particularly with the high bolt stresses and flange stresses involved in example 4(b). For long-term service (many years) at 850°F, one might expect the flanges and/or bolts to creep so that a residual bolt stress of around 20,000 psi would exist, at which time  $W_2 = 2000 \times 136.92 = 2.7384 \times 10^6$  lb. Because this is larger than  $W_c = 2.7045 \times 10^6$  lb obtained from Eq. (A.5), indications are that the flanged joint could still carry the external moment and pressure, albeit with almost no margin of safety.

It should be noted that, if bolts relax in high-temperature service, then the bolt load does not return to its initial value upon returning to initial conditions. The permanent loss in bolt load would be  $W_2 - S_{br} A_b$ , where  $S_{br}$  = relaxed bolt stress, assumed here to be 20,000 psi. The permanent loss in bolt load, in this example, is  $3.2718 \times 10^6 - 20,000 \times 136.92 = 533,400$  lb. The load is theoretically not sufficient to pass a hydrotest of 1080 psi, but it is extremely unlikely such a hydrotest would be required for a system operating at 300 psi and 850°F.

#### Flange Stresses

Tables A.8c and A.9c show the flange stresses for examples 4(a) and 4(b), respectively. The maximum calculated stress occurs in example 4(a) where SLSO = 57,253 psi for combined loadings. Note that this is not the sum of the stresses due to initial moment loading only plus pressure loading only (first two groups of stresses), but rather it is the stress due to the moment as changed by pressure,  $M_2 = M_{2P} = 1.829 \times 10^7$  in.-lb, plus the stress due to pressure only.

The question arises as to whether the flanges in the flanged joint are strong enough to pass the hydrostatic test. To pursue this question, it is appropriate to tabulate the tangential and radial stresses at initial and pressurized conditions:

<u>Condition</u>	<u>STH</u>	<u>STF</u>	<u>SRH</u>	<u>SRF</u>
Initial	20,499	-33,907	15,492	-12,197
Pressurized	31,436	-30,496	9,739	-9,970

It should be noted that the stresses are, in large part, bending stresses. Before large plastic deformations occur, these stresses must reach about  $1.5S_y$ , where  $S_y$  is the yield strength of the flange material. Further, high stresses in the hub will not lead to large plastic deformations if there is reserve strength in the flange ring as indicated by relatively low tangential and radial stresses. If the capability for calculating these stresses has been attained, the next logical step is to conduct an extensive study to develop suitable design criteria for stress limits in flanged joints. Until such a study is conducted, however, the following limits are suggested as appropriate for stresses under hydrostatic test conditions:

Stress	Limit
Longitudinal hub stresses	$<1.5S_y$
Radial stress or tangential stress	$<S_y$
Averages of radial or tangential stress and longitudinal hub stress	$<S_y$

The above criterion makes the average of SLSO and STH under pressurized conditions [i.e.,  $1/2(5.7253 \times 10^4 + 3.1436 \times 10^4) = 44,344$  psi] the controlling stress and infers that the flanged joint is acceptable, provided the flange-material yield strength is not less than 44,344 psi.

### Displacements

In tightening the bolts to 46,100 psi, the question arises as to whether the flanges will rotate so that contact occurs on the outer edge. Table A.8c shows values of THETA, the rotation of the ring at the mean radius of the pipe wall. An estimate\* of the displacement of the ring edge with respect to the gasket centerline can be obtained by

---

\* The deformation of the ring is not exactly linear across the ring, but in this example it is sufficiently close to linear.

multiplying THETA by  $(A-G)/2$ , the radial distance between the ring edge and gasket centerline. In example 4(a),  $A = 73.9375$ ,  $G = 62.625$ , and  $\text{THETA} = -9.0466 \times 10^{-3}$  under combined loading; the minus sign means that the rotation is such that clearance is reduced at the outer edge. The displacement of A with respect to C is  $9.0466 \times 10^{-3} \times (73.9375 - 62.625)/2 = 0.0512$  in. Because API-605 flanges have 1/16-in. raised faces, the outer edges of the flanges will not contact each other. The clearance will then be  $(0.0625 - 0.0512) \times 2 = 0.0056$  in. plus the thickness of the gasket.

## COMPUTER TIME

The six examples discussed in this appendix were run on Battelle's CDC 6400 computer and also on ORNL's IBM 360/91. The IBM FORTRAN source deck (converted to double precision for use on the IBM machine) has 1583 cards. The total length of the program is 80K bytes (10,240 actual words), and it needs no auxiliary storage devices except standard read and write units. The program requires 270K bytes for compilation and has a compilation time of 19.4 sec. The total execution time for the six examples was 1.15 sec.

APPENDIX B

FLOWCHARTS AND LISTING OF COMPUTER PROGRAM FLANGE  
AND ATTENDANT SUBROUTINES



APPENDIX B

CONTENTS

	<u>Page</u>
1. Flowcharts of Program FLANGE and Attendant Subroutines . . . . .	101
2. Listing of Program FLANGE and Attendant Subroutines . . . . .	114



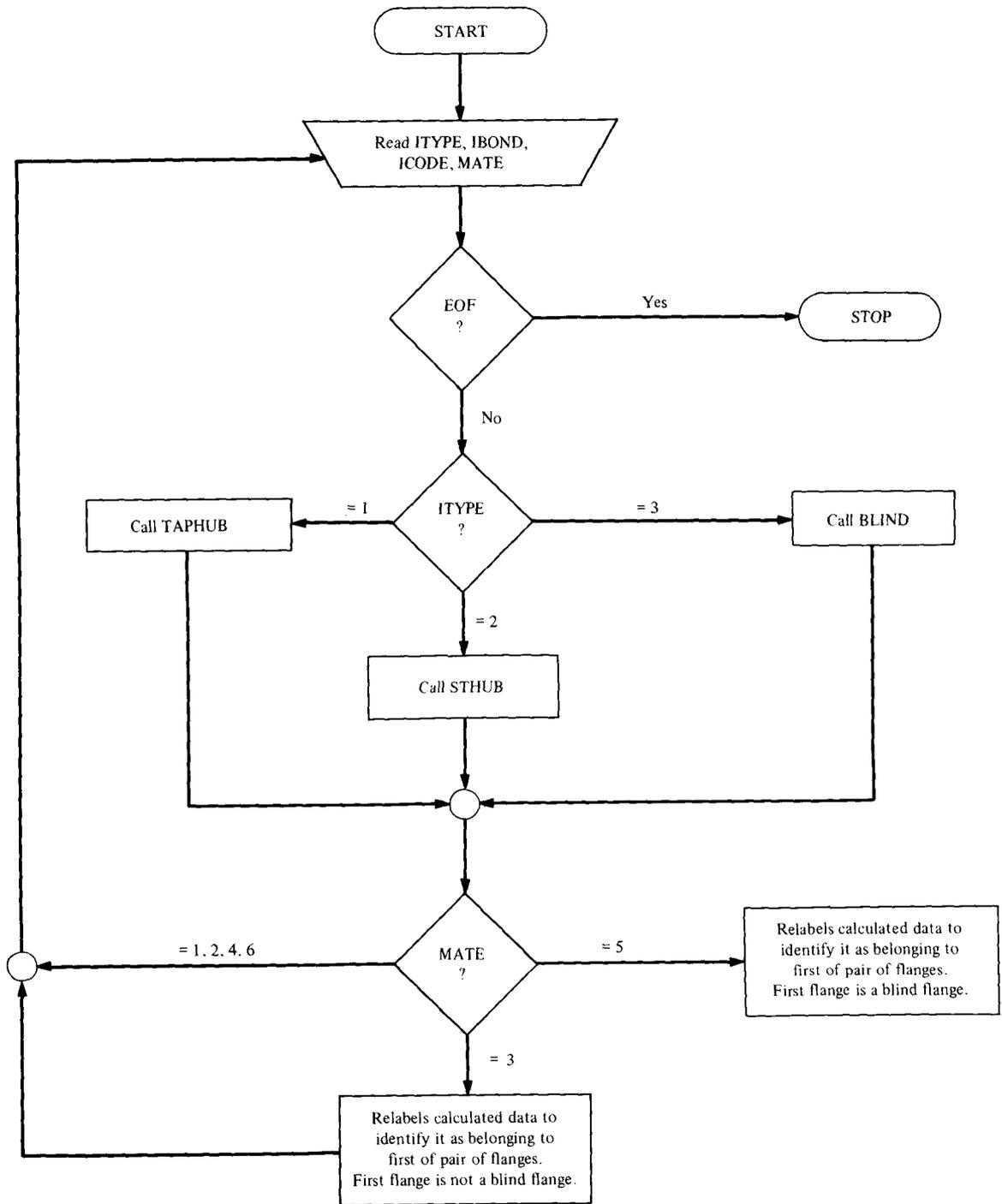


Fig. B.1. Program FLANGE.

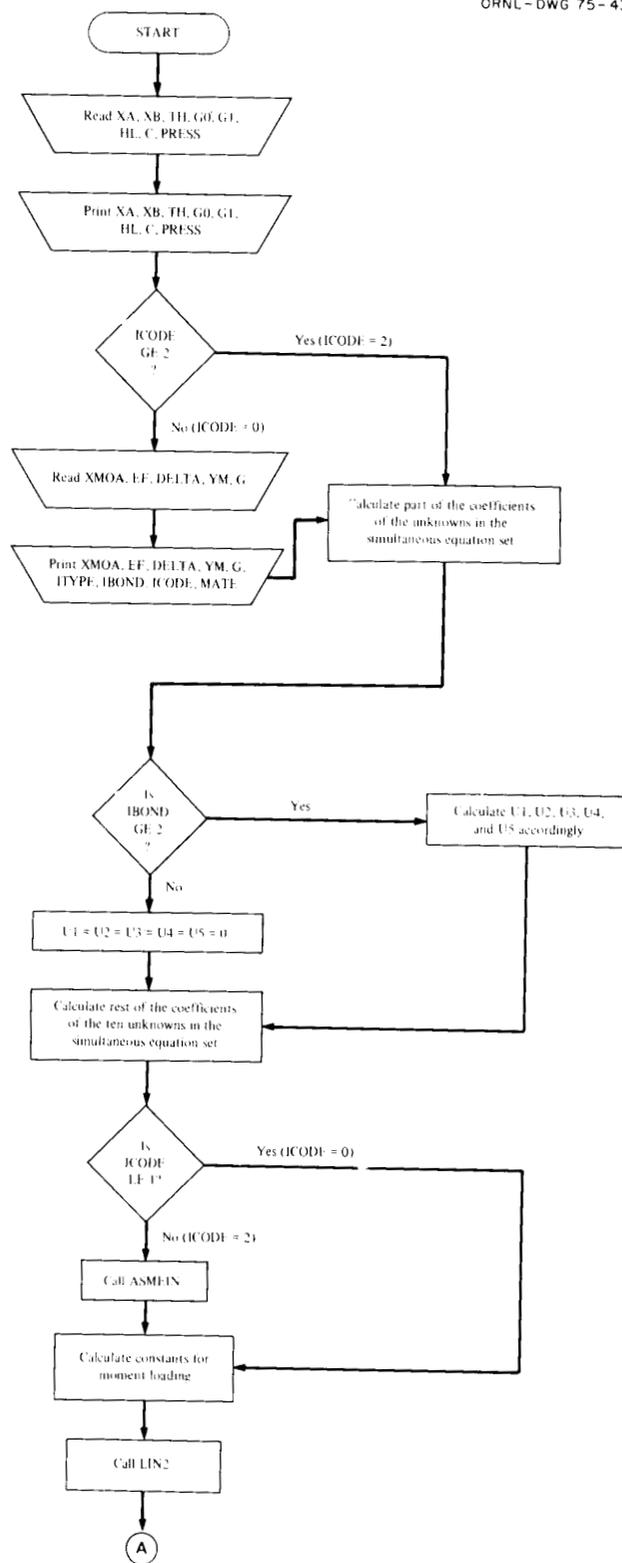


Fig. B.2. Subroutine TAPHUB (Part 1).

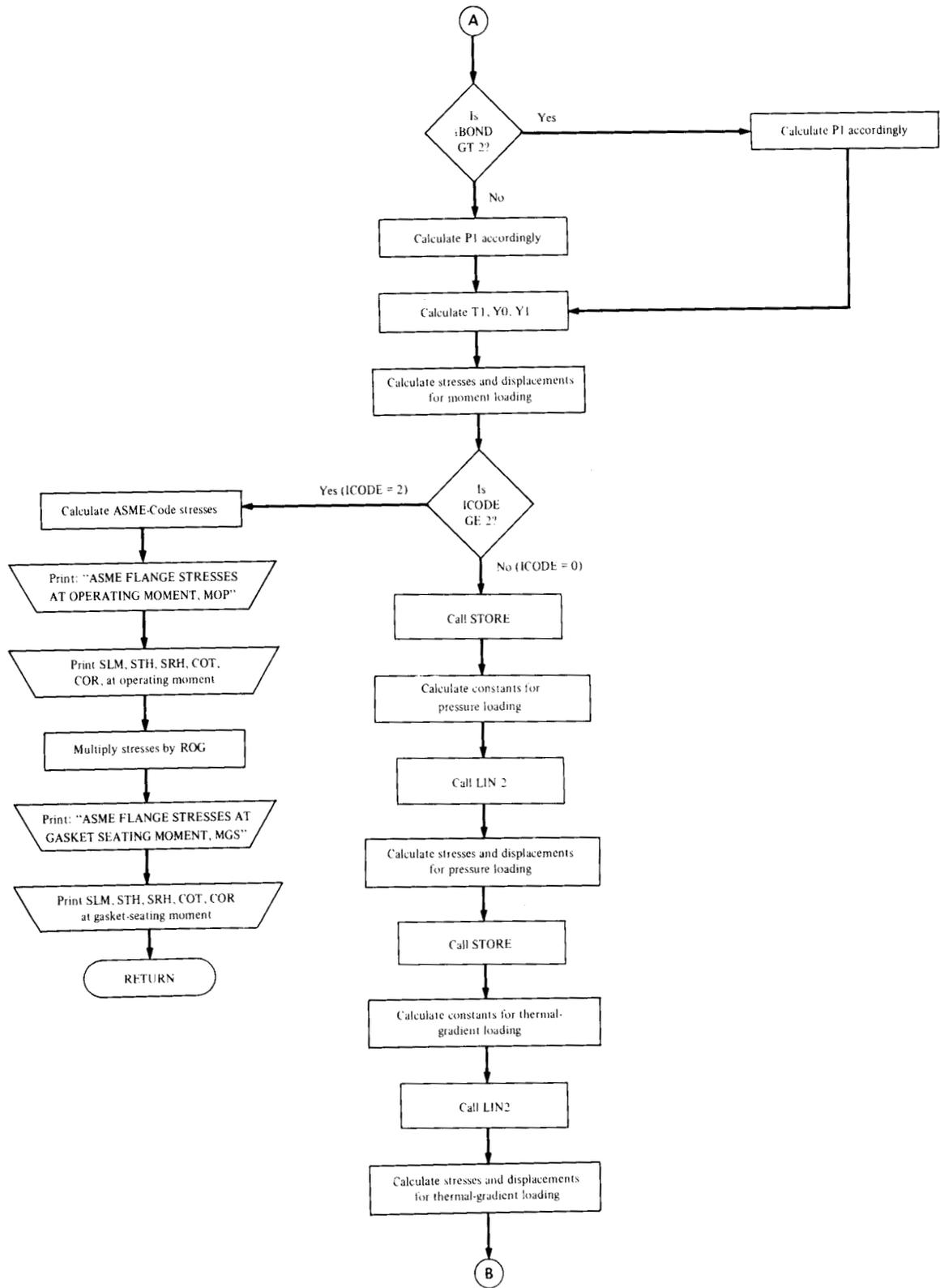


Fig. B.2. Subroutine TAPHUB (Part 2).

ORNL-DWG 75-4303R

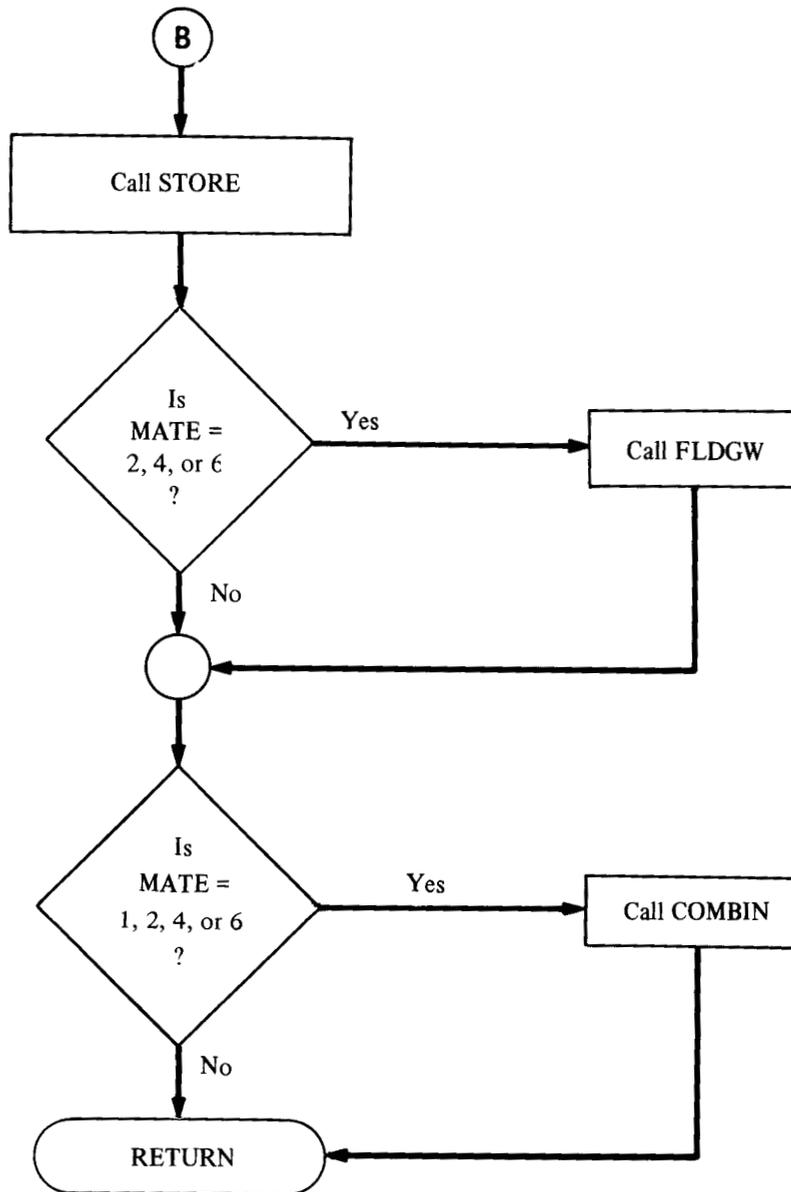


Fig. B.2. Subroutine TAPHUB (Part 3).

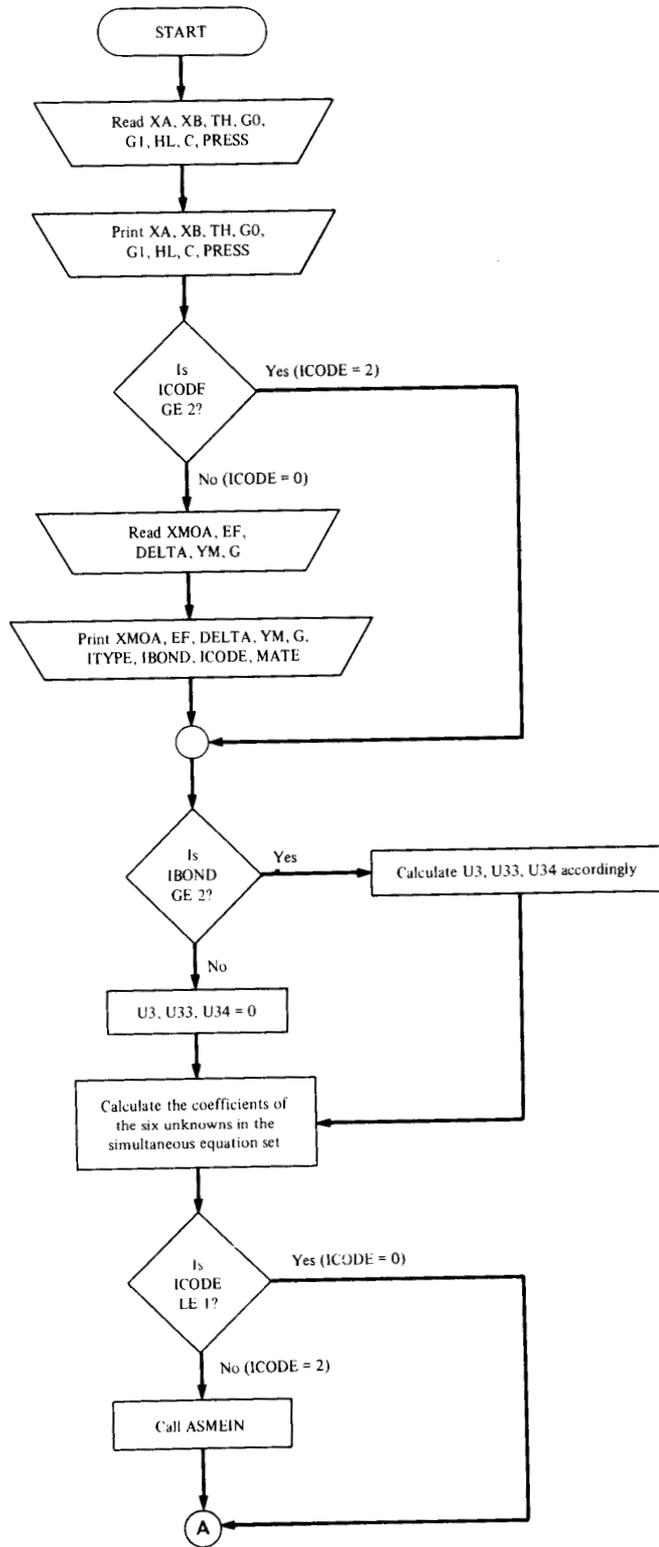


Fig. B.3. Subroutine STHUB (Part 1).

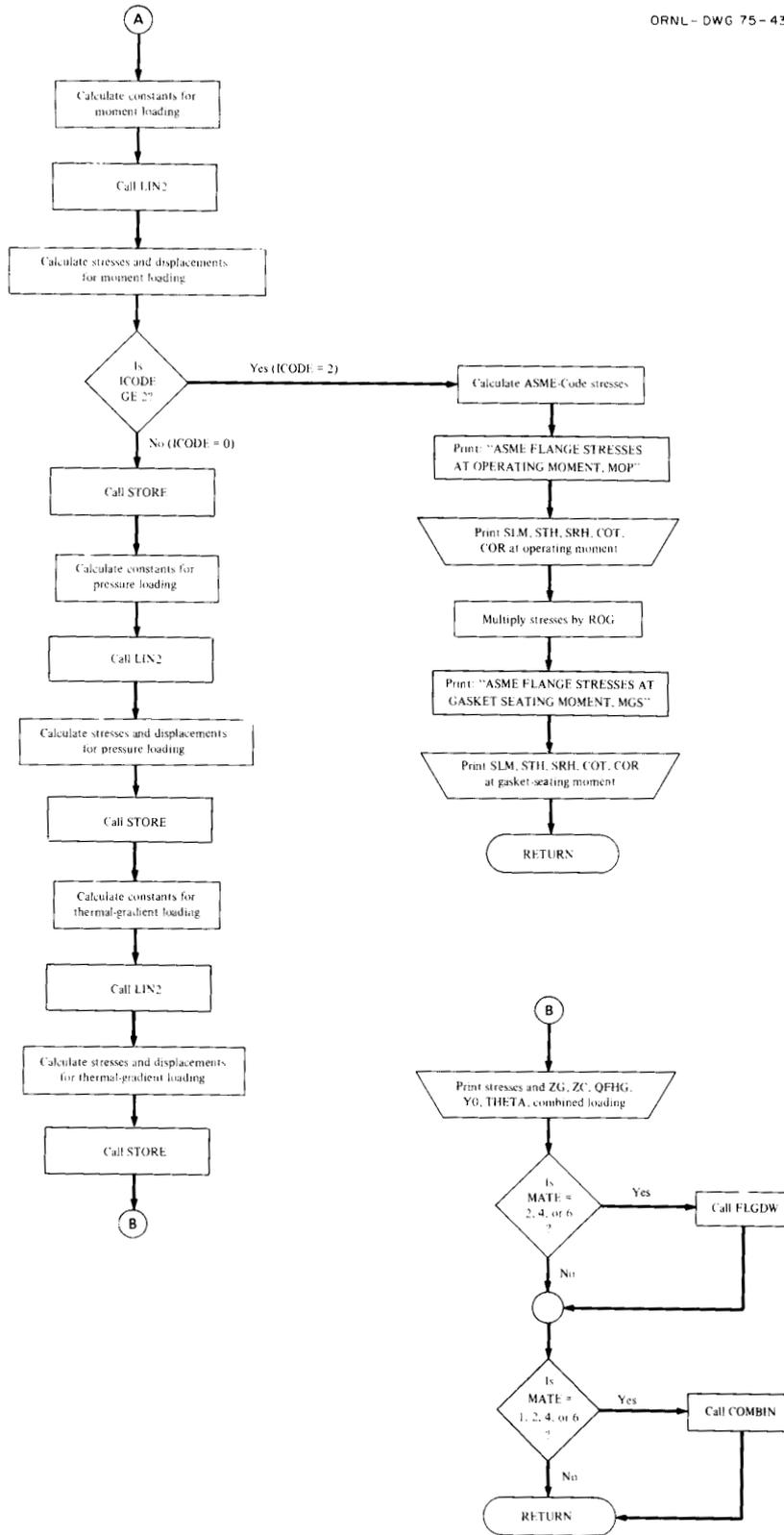


Fig. B.3. Subroutine STHUB (Part 2).

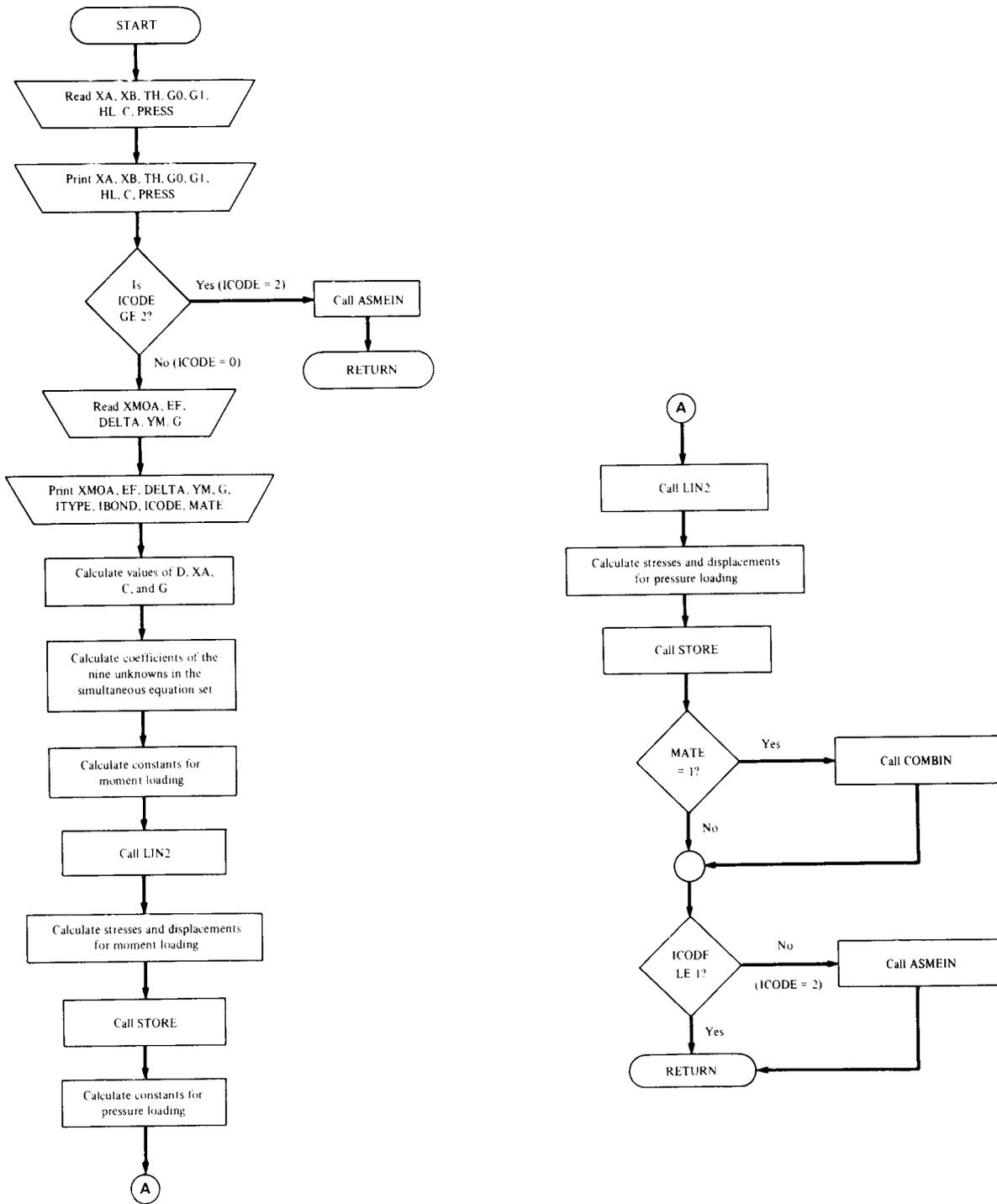


Fig. B.4. Subroutine BLIND.

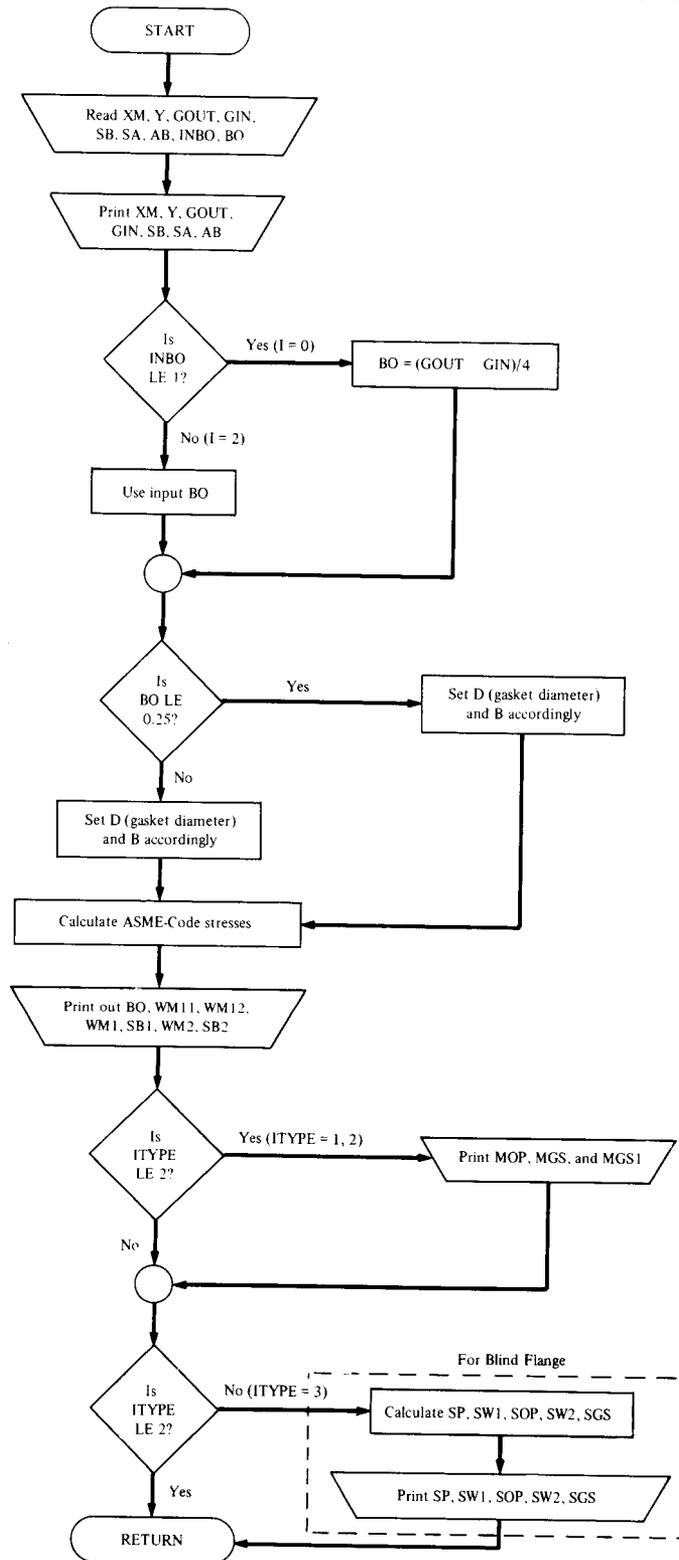


Fig. B.5. Subroutine ASMEIN.

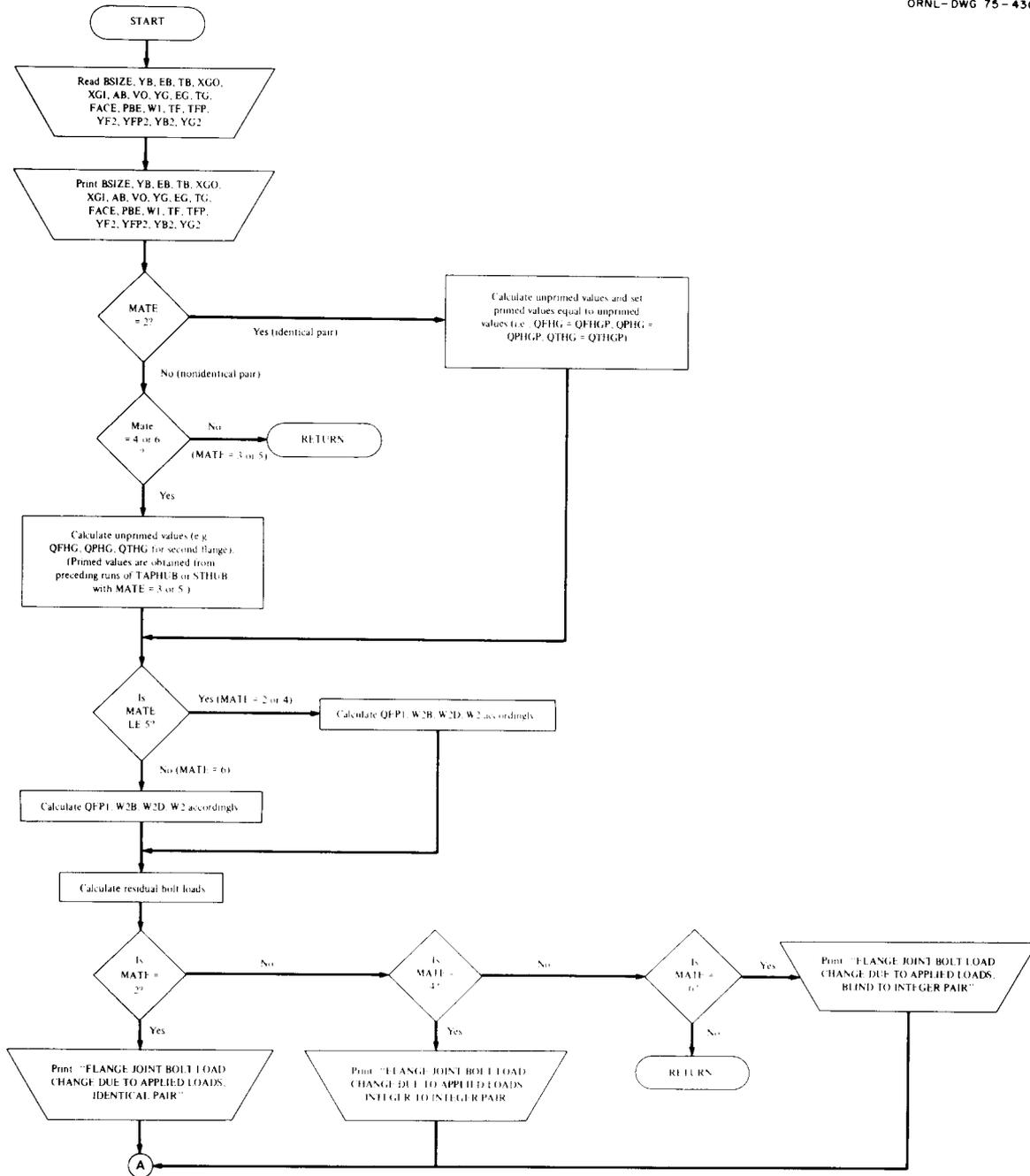


Fig. B.6. Subroutine FLGDW (Part 1).

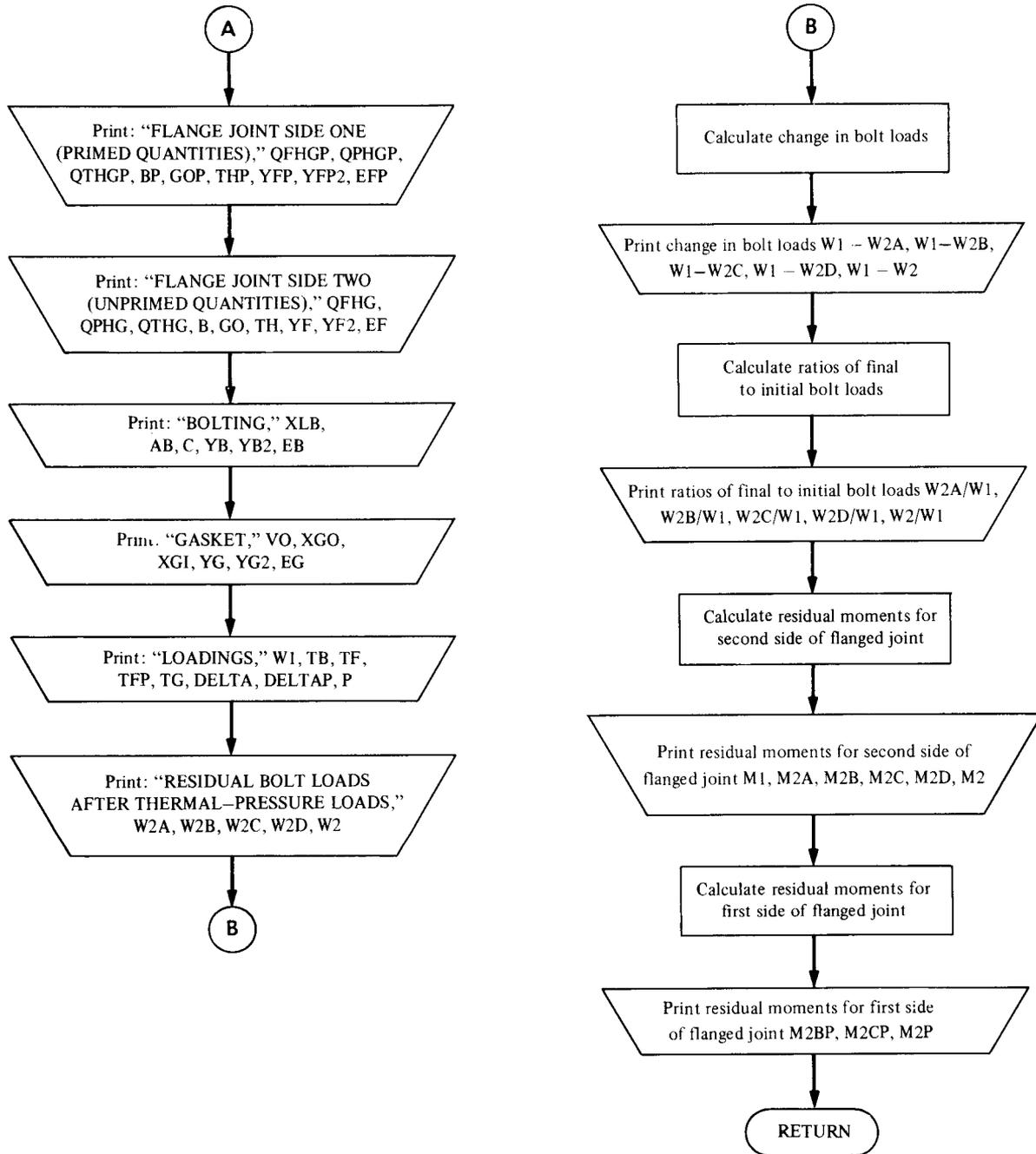


Fig. B.6. Subroutine FLGDW (Part 2).

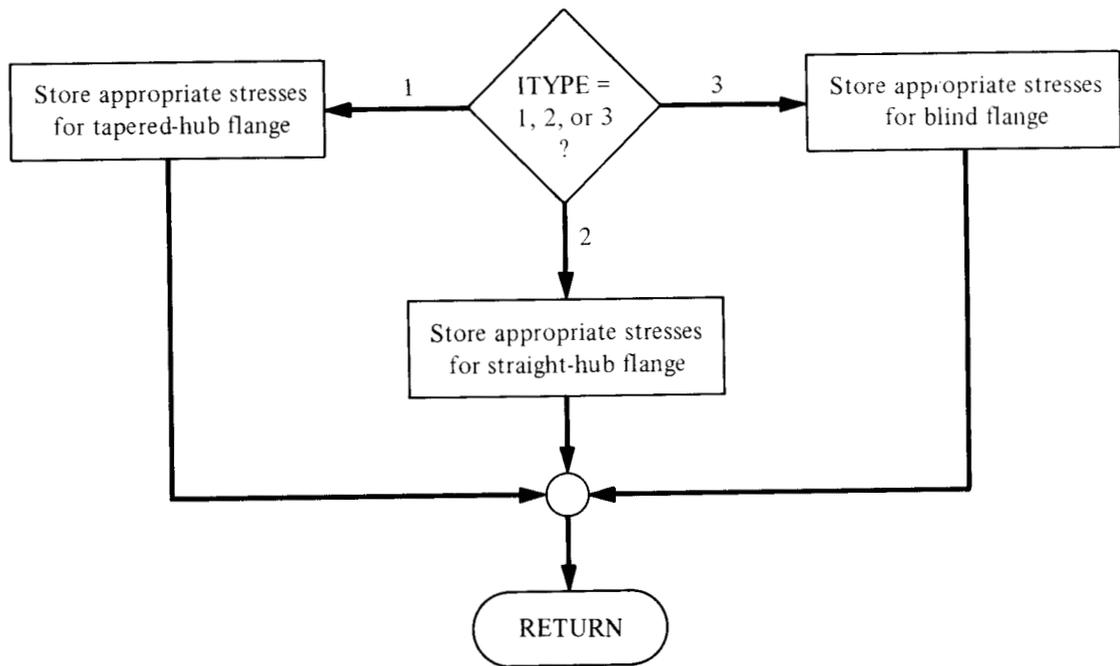


Fig. B.7. Subroutine STORE.

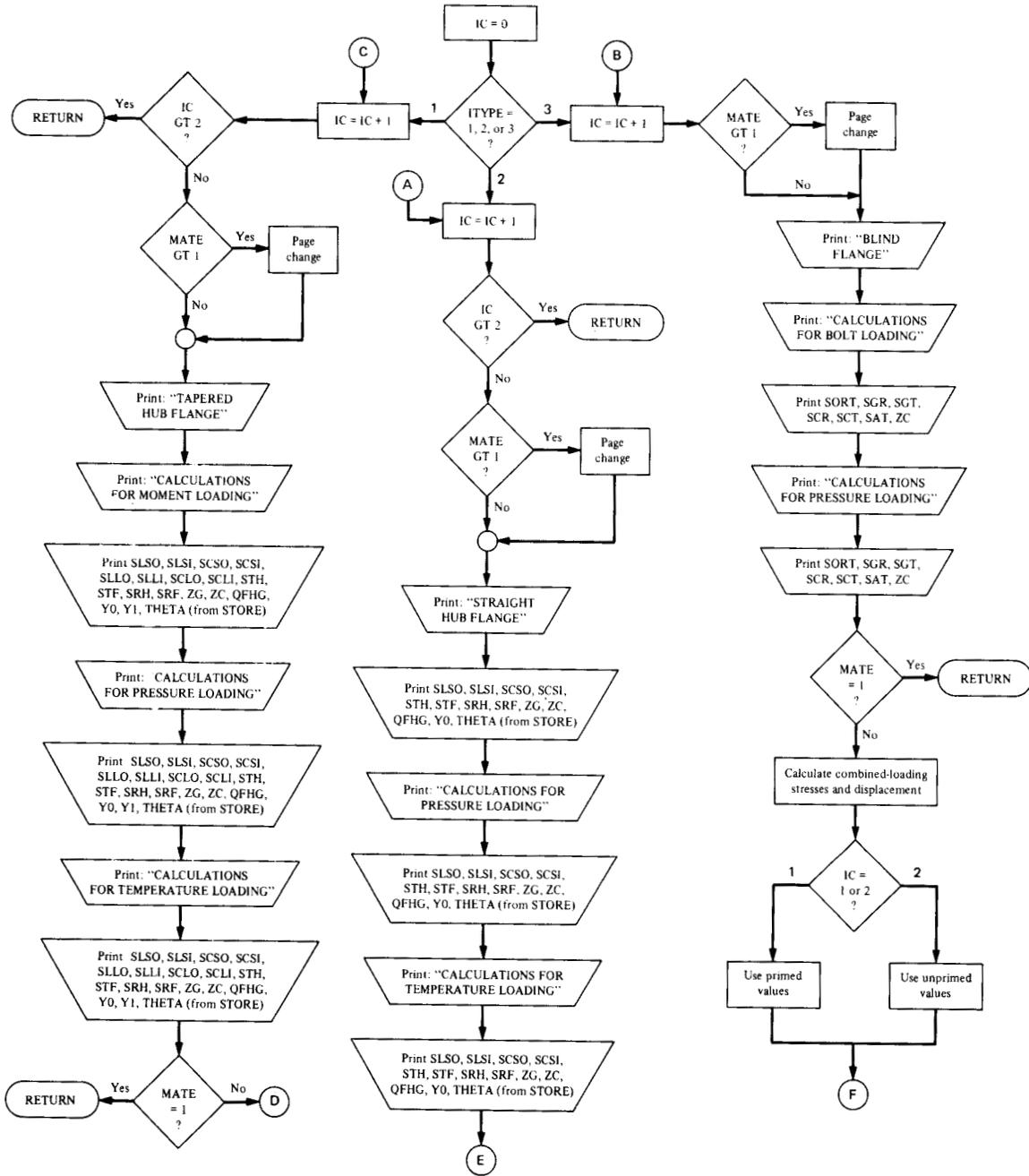


Fig. B.8. Subroutine COMBIN (Part 1).

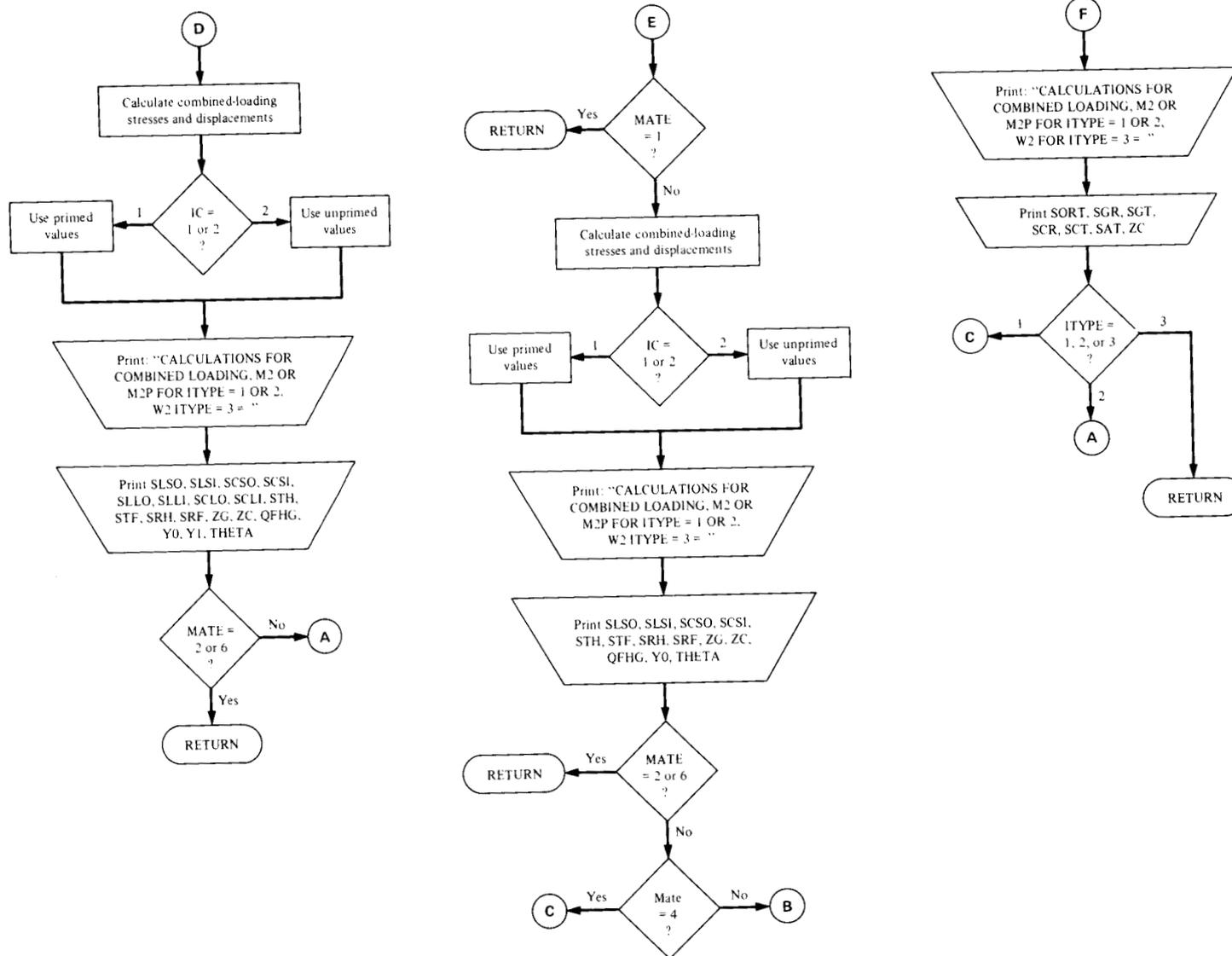


Fig. B.8. Subroutine COMBIN (Part 2).



	DELTA=DELTA	FLA	51
	IT = ITYPE	FLA	51A
	GO TO 1	FLA	52
C	10 RETURN	01-27-75	
		FLA	54
	11 FORMAT (1H1)	FLA	55
	12 FORMAT (4I5)	FLA	56
	END	FLA	57
	SUBROUTINE TAIHUB	TAP	2
C	THIS CALCULATION IS FOR ITYPE = 1, TAPERED HUB FLANGES	TAP	4
	IMPLICIT REAL*8 (A-H,C-Z)	01-28-75	
	DIMENSION A(10,10), B(10), LTEMP(10), LPR(10), LPC(10), AM(10,10)	TAP	6
	DIMENSION SB(6,18), SC(18)	TAP	7A
	COMMON ITYPE, IBCND, ICCDE, MATE, XA, XB, G, C, PRESS, XGS, XOP, G1, GO, TH, YM, TAP		8
	1AB, QFHR(4), AL, DELTA, XMO, XMOA, QFHGP, QPHGP, QTHGP, BF, GOP, THP, YFP, EFP, TAP		10
	2DELTA P, GOUT, GIN, BCG	TAP	12
	3, SLSO, SLSI, SC SC, SCSI, SLIO, SILI, SCLO, SCLI, SPH	TAP	7A
	4, STF, SFH, SFF, ZG, ZC, QFHG, Y0, Y1, T1, THETA, SORT, SGR, SGI, SCR, SCT, SAT	TAP	7B
	5, W2, W1, SB, MA, IT, XM1, XM2, XM2E	TAP	7C
	DATA A/100*0./, B/10*0./, LTEMP/10*0/, LPR/10*0/, LPC/10*0/, AM/100*0./		
C			
	1 READ 48, XA, XE, TH, GO, G1, HL, C, PRESS	TAP	14
	PRINT 49	TAP	16
	PRINT 50, XA, XE, TH, GO, G1, HL, C, PRESS	TAP	18
	G=1.	TAP	20
	YM=1.	TAP	22
	IF (ICODE.GE.2) GO TO 2	TAP	24
	READ 51, XMOA, EF, DELTA, YM, G	TAP	26
	PRINT 52	TAP	28
	AL=EF	TAP	30
	PRINT 53, XMOA, EF, DELTA, YM, G, ITYPE, IBCND, ICODE, MATE	TAP	32
	2 HHO = HL/DSQRT(XB*GO)	TAP	34A
	XA=XA/2.	TAP	36
	XB=XB/2.	TAP	38
	G=G/2.	TAP	40
	C=C/2.	TAP	42
	RHO=G1/GO	TAP	44
	ALPHA=RHO-1	TAP	46
	GAMMA = (10.92**0.25) *HL/DSQRT(XB*GO)	TAP	48A
	PHI0=1./ALPHA	TAP	50
	PHI1=RHO/ALPHA	TAP	52
	ETA0=2.*GAMMA/ALPHA	TAP	54
	ETA1=(RHO**.5)*ETA0	TAP	56
	XK=XA/XB	TAP	58
	J=1	TAP	60
	X=ETA0	TAP	62
	PS=(.85*XB/(YM*GO))*PRESS	TAP	64
	3 CONTINUE	TAP	66
	IF (X-10.0) 4,4,5	TAP	68
	4 T=X/10.0	TAP	70
	C3 = DLOG(X/2.0)	TAP	72A
	T2=T*T	TAP	74
	T3=T2*T	TAP	76
	T4=T3*T	TAP	78
	T8=T4*T4	TAP	80
	T12=T8*T4	TAP	82
	T16=T12*T4	TAP	84
	T20=T16*T4	TAP	86

```

T24=T20*T4
T28=T24*T4
T32=T28*T4
C ** CORR. TO CARDS TAP 94-149 OF SUBR. TAP HUB, 02-27-75.
BERX=.999999999974D0-156.24999999995701D0*T4+678.1684027663091D0*TT AP 94 A
18-4 70.9502795889968D0*T12+93.8596692971726D0*T16-7.2422567278207D0TAP 96 A
2*T20+.2597773C007E0*T24-.0C48987125727D0*T28+.0000516070465D0*T32 T AP 98 A
BEIX=-T2*(-24.999999999998E0+434.027777777748D0*T4-678.1684027769TAP 100 A
1807D0*T8+240.2807549442574D0*T12-28.9690338786499D0*T16+1.49633427T AP 102 A
249742D0*T20-.0384288282734D0*T24+.0005444243175D0*T28-.44913D-5*T3T AP 104 A
42) TAP 105 A
DBERX=T3*(-62.4995999599999D0+542.534722222147D0*T4-565.140335647T AP 106 A
19486D0*T8+150.1754718432278D0*T12-14.4845169498403D0*T16+.62347263TAP 108 A
248243D0*T20-.013724603619D0*T24+.1701453451D-3*T28-.12506046D-5*T3TAP 110 A
32) T AP 111 A
DBEIX=-T*(-4.999999999993D0+260.4166666665533D0*T4-678.1684027747TAP 112 A
1539D0*T8+336.3930569023651D0*T12-52.1442608975905D0*T16+3.29193521T AP 114 A
208579D0*T20-.0999147064932D0*T24+.0016331100837D0*T28-.00001522698TAP 116 A
384D0*T32) TAP 117 A
R1X=T2*(24.999999999993D0-795.7175925924866D0*T4+1548.48451967309T AP 118 A
192D0*T8-623.0136717405201D0*T12+81.95247716062D0*T16-4.51874591326TAP 120 A
239D0*T20+.1222087382192D0*T24-.0018064777860D0*T28+.154363047D-4* TAP 122 A
3T32) T AP 123 A
R2X=T4*(234.375-1412.8508391203636D0*T4+1153.8281852814561D0*T8-25TAP 124 A
15.0971742710479D0*T12+21.2123451660231D0*T16-.8061529027876D0*T20+T AP 126 A
2.0159380149705D0*T24-.0001797627986D0*T28+.0000012161109D0*T32) T AP 128 A
DR1X=T*(4.9999999999975E0-477.4305555551536D0*T4+1548.484519665203TAP 130 A
15D0*T8-872.2191403672455D0*T12+147.5144585913337D0*T16-9.941240320T AP 132 A
29725D0*T20+.3177418434686D0*T24-.0054188558408D0*T28+.000052329431TAP 134 A
34D0*T32) TAP 135 A
DR2X=T3*(93.749999999998D0-1130.2806712962694D0*T4+1384.593822337T AP 136 A
12452D0*T8-408.1554788292578D0*T12+42.4246903131088D0*T16-1.9347669TAP 138 A
2229237D0*T20+.0446263862145D0*T24-.0005752042283D0*T28+.0000043682T AP 140 A
3053D0*T32) T AP 141 A
CEIX=-.78539816439745D0*BERX+R1X-(.5772156649D0+C3)*BEIX TAP 142 A
CERX=+.78539816439745D0*BEIX-R2X-(.5772156649D0+C3)*BERX T AP 144 A
DKERX=+.78539816439745D0*CEIX-DR2X-(ERX/X)-(.5772156649D0+C3)*DBTAP 146 A
1ERX TAP 147 A
DKEIX=-.78539816439745D0*DBERX+DR1X-(BEIX/X)-(.5772156649D0+C3)*DBTAP 148 A
1EIX TAP 149 A
GO TO 6 TAP 150
5 T=10.0/X T AP 152
C1=(DEXP(+X/1.414213562371D0)/DSQRT(6.28318503718D0*X)) TAP 154 B
C2=(DEXP(-X/1.414213562371D0)*DSQRT(1.57079632679D0/X)) T AP 156 B
SIN1=DSIN((X/1.414213562371D0)+(.392699081699D0)) T AP 158 B
SIN2=DSIN((X/1.414213562371D0)-(.392699081699D0)) TAP 160 B
COS1=DCOS((X/1.414213562371D0)+(.392699081699D0)) T AP 162 B
COS2=DCOS((X/1.414213562371D0)-(.392699081699D0)) TAP 164 B
T2=T*T TAP 166
T3=T2*T TAP 168
T4=T3*T TAP 170
T5=T4*T TAP 172
T6=T5*T TAP 174
T7=T6*T TAP 176
T8=T7*T TAP 178
S=1+.0088388346D0*T+.7D-9*T2-.0000517869E0*T3-.0000112207D0*T4-.0TAP 180 A
1000016192D0*T5+.135D-8*T6+.1452D-6*T7+.492D-7*T8 TAP 182 A
IT=-.0088388340D0*T-.0007031241D0*T2-.0000518006D0*T3-.72D-8*T4+.1T AP 184 A
164310D-5*T5+.5929E-6*T6+.750D-7*T7-.243E-7*T8 TAP 186 A
U=1-.0265165040D0*T-.8D-9*T2+.725024D-4*T3+.144255D-4*T4+.19780D-T AP 188 A
15*T5-.147D-7*T6-.1671E-6*T7-.563D-7*T8 TAP 190 A
V+-.0265165034D0*T+.0011718740D0*T2+.725179D-4*T3+.79D-8*T4-.20042TAP 192 A
1D-5*T5-.6992D-6*T6-.8E3D-6*T7+.269D-8*T8 T AP 194 A
BERX=C1*((S*CCS2)-(T*SIN2)) T AP 196
BEIX=C1*((T*CCS2)+(S*SIN2)) T AP 198
DBERX=C1*((U*CCS1)-(V*SIN1)) T AP 200
DBEIX=C1*((V*CCS1)+(U*SIN1)) TAP 202
T=-T T AP 204
T2=T*T TAP 206
T3=T2*T TAP 208

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T4=T3*T	TAP	210
T5=T4*I	TAP	212
T6=T5*T	TAP	214
T7=T6*T	TAP	216
T8=T7*I	TAP	218
S=1.+ .0088388346D(*T+.7D-9*T2-.517869D-4*T3-.112207D-4*T4-.16192D-5*T5+.135D-8*T6+.1452D-6*T7+.492D-7*T8	TAP	220A
TI=-.8838834D-2*T-.7031241D-3*T2-.518006D-4*T3-.72D-8*T4+.16431D-5*TAP	TAP	222A
1*T5+.5929D-6*T6+.75CD-7*T7-.243D-7*T8	TAP	224A
U=1.-.026516504D0*T-.8D-9*T2+.725024D-4*T3+.144255D-4*T4+.1978D-5*TAP	TAP	226A
T5-.147D-7*T6-.1671D-6*T7-.563D-7*T8	TAP	228A
V=+.0265165034D0*T+.1171874D-2*T2+.725179D-4*T3+.79D-8*T4-.20042D-5*TAP	TAP	230A
15*T5-.6992D-6*T6-.8831D-6*T7+.269D-8*T8	TAP	232A
CEIX=C2*(S*COS1)+(T*T*SIN1)	TAP	234A
CEIX=C2*(T*T*CCS1)-(S*SIN1)	TAP	236
DKERX=-C2*((U*COS2)+(V*SIN2))	TAP	238
DKEIX=-C2*((V*COS2)-(U*SIN2))	TAP	240
6 CONTINUE	TAP	242
IF (J-1) 7,7,8	TAP	244
7 PO=(1./(RHO-1.))**.5	TAP	246
J=J+1	TAP	248
A(1,1)=DBERX	TAP	250
A(1,2)=DBEIX	TAP	252
A(1,3)=DKERX	TAP	254
A(1,4)=DKEIX	TAP	256
A(1,5)=0.	TAP	258
A(1,6)=-PO	TAP	260
A(1,7)=0.	TAP	262
A(1,8)=0.	TAP	264
A(1,9)=0.	TAP	266
A(1,10)=0.	TAP	268
A(2,1)=-X*BEIX-2.*DBERX	TAP	270
A(2,2)=X*BERX-2.*DBEIX	TAP	272
A(2,3)=-X*CEIX-2.*DKERX	TAP	274
A(2,4)=X*CEIX-2.*DKEIX	TAP	276
A(2,5)=-X*PO/(2.**.5)	TAP	278
A(2,6)=A(2,5)	TAP	280
A(2,7)=0.	TAP	282
A(2,8)=0.	TAP	284
A(2,9)=0.	TAP	286
A(2,10)=0.	TAP	288
A(3,1)=4.*X*BEIX+8.*DBERX-X*X*DBEIX	TAP	290
A(3,2)=-4.*X*BERX+8.*DBEIX+X*X*DBERX	TAP	292
A(3,3)=4.*X*CEIX+8.*DKERX-X*X*DKEIX	TAP	294
A(3,4)=-4.*X*CEIX+8.*DKEIX+X*X*DKERX	TAP	296
A(3,5)=-X*X*PO	TAP	298
A(3,6)=0.	TAP	300
A(3,7)=0.	TAP	302
A(3,8)=0.	TAP	304
A(3,9)=0.	TAP	306
A(3,10)=0.	TAP	308
A(4,1)=(-X*BERX+2.*DBEIX)	TAP	310
A(4,2)=(-X*BEIX-2.*DBERX)	TAP	312
A(4,3)=(-X*CEIX+2.*DKEIX)	TAP	314
A(4,4)=(-X*CEIX-2.*DKERX)	TAP	316
A(4,5)=A(2,5)	TAP	318
A(4,6)=-A(2,5)	TAP	320
A(4,7)=0.	TAP	322
A(4,8)=0.	TAP	324
A(4,9)=0.	TAP	326
A(4,10)=0.	TAP	328
X=X*RHO**.5	TAP	330
GO TO 3	TAP	332
8 PO=(RHO/(RHO-1.))**.5	TAP	334
IF (IBOND-1) 9,10,10	TAP	336
9 U1=0.	TAP	338
U2=0.	TAP	340
U3=0.	TAP	342
U4=0.	TAP	344
U5=0.	TAP	346

GO TO 11	TAP	350
10 PHI 1=PO*PO	Γ AP	352
P=P E E S	TAP	354
XK2=XK*XK	TAP	356
U1=TH/(4.*PHI 1*HL)	Γ AP	358
U2=X*X*Y*M*G1**3/(87.36*TH*(PHI1*HL)**3)	TAP	360
U3=(XB/YM)*((1.3*XK2+.7)/(XK2-1.))	Γ AP	362
U4=-TH*XB*ALPHA*E S/(2.*HL*(1.+ALPHA)**2)	TAP	364
U5=ALPHA*GO*X E P/(4.*HL*TH)	TAP	366
11 AA11=DEERX	Γ AP	368
AA12=DBEIX	TAP	370
AA13=DKERX	TAP	372
AA14=DKEIX	Γ AP	374
AA21=-X*B E I X-2.*D E E R X	TAP	376
AA22=X*B E R X-2.*D B E I X	Γ AP	378
AA23=-X*C E I X-2.*D K E R X	Γ AP	380
AA24=X*C E R X-2.*D K E I X	TAP	382
AA41=(-X*E E R X+2.*I B E I X)	Γ AP	384
AA42=(-X*B E I X-2.*I B E R X)	TAP	386
AA43=(-X*C E R X+2.*I K E I X)	TAP	388
AA44=(-X*C E I X-2.*I K E R X)	Γ AP	390
A(5,1)=AA11+U1*AA21-U2*U3*AA41	TAP	392
A(5,2)=AA12+U1*AA22-U2*U3*AA42	Γ AP	394
A(5,3)=AA13+U1*AA23-U2*U3*AA43	TAP	396
A(5,4)=AA14+U1*AA24-U2*U3*AA44	TAP	398
A(5,5)=0.	Γ AP	400
A(5,6)=0.	TAP	402
A(5,7)=0.	TAP	404
A(5,8)=0.	Γ AP	406
A(5,9)=0.	TAP	408
A(5,10)=0.	Γ AP	410
A(6,1)=-X*B E I X-2.*D B E F X	Γ AP	412
A(6,2)=X*B E R X-2.*I B E I X	TAP	414
A(6,3)=-X*C E I X-2.*D K E R X	Γ AP	416
A(6,4)=X*C E R X-2.*I K E I X	TAP	418
A(6,5)=0.	TAP	420
A(6,6)=0.	Γ AP	422
A(6,7)=-2.0*PHI1**1.5*HL*(2.0*DLOG(XB)+1.0)	TAP	424A
A(6,8)=-4.*PHI1**1.5*HL	Γ AP	426
A(6,9)=-2.*PHI1**1.5*HL/(XB*XB)	TAP	428
A(6,10)=0.	Γ AP	430
A(7,1)=4.*X*B E I X+8.*D B E R X-X*X*D B E I X+((GAMMA**2.*TH)/(HL*ALPHA))*(-TAP	432	
1X*B E R X+2.*D B E I X)	Γ AP	434
A(7,2)=-4.*X*B E R X+8.*D B E I X+X*X*D B E R X+((GAMMA**2.*TH)/(HL*ALPHA))*TAP	436	
1-X*B E I X-2.*D B E R X)	TAP	438
A(7,3)=4.*X*C E I X+ε.*D K E R X-X*X*D K E I X+((GAMMA**2.*TH)/(HL*ALPHA))*(-TAP	440	
1X*C E R X+2.*D K E I X)	TAP	442
A(7,4)=-4.*X*C E R X+8.*D K E I X+X*X*D K E R X+((GAMMA**2.*TH)/(HL*ALPHA))*TAP	444	
1-X*C E I X-2.*D K E R X)	Γ AP	446
A(7,5)=0.	TAP	448
A(7,6)=0.	Γ AP	450
TEMP=-4.*PHI1**2.5*HL*H I*TH**3./((G1**3.)*XB)	TAP	452
A(7,7)=TEMP*(2.ε*DLOG(XB)+3.3)	TAP	454A
A(7,8)=TEMP*2.6	Γ AP	456
A(7,9)=-TEMP*0.7/(XB*XB)	TAP	458
A(7,10)=0.	Γ AP	460
A(8,1)=0.	TAP	462
A(8,2)=0.	TAP	464
A(8,3)=0.	Γ AP	466
A(8,4)=0.	TAP	468
A(8,5)=0.	Γ AP	470
A(8,6)=0.	Γ AP	472
A(8,7)=XB*XB*DLOG(XB)	TAP	474A
A(8,8)=XB*XB	Γ AP	476
A(8,9)=DLOG(XB)	TAP	478A
A(8,10)=1.0	Γ AP	480
A(9,1)=0.	Γ AP	482
A(9,2)=0	TAP	484
A(9,3)=0	Γ AP	486
A(9,4)=0	Γ AP	488

A (9,5)=0	TAP	490
A (9,6)=0	TAP	492
A (9,7) = 2.6*DLCG (XA) +3.3	TAP	494A
A (9,8)=2.6	TAP	496
A (9,9)=-0.7/(XA*XA)	TAP	498
A (9,10)=0.	TAP	500
A (10,1)=0.	TAP	502
A (10,2)=0.	TAP	504
A (10,3)=0.	TAP	506
A (10,4)=0.	TAP	508
A (10,5)=0.	TAP	510
A (10,6)=0.	TAP	512
A (10,7)=1.0	TAP	514
A (10,8)=0.	TAP	516
A (10,9)=0.	TAP	518
A (10,10)=0.	TAP	520
C PRINT 3,B (1), B (2), B (3), B (4), B (5), B (6), B (7), B (8), B (9), B (10)	TAP	522
DO 13 I=1,10	TAP	524
DO 12 J=1,10	TAP	526
AM (I,J)=A (I,J)	TAP	528
12 CONTINUE	TAP	530
13 CONTINUE	TAP	532
C CALCULATIONS FOR MOMENT LOADING, TAPERED HUB	TAP	534
P=0.	TAP	536
PS=0.	TAP	538
DELT=0.	TAP	540
IF (ICODE-1) 14,14,15	TAP	542
14 XMO=XMOA	TAP	544
GO TO 16	TAP	546
15 CALL ASMEIN	TAP	548
XMO=XOP	TAP	550
G=(GOUI+GIN)/2.	TAP	552
C 16 PRINT 54	TAP	554A
16 CONTINUE	TAP	554B
DO 17 I=1,10	TAP	556
B (I)=0.	TAP	558
17 CONTINUE	TAP	560
B (10) =-(2.73/(6.2832*YM*TH**3*(XA-XB)))*XMO	TAP	562
CALL LIN2 (A,10,1C,0.,B,1,1C,LTEMP,IERR,DET,NPIV,PIV,LPA,LPC)	TAP	564
B17=(-X*BERX+2.*DEEIX)	TAP	566
B18=(-X*BEIX-2.*DEERX)	TAP	568
B19=(-X*CERX+2.*DKEIX)	TAP	570
B20=(-X*CEIX-2.*DKERX)	TAP	572
P1=(-YM*G1**3*XB*ETA1**2./(87.36*PHI1**3.5*HL**3.))*(B17*B(1)+B18*	TAP	574
B(2)+B19*B(3)+B20*B(4))	TAP	576
B9=4.*X*BEIX+8.*DEERX-X*X*DEEIX	TAP	578
B10=-4.*X*BERX+8.*DBEIX+X*X*DBERX	TAP	580
B11=4.*X*CEIX+8.*DKERX-X*X*CKEIX	TAP	582
B12=-4.*X*CERX+8.*DKEIX+X*X*DKERX	TAP	584
A1=(1./(4.*PHI1**2.5))*(B9*B(1)+B10*B(2)+B11*B(3)+B12*B(4))+2.*ALP	TAP	586
T1=HA**2*PS/((1.+ALPHA)**3)	TAP	588
T1 = B (7) * (2.0*XB*DLOG (XB) +XB) +2.0*B (8) *XB+B (9) /XB	TAP	590A
P1A1=P1/A1	TAP	592
COF=- (YM*G0*HI*RH (**3.)) / (XB*2.73**2.25*GAMMA**3.)	TAP	594
F=P1A1/COF	TAP	596
T1A1=T1/A1	TAP	598
COV=(XB*2.73**2.25*RHO**3.)/(HL*GAMMA)	TAP	600
V=T1A1/COV	TAP	602
C-----01-17-75	TAP	604
C IF (IBOND-1) 18,18,19	TAP	606
C 18 CONTINUE	TAP	606
C-----01-17-75	TAP	608
19 IP=0	TAP	610
MA=1	TAP	612
20 SLBS=1.816*YM*B (5)	TAP	612
IP (IBOND-2) 21,21,22	TAP	614
21 P1=(-YM*G1**3*XB*ETA1**2/(87.36*PHI1**3.5*HL**3.))*(B17*B(1)+B18*B	TAP	616
12)+B19*B(3)+B20*B(4))	TAP	618
GO TO 23	TAP	620
22 P1=(-YM*G1**3*XB*ETA1**2/(87.36*PHI1**3.5*HL**3.))*(B17*B(1)+B18*B	TAP	622

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12) +E19*E(3) +B20*B(4) +ALPHA*G C*XB*P/(4.*HI)          TAP 624
23 T1 = B(7) * (2.0*XB*DLOG(XB) +XB) +2.0*B(8) *XE+B(9)/XE   TAP 626A
    Y0=XB*(B(6) +PS)                                          TAP 628
    Y1=(XB/FO)*(DEERX*B(1) +DBLIX*B(2) +DKERX*B(3) +DKELX*B(4)) +XB*PS/RHOTAP 630
    SLS0=-SIBS+P*XB/(2.*G0)                                   TAP 632
    SLSI=SLS0+P*XE/(2.*G0)                                    TAP 634
    SCS0=.3*SLS0+Y1*Y(XB)                                     TAP 636
    SCSI=.3*SLSI+Y1*Y0/XB                                     TAP 638
    SLBL=(YM*G1/1.82)*((XB/(4.*PHI1**2.5*HL*HL))*(B9*B(1) +B10*B(2) +B11*B(3) +B12*B(4)) +2.*XB*ALPHA**2*PS/(HL*HL*(1.+ALPHA)**3)) TAP 640
    SLLO=-SLBL+P*XE/(2.*G1)                                   TAP 642
    SLLI=SLLO+P*XE/(2.*G1)                                    TAP 644
    SCLO=.3*SLLI+Y1*Y(XB)                                     TAP 646
    SCLI=.3*SLLI+Y1*Y0/XB                                     TAP 648
    STB = -(YM*TH/1.82)*((2.6*DLOG(XB) +1.9)*B(7) +2.6*B(8) + (0.7/(XB*XB)) TAP 650
1) *B(9))
    STM=((XK*KK+1.)/(XK*KK-1.))*(P-P1/TH)                    TAP 652A
    STH=STB+STM                                               TAP 654A
    STP=-STB+STM                                               TAP 656
    SRB = -(YM*TH/1.82)*((2.6*DLOG(XE) +3.3)*B(7) +2.6*B(8) -0.7*B(9)/(XB TAP 658
1*XB))
    SRH=SRB-P+P1/TH                                           TAP 660
    SEF=-SRB-P+P1/TH                                           TAP 662A
    FR=SLS0/SLL0                                               TAP 664A
    ZG = B(7) *G*G*DLOG(G) +B(8) *G*G+B(9) *DLOG(G) +B(10)   TAP 666
    ZC = B(7) *C*C*DLOG(C) +B(8) *C*C+B(9) *DLOG(C) +B(10)   TAP 668
    QFHG=-ZC+ZG                                               TAP 670
    QFHR(MA)=QFHG                                              TAP 672A
    IF (ICODS-2) 24,25,25                                       TAP 674A
24 CALL STORE                                                  TAP 676
C 24 PRINT 55, ETC,ETC.                                         TAP 678
C 1,ETC,ETC.                                                  TAP 680
    GO TO 26                                                    TAP 681A
25 SLMAX = DMAX1( EABS(SLS0),DABS(SLLO) )                    TAP 682A
    SLM=.66667*SLMAX                                           TAP 684A
    COT=(SLMAX+STH)/2.                                          TAP 686
    COR=(SLMAX+SRH)/2.                                          TAP 688A
    PRINT 56                                                    TAP 690
    PRINT 57, SLM,STH,SRH,COT,COR                             TAP 692
    PRINT 58                                                    TAP 694
    SLM=SLM*ROG                                                TAP 696
    STH=STH*ROG                                                TAP 700
    SRH=SRH*ROG                                                TAP 702
    COT=COT*ROG                                                TAP 704
    COR=COR*ROG                                                TAP 706
    PRINT 57, SLM,STH,SRH,COT,COR                             TAP 708
    PRINT 62                                                    TAP 710
    GO TO 47                                                    TAP 712
26 IP=IP+1                                                    TAP 714
C GO TO( 27,36,40,44 ),IP                                     TAP 716
C GO TO( 27,36,40 ),IP                                       TAP 718
C CALCULATION PCR PRESSURE ICADING, TAPERED HUB            TAP 720A
27 XMO=0.                                                      TAP 721A
    P=PRESS                                                    TAP 722
    DELT=0.                                                    TAP 724
    PS=(.85*XB/(YM*G0))*E                                       TAP 726
C PRINT 59                                                    TAP 728
    DO 28 I=1,10                                               TAP 730
    B(I)=0.                                                    TAP 732A
28 CONTINUE                                                  TAP 734
    FO=(1./(RHO-1.))**.5                                       TAP 736
    E(2)=-2.*FO*PS                                             TAP 738
    B(3)=8.*FO*PS                                             TAP 740
-----01-17-75
C ** THESE TWO STATEMENTS NO LONGER COMMENTS, 09-17-75.    TAP 742
    IF (IBOND-2) 30,30,29                                       TAP 744
29 B(4) = -1.944*E*E                                           TAP 746A
-----01-17-75
30 FO=(RHO/(RHO-1.))**.5                                       TAP 748A
    IF (IBOND-2) 31,31,32                                       TAP 750

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31 B(5) = (PO/XB) * ((XB*PS / (1.+ALPHA)) - U3*P + U4 + XB*AL*DELTA) TAP 754
B(7) = 8.*PO*PS / (RHC) TAP 756
GO TO 33 TAP 758
32 B(5) = (PO/XB) * ((XB*PS / (1.+ALPHA)) - U3*P + U4 + U3*U5 + XB*AL*DELTA) TAP 760
B(7) = 8.*PO*PS / (RHC) - 5.46*TH*HL*P / (GO*GO*RF0** .5*ALPHA**1.5*YM) TAP 762
33 B(6) = -2.*PO*PS / (1.+ALPHA) TAP 764
DO 35 I=1,10 TAP 766
DO 34 J=1,10 TAP 768
A(I,J) = AM(I,J) TAP 770
34 CONTINUE TAP 772
35 CONTINUE TAP 774
CALL LIN2 (A,10,10,0.,B,1,10,LTEMP,IERR,DET,NEIV,PIV,LPA,LPC) TAP 776
MA=2 TAP 778
GO TO 20 TAP 780
C CALCULATION FOR DELTA TEMPERATURE, TAPERED HUB TAP 782
36 P=0. TAP 784
PS=0. TAP 786
DELTA=DELTA TAP 788
C PRINT 60 TAP 790A
DO 37 I=1,10 TAP 792
B(I)=0. TAP 794
37 CONTINUE TAP 796
B(5) = (PO/XB) * (XB*AL*DELTA) TAP 798
DO 39 I=1,10 TAP 800
DO 38 J=1,10 TAP 802
A(I,J) = AM(I,J) TAP 804
38 CONTINUE TAP 806
39 CONTINUE TAP 808
CALL LIN2 (A,10,10,0.,B,1,10,LTEMP,IERR,DET,NEIV,PIV,LPA,LPC) TAP 810
MA=3 TAP 812
GO TO 20 TAP 814
C ** CARDS TAP816-864 DELETED 09-19-75. TAP 866A
C 44 PRINT 62 TAP 866B
40 CONTINUE TAP 866C
GO TO (40,45,46,45,46,45), MATE TAP 868
45 CALL FLGDW TAP 870
46 CONTINUE TAP 872
GO TO (70,70,71,70,71,70), MATE TAP 873A
70 CALL COMBIN TAP 873B
71 CONTINUE TAP 873C
47 RETURN TAP 874
C 48 FORMAT (8E10.5) TAP 876
49 FORMAT (84H FLANGE FLANGE FLANGE PIPE HUB A. HUB TAP 880
1B BOLT PFESSURE, /84H O.L., A I.D., B THICK., T WATAP 882
2LL,GO BASE, G1 LENGTH, H CIRCLE, C P ) TAP 884
50 FORMAT (7F10.5,1F10.3/) TAP 886
51 FORMAT (5E10.5) TAP 888
52 FORMAT (98H MOMENT COEFF. OF DELTA MOD. OF MEAN GASKET IT TAP 890
1TYPE IBOND ICODE MATE /51H THERMAL ETAP 892
2XL. ELASTICITY DIAMETER ) TAP 894
53 FORMAT (1P5E10.3,16,3I10//) TAP 896
54 FORMAT (52H CALCULATIONS FOR MOMENT LOADING, TAPERED HUB FLANGE//) TAP 898
55 FORMAT (7H SLSO=1PE12.4,7H SLSI=E12.4,7H SCSO=E12.4,7H SCSI=E12.4 TAP 900
12.4//7H SLSO=E12.4,7H SLSI=E12.4,7H SCSO=E12.4,7H SCSI=E12.4//TAP 902
27H STH=E12.4,7H STP=E12.4,7H SRH=E12.4,7H SRP=E12.4//5H ZTAP 904
33=E12.4,5H ZC=E12.4,7H QPHG=E12.4,5H YC=E12.4,5H Y1=E12.4,8H TAP 906
4THETA=E12.4//) TAP 908
56 FORMAT (49H ASME FLANGE STRESSES AT OPERATING MOMENT, MOP //) TAP 910
57 FORMAT (11H (2/3)*SH=,1PE12.4,6H ST =,E12.4,6H SR =,E12.4,13H TAP 912
1(SH+SI)/2=,E12.4,13H (SH+SR)/2=,E12.4//) TAP 914
58 FORMAT (55H ASME FLANGE STRESSES AT GASKET SEATING MOMENT, MGS TAP 916
1//) TAP 918
59 FORMAT (34H CALCULATIONS FOR PRESSURE LOADING//) TAP 920
60 FORMAT (37H CALCULATIONS FOR TEMPERATURE LOADING//) TAP 922
61 FORMAT (34H CALCULATIONS FOR COMBINED LOADING//) TAP 924
62 FORMAT (1H1) TAP 926
END TAP 928

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SUBROUTINE SIHUB
THIS CALCULATION IS FOR ITYPE = 2, STRAIGHT HUB FLANGES
IMPLICIT REAL*8 (A-H,C-Z)
DIMENSION A(10,10), B(10), ITEMP(10), LPR(10), LPC(10), AM(10,10)
DIMENSION SB(6,18), SC(18)
COMMON ITYPE, IBCND, ICCDE, MATE, XA, XB, G, C, PRESS, XGS, XOP, G1, GJ, TH, YM,
1AE, QPHR(4), AL, DELTA, XMO, XMOA, QPHGP, QPHGP, QTHGP, BE, GOP, THP, YFP, EFP,
2DELTAE, GOUT, GIN, RCG
3, SLSO, SLSI, SCSC, SCSI, SLLS, SILI, SCLO, SCLI, STH
4, STF, SRH, SEF, ZG, ZC, QPHG, YC, Y1, T1, THETA, SOFT, SGR, SGT, SCR, SCT, SAT
5, W2, W1, SB, MA, IT, XM1, XM2, XM2F
DATA A/100*0./, B/10*0./, LTEMP/10*0/, LPR/10*0/, LPC/10*0/, AM/100*0./
C
1 READ 32, XA, XE, TH, GO, G1, HL, C, PRESS
PRINT 33
PRINT 34, XA, XB, TH, GO, G1, HL, C, PRESS
G=1.
YM=1.
IF (ICODE.GE.2) GO TO 2
READ 35, XMOA, EF, DELTA, YM, G
PRINT 36
AL=EF
PRINT 37, XMOA, EF, DELTA, YM, G, ITYPE, IBCND, ICODE, MATE
2 XA=XA/2.
XB=XB/2.
XK=XA/XB
XK2=XK*XK
G=G/2.
C=C/2.
BETA = 2.73**C.25/DSQRT(XB*GO)
IF (IBOND-1) 3,4,4
3 U3=0.
U33=0.
U34=0.
GO TO 5
4 U3=(XB/YM)*((1.3*XK2+.7)/(XK2-1.))
U33=2.*U3*YM*(GO*BETA)**3/(TH*10.92)
U34=TH*BETA/2.
5 XT1=U34-U33
XT2=1.+U34+U33
PS=(.85*XB/(YM*GO))*PRESS
A(1,1)=XT1
A(1,2)=XT2
A(1,3)=0.
A(1,4)=0.
A(1,5)=0.
A(1,6)=0.
A(2,1)=BETA
A(2,2)=BETA
A(2,3)=-2.0*XB*DLOG(XB)+XB
A(2,4)=-2.*XB
A(2,5)=-1./XB
A(2,6)=0.
A(3,1)=2.*BETA**2*(1.+BETA*TH/2.)
A(3,2)=-2.*BETA**3*TH/2.
A(3,3)=-2.6*DLOG(XB)+3.3*(TH/GO)**3
A(3,4)=-2.6*(TH/GO)**3
A(3,5)=(.7/(XE*XB))*(TH/GO)**3
A(3,6)=0.
A(4,1)=0.
A(4,2)=0
A(4,3)=XB*XB*DLOG(XB)
A(4,4)=XB*XB
A(4,5)=DLOG(XB)
A(4,6)=1.
A(5,1)=0.
A(5,2)=0.
A(5,3)=2.6*DLOG(XA)+3.3
A(5,4)=2.6

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	A (5,5) = -.7/(KA*XA)	STH	126
	A (5,6) = 0.	STH	128
	A (6,1) = 0.	STH	130
	A (6,2) = 0.	STH	132
	A (6,3) = 1.	STH	134
	A (6,4) = C.	STH	136
	A (6,5) = 0.	STH	138
	A (6,6) = 0.	STH	140
	DO 7 I=1,6	STH	142
	DO 6 J=1,6	STH	144
	AM (I,J) = A (I,J)	STH	146
	o CONTINUE	STH	148
	7 CONTINUE	STH	150
C	CALCULATIONS FOR MOMENT LOADING, STRAIGHT HUB	STH	152
	P=0.	STH	154
	PS=0.	STH	156
	DELI=0.	STH	158
	IF (ICORF-1) 8,8,9	STH	160
8	XMO=XMOA	STH	162
	GO TO 10	STH	164
9	CALL ASMLIN	STH	166
	XMO=XOP	STH	168
C	10 PRINT 38	STH	170A
	10 CONTINUE	STH	170B
	DO 11 I=1,6	STH	172
	B (I) = 0.	STH	174
11	CONTINUE	STH	176
	B (6) = -2.73*XMC/(6.2832*YM*TH**3*(XA-XE))	STH	178
	CALL LIN2 (A,6,10,0.,B,1,10,LEMP,IEAR,DET,NEIV,PIV,LPA,LPC)	STH	180
	IP=0	STH	182
	MA=1	STH	184
12	C5=B(1)	STH	186
	C6=B(2)	STH	188
	D1=B(3)	STH	190
	D2=B(4)	STH	192
	D3=B(5)	STH	194
	D4=B(6)	STH	196
	THETA=BETA*(C5+C6)	STH	198
	THETA1 = D1*(2.0*XB*DLOG(XE)+XB)+2.0*D2*XE+D3/XB	STH	200A
	XHO=YM*(G0**3)*(BETA**2)*C5/5.46	STH	202
	PO=YM*G0**3*BETA**3*(-C5+C6)/5.46	STH	204
	YO=C6+XJ*PS	STH	206
	SLBS=6.*XHO/(G0*G0)	STH	208
	SLSO=-SLBS+P*XB/(2.*G0)	STH	210
	SLSI=SLBS+P*XE/(2.*G0)	STH	212
	SCSO=.3*SLSO+YM*YO/XE	STH	214
	SCSI=.3*SLSI+YM*YC/XB	STH	216
	STM = -(YM*TH/1.82)*(2.6*D2+0.7*D3/(XB+XE)+D1*(2.6*DLOG(XB)+1.9))	STH	218A
	STH = (XK*XK+1.)/(XK*XK-1.)* (P-PO/TH)	STH	220
	STH=STH+STM	STH	222
	STP=-SIB+STM	STH	224
	SRB = -(YM*TH/1.32)*(2.6*D2+0.7*D3/(XB+XE)+D1*(2.6*DLOG(XB)+3.3))	STH	226A
	SRB=SRB-P+PO/TH	STH	228
	SFB=-SRB-I+PO/TH	STH	230
	ZG = D2*G*G+D3*DLOG(G)+D4+D1*(G*G*DLOG(G))	STH	232A
	ZC = D2*C*C+D3*DLOG(C)+D4+D1*(C*C*DLOG(C))	STH	234A
	QFHG=-ZC+ZG	STH	236
	QFHA(MA)=QFHG	STH	238
	IF (ICORF-2) 13,14,14	STH	240
C	13 PRINT 39, HIC, ETC.	STH	242A
	13 CALL SLOGE	STH	242B
	GO TO 15	STH	244
14	SLM=.66667*SLSO	STH	246
	COT=(SLSO+STH)/2.	STH	248
	COR=(SLSO+STH)/2.	STH	250
	PRINT 40	STH	252
	PRINT 41, SLM,STH,SFB,COT,COR	STH	254
	PRINT 42	STH	256
	SLN=SLM*LOG	STH	258
	STH=STH*LOG	STH	260

	SRH=SRH*ROG	STH	262
	COT=COT*ROG	STH	264
	COR=COR*ROG	STH	266
	PRINT 41, SLM,STH,SRH,COT,COR	STH	268
	PRINT 46	STH	270
	GO TO 31	STH	272
	15 IP=IP+1	STH	274
C	GO TO ( 16,20,24,28 ),IP	STH	276A
	GO TO ( 16,20,24 ),IP	STH	276B
C	CALCULATIONS FOR PRESSURE LOADING, STRAIGHT HUB	STH	278
	16 XMO=0.	STH	280
	DELT=0.	STH	282
	P=PRESS	STH	284
	PS=(.85*XB/(YM*GO))*P	STH	286
C	PRINT 43	STH	288A
	DO 17 I=1,6	STH	290
	B(I)=0.	STH	292
	17 CONTINUE	STH	294
	B(1)=+XP*PS+XE*AL*DELT-U3*PRESS	STH	296
	DO 19 I=1,6	STH	298
	DO 18 J=1,6	STH	300
	A(I,J)=AM(I,J)	STH	302
	18 CONTINUE	STH	304
	19 CONTINUE	STH	306
	CALL LIN2 (A,6,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPA,LPC)	STH	308
	MA=2	STH	310
	GO TO 12	STH	312
C	CALCULATIONS FOR DELTA TEMPERATURE LOADING, STRAIGHT HUB	STH	314
	20 P=0.	STH	316
	PS=0.	STH	318
	DELT=DELTA	STH	320
C	PRINT 44	STH	322A
	DO 21 I=1,6	STH	324
	B(I)=0.	STH	326
	21 CONTINUE	STH	328
	B(1)=XB*AL*DELT	STH	330
	DO 23 I=1,6	STH	332
	DO 22 J=1,6	STH	334
	A(I,J)=AM(I,J)	STH	336
	22 CONTINUE	STH	338
	23 CONTINUE	STH	340
	CALL LIN2 (A,6,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPA,LPC)	STH	342
	MA=3	STH	344
	GO TO 12	STH	346
C	** DELETED CARDS STH348-384 OF SUBR. STHUE 09-19-75.		
C	28 PRINT 46	STH	386A
	24 CONTINUE	STH	386B
	GO TO (30,29,30,29,30,29),MATE	STH	388
	29 CALL FLGDW	STH	390
	30 CONTINUE	STH	392
	GO TO (70,70,71,70,71,70),MATE	STH	392A
	70 CALL COMBIN	STH	392B
	71 CONTINUE	STH	392C
	31 RETURN	STH	394
C		STH	396
	32 FORMAT (8E10.5)	STH	398
	33 FORMAT (84H FLANGE FLANGE FLANGE PIPE HUB AT HUBSTH	400	
	18 BOLT PRESSURE, /84H O.L.,A I.D.,B THICK.,T WASTH	402	
	2LL,GO BASE,G1 LENGTH,H CIRCLE,C P )	STH	404
	34 FORMAT (7F10.5,1F10.3/)	STH	406
	35 FORMAT (5E10.5)	STH	408
	36 FORMAT (98H MOMENT COEFF. OF DELTA MOD. OF MEAN GASKET ITSTH	410	
	1YPE IBOND ICODE MATE /51H THERMAL ESTH	412	
	2XP. ELASTICITY DIAMETER )	STH	414
	37 FORMAT (1P5E10.3,16,3110//)	STH	416
	38 FORMAT (53H CALCULATIONS FOR MOMENT LOADING, STRAIGHT HUB FLANGE//STH	418	
	1)	STH	420
	39 FORMAT (7H SLSO=1PE12.4,7H SLSI=E12.4,7H SCSO=E12.4,7H SCSI=E1STH	422	
	12.4//7H STH=E12.4,7H STF=E12.4,7H SRH=E12.4,7H SRF=E12.4//STH	424	
	25H ZG=E12.4,5H ZC=E12.4,7H QPHG=E12.4,5H Y0=E12.4,8H THETA=E1STH	426	

	32.4//)		STH	428
40	FORMAT (49H ASME FLANGE STRESSES AT OPERATING MOMENT, MOP //)		STH	430
41	FORMAT (11H (2/3)*SH=, 1P212.4, 6H SI =, F12.4, 6H SA =, E12.4, 13H		STH	432
	1(SH*SI)/2=, E12.4, 13H (SH*SR)/2=, E12.4//)		STH	434
42	FORMAT (55H ASME FLANGE STRESSES AT GASKET SEATING MOMENT, MGS		STH	436
	1//)		STH	438
43	FORMAT (34H CALCULATIONS FOR PRESSURE LOADING//)		STH	440
44	FORMAT (37H CALCULATIONS FOR TEMPERATURE LOADING//)		STH	442
45	FORMAT (34H CALCULATIONS FOR COMBINED LOADING//)		STH	444
46	FORMAT (1H1)		STH	446
	END		STH	448
	SUBROUTINE BLIND		BLI	2
C	THIS CALCULATION IS FOR ITYPE = 3, BLIND FLANGES		BLI	4
	IMPLICIT REAL*8 (A-H, O-Z)			01-28-75
	DIMENSION A(10,10), B(10), LTEMP(10), LPR(10), LPC(10), AM(10,10)		BLI	6
	DIMENSION SB(6,18), SC(18)		BLI	6A
	COMMON ITYPE, IRONE, ICODE, MATE, XA, XB, G, C, PRESS, XGS, XOP, G1, GO, TH, YM, BLI			8
	1AB, QPHF(4), AL, DELTA, XMO, XMCA, QPHGF, QPHGP, QTHGF, BP, GOP, THP, YPF, EFP, BLI			10
	2DELTA, SOUT, GIN, FCG		BLI	12
	3, SLSO, SLSI, SCSO, SCSI, SLLO, SLLI, SULO, SULL, STH		BLI	12A
	4, STP, SRH, SFP, ZS, ZC, QFHG, Y0, Y1, T1, THETA, SOFT, SGR, SGA, SCR, SCT, SAT		BLI	12B
	5, W2, W1, SB, MA, IT, XM1, XM2, XM2F		BLI	12C
	DATA A/100*0., B/10*0., LTEMP/10*0., LPR/10*0., LPC/10*0., AM/100*0./			
C				
1	READ 17, XA, XB, TH, GO, G1, HL, C, PRESS		BLI	14
	PRINT 18		BLI	16
	PRINT 19, XA, XB, TH, GO, G1, HL, C, PRESS		BLI	18
	G=1.		BLI	20
	YM=1.		BLI	22
	IF (ICODE.GE.2) GO TO 15		BLI	24
	READ 20, XMCA, EF, DELTA, YM, G		BLI	26
	PRINT 21		BLI	28
	AL=EF		BLI	30
	PRINT 22, XMCA, EF, DELTA, YM, G, ITYPE, IRONE, ICODE, MATE		BLI	32
	D=YM*TH**3/10.92		BLI	34
	XA=XA/2.		BLI	36
	C=C/2.		BLI	38
	G=G/2.		BLI	40
	A(1,1)=G*G		BLI	42
	A(1,2)=1.		BLI	44
	A(1,3)=0.		BLI	46
	A(1,4)=0.		BLI	48
	A(1,5)=0.		BLI	50
	A(1,6)=0.		BLI	52
	A(1,7)=0.		BLI	54
	A(1,8)=0.		BLI	56
	A(1,9)=0.		BLI	58
	A(2,1)=-2.*G		BLI	60
	A(2,2)=0.		BLI	62
	A(2,3)=2.0*G*DLCG(G)+G		BLI	64A
	A(2,4)=2.*G		BLI	66
	A(2,5)=1./G		BLI	68
	A(2,6)=0.		BLI	70
	A(2,7)=0.		BLI	72
	A(2,8)=0.		BLI	74
	A(2,9)=0.		BLI	76
	A(3,1)=0.		BLI	78
	A(3,2)=0.		BLI	80

A (3,3) = 1.	B LI 82
A (3,4) = 0.	B LI 84
A (3,5) = 0.	B LI 86
A (3,6) = 0.	B LI 88
A (3,7) = 0.	B LI 90
A (3,8) = 0.	B LI 92
A (3,9) = 0.	B LI 94
A (4,1) = 0.	B LI 96
A (4,2) = 0.	B LI 98
A (4,3) = G*G*DLOG (G)	B LI 100A
A (4,4) = G*G	B LI 102
A (4,5) = DLOG (G)	B LI 104A
A (4,6) = 1.	B LI 106
A (4,7) = 0.	B LI 108
A (4,8) = 0.	B LI 110
A (4,9) = 0.	B LI 112
A (5,1) = -2.6	B LI 114
A (5,2) = 0.	B LI 116
A (5,3) = 2.6*DLOG (G) + 3.3	B LI 118A
A (5,4) = 2.6	B LI 120
A (5,5) = -.7 / (G*G)	B LI 122
A (5,6) = 0.	B LI 124
A (5,7) = 0.	B LI 126
A (5,8) = 0.	B LI 128
A (5,9) = 0.	B LI 130
A (6,1) = 0.	B LI 132
A (6,2) = 0.	B LI 134
A (6,3) = 2.0*C*DLOG (C) + C	B LI 136A
A (6,4) = 2.*C	B LI 138
A (6,5) = 1./C	B LI 140
A (6,6) = 0.	B LI 142
A (6,7) = -2.*C	B LI 144
A (6,8) = -1./C	B LI 146
A (7,4) = 2.6	B LI 156
A (7,8) = .7 / (C*C)	B LI 164
A (6,9) = 0.	B LI 148
A (7,1) = 0.	B LI 150
A (7,2) = 0.	B LI 152
A (7,3) = 2.6*DLOG (C) + 3.3	B LI 154A
A (7,5) = -.7 / (C*C)	B LI 158
A (7,6) = 0.	B LI 160
A (7,7) = -2.6	B LI 162
A (7,9) = 0.	B LI 166
A (8,1) = 0.	B LI 168
A (8,2) = 0.	B LI 170
A (8,3) = 0.	B LI 172
A (8,4) = 0.	B LI 174
A (8,5) = 0.	B LI 176
A (8,6) = 0.	B LI 178
A (8,7) = 2.6	B LI 180
A (8,8) = -.7 / (X A * X A)	B LI 182
A (3,9) = 0.	B LI 184
A (9,1) = 0.	B LI 186
A (9,2) = 0.	B LI 188
A (9,3) = C*C*DLOG (C)	B LI 190A
A (9,4) = C*C	B LI 192
A (9,5) = DLOG (C)	B LI 194A
A (9,6) = 1.	B LI 196
A (9,7) = -C*C	B LI 198
A (9,8) = -DLOG (C)	B LI 200A
A (9,9) = -1.	B LI 202
DO 3 I=1,9	B LI 204
DO 2 J=1,9	B LI 206
AM (I,J) = A (I,J)	B LI 208
2 CONTINUE	B LI 210
3 CONTINUE	B LI 212
C CALCULATION FOR MOMENT LOADING, BLIND FLANGES	B LI 214
MA = 1	B LI 215A
P=0.	B LI 216
W=X*MOA	B LI 218

C	PRINT 23	B LI 220A
	DO 4 I=1,9	B LI 222
	B(I)=0.	B LI 224
4	CONTINUE	B LI 226
	B(3)=-W/(25.1328*I)	B LI 228
	CALL LIN2 (A,9,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPR,LPC)	B LI 230
	IP=0	B LI 232
5	ZC = C*C*B(7) +DLOG(C)*B(8) +B(9)	B LI 234A
	QFHR(IP+1)=ZC	B LI 236
	SORT=-(YM*TH/1.82)*2.6*B(1)	B LI 238
	SGR=-(YM*TH/1.82)*(2.6*B(1)+G*G*P*3.3/(16.*D))	B LI 240
	SGT=-(YM*TH/1.82)*(2.6*E(1)+G*G*1.9*P/(16.*D))	B LI 242
	SCR=-(YM*TH/1.82)*(2.6*B(7)-.7*B(8)/(C*C))	B LI 244
	SCT=-(YM*TH/1.82)*(2.6*B(7)+.7*B(8)/(C*C))	B LI 246
	SAT=-(YM*TH/1.82)*(2.6*E(7)+.7*B(8)/(XA*XA))	B LI 248
C	PRINT 24,ETC,ETC.	B LI 250A
	IP=IP+1	B LI 252
	CALL STOP	B LI 254A
C	GO TO(6,10,14),IP	B LI 254B
	GO TO(6,10),IP	B LI 254C
C	CALCULATION FOR PRESSURE LOADING, BLIND FLANGES	B LI 256
6	P=PRESS	B LI 258
	MA = 2	B LI 259A
	W=0.	B LI 260
C	PRINT 25	B LI 262A
	DO 7 I=1,9	B LI 264
	B(I)=0.	B LI 266
7	CONTINUE	B LI 268
	B(1)=G**4*P/(64.*D)	B LI 270
	B(2)=-G**3*P/(16.*D)	B LI 272
	B(5)=-G*G*P*3.3/(16.*D)	B LI 274
	DO 9 I=1,9	B LI 276
	DO 8 J=1,9	B LI 278
	A(I,J)=AM(I,J)	B LI 280
8	CONTINUE	B LI 282
9	CONTINUE	B LI 284
	CALL LIN2 (A,9,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPR,LPC)	B LI 286
	GO TO 5	B LI 288
C	** DELETED CARDS ELI290-322 OF SUBR. ELINL, C9-19-75.	
C	14 CONTINUE	B LI 324A
	10 CONTINUE	B LI 324B
	IF(MATE.EQ.1) CALL COMBIN	B LI 324C
	IF(CODE-1) 16,14,15	B LI 326A
15	C=C/2.	B LI 328
	CALL ASMEIN	B LI 330
C	PLGDW IS CALLED THRU TAEHUE OR STHUB, 2ND TIME THRU	B LI 332
	PRINT 27	B LI 334A
16	CONTINUE	B LI 334B
	RETURN	B LI 336
C		B LI 338
17	FORMAT (8E10.5)	B LI 340
18	FORMAT (84H FLANGE FLANGE FLANGE PIPE HUB AT HUBLI	B LI 342
	1B BOLT PRESSURE, /84H O.D.,A I.D.,B THICK.,T WABLI	B LI 344
	2LL,GO BASE,G1 LENGTH,H CIRCLE,C P )	B LI 346
19	FORMAT (7F10.5,1F10.3/)	B LI 348
20	FORMAT (5E10.5)	B LI 350
21	FORMAT (98H BOLT COEFF. OF ELIA MOD. OF MEAN GASKET ITBLI	B LI 352
	1TYPE IBOND ICCDE MATE /	B LI 354
	2 51H LOAD THERMAL EXP. ELASTICITY DIAMETER )	B LI 356
22	FORMAT (1F5E10.3,16,3I10//)	B LI 358
23	FORMAT (46H CALCULATIONS FOR BOLT LOADING, ELINL FLANGE//)	B LI 360
24	FORMAT (7H SORT=E12.4,7H SGR=E12.4,7H SGT=E12.4,7H SCR=E1B LI	B LI 362
	12.4,7H SCT=E12.4,7H SAT=E12.4//9H ZC=E12.4//)	B LI 364
25	FORMAT (34H CALCULATIONS FOR PRESSURE LOADING//)	B LI 366
26	FORMAT (34H CALCULATIONS FOR COMBINED LOADING//)	B LI 368
27	FORMAT (1H1)	B LI 370
	END	B LI 372

```

SUBROUTINE ASMEIN                                ASM      2
  IMPLICIT REAL*8 (A-H,O-Z)                      01-28-75
  DIMENSION SS(6,18),SI(18)                      ASM      3A
  COMMON ITYPE,IBCNI,ICCDE,MATE,XA,XB,G,C,PRESS,XGS,XOP,G1,G0,TH,YM,ASM      4
  1AE,QFHR(4),AL,DELTA,XMO,XMOA,QFHGP,QPHGF,QTHGF,BE,SOP,AMP,YFP,RFP,ASM      6
  2DELTA,P,GOUT,GIN,RCG                          ASM      8
  3,SLSO,SLSI,SCSO,SCSI,SLLO,SLLI,SCLO,SCLI,STH   ASM      8A
  4,SFP,SRH,SFF,ZG,ZC,QFHG,Y0,Y1,T1,THETA,SOFT,SGP,SGI,SCR,SCT,SAT  ASM      8B
  5,W2,W1,SS,MA,IF,XM1,XM2,XM2P                 ASM      8C

C
  READ 10, XM,Y,GOUT,GIN,SB,SA,AB,INBO,BO        ASM      10
  PRINT 11                                       ASM      12
  PRINT 12                                       ASM      14
  PRINT 13, XM,Y,GOUT,GIN,SB,SA,AB             ASM      16
  XA=XA*2.                                       ASM      18
  XB=XB*2.                                       ASM      20
  C=C*2.                                         ASM      22
  IF (INBO-1) 1,1,2                              ASM      24
1 BO=(GOUT-GIN)/4.                               ASM      26
2 IF (BO-.25) 3,3,4                              ASM      28
C D = GASKET DIAMETER IN THIS SUBROUTINE        ASM      30
3 D=(GOUT+GIN)/2.                                ASM      32
  B=BO                                           ASM      34
  GO TO 5                                         ASM      36
4 B = DSQR1(BO)/2.0                             ASM      38A
  D=GOUT-2.*B                                    ASM      40
5 P=PRESS                                        ASM      42
  WM1=.7854*D*D*E                                ASM      44
  WM12=6.2832*B*D*XM*P                          ASM      46
  WM1=.7854*D*D*P+6.2832*B*D*XM*P              ASM      48
  SB1=WM1/AB                                     ASM      50
  WM2=3.1416*B*D*Y                              ASM      52
  SB2=WM2/AB                                     ASM      54
  AM1=WM1/SB                                     ASM      56
  AM2=WM2/SA                                     ASM      58
  AM = DMAX1(AM1,AM2)                           ASM      60A
  WGS=(AM+AB)*SA/2.                              ASM      62
  XGS=WGS*(C-D)/2.                              ASM      64
  XGS1=WM2*(C-D)/2.                             ASM      66
  R=(C-XE)/2.-G1                                ASM      68
  H=WM11                                         ASM      70
  HD=.7854*XB*XB*E                              ASM      72
  HT=H-HD                                        ASM      74
  HG=WM1-H                                       ASM      76
  XD=(R+.5*G1)*ED                               ASM      78
  XT=((R+G1+(C-D)/2.)/2.)*HT                   ASM      80
  XG=((C-D)/2.)*HG                              ASM      82
  XOP=XD+XT+XG                                  ASM      84
  ROG=XGS/XOP                                   ASM      86
  PRINT 14                                       ASM      88
  PRINT 15, BO,WM11,WM12,WM1,SB1,WM2,SB2       ASM      90
  IF (ITYPE-2) 6,6,7                             ASM      92
6 PRINT 16                                       ASM      94
  PRINT 17, XOP,XGS,XGS1                        ASM      96
C IN PRINT OUT, MCP=XOP, MGS=XGS, MGS1=XGS1     ASM      98
7 IF (ITYPE-2) 9,9,8                             ASM     100
8 SP=((D/TH)**2)*(.3*E)                          ASM     102
  SW1=((D/TH)**2)*(.178*WM1*(C-D)/2./(D**3))    ASM     104
  SOP=SP+SW1                                     ASM     106
  SW2=((D/TH)**2)*(.178*WM2*(C-D)/2./(D**3))    ASM     108
  SGS=((D/TH)**2)*(.178*WGS*(C-D)/2./(D**3))    ASM     110
  PRINT 18                                       ASM     112
  PRINT 19                                       ASM     114
  PRINT 20, SP,SW1,SOP,SW2,SGS                 ASM     116
9 XA=XA/2.                                       ASM     118
  XE=XB/2.                                       ASM     120
  C=C/2.                                         ASM     122
  RETURN                                         ASM     124
C                                               ASM     126
10 FORMAT (7E10.5,1I2,1E8.5)                   ASM     128

```

11	FORMAT (1H0)						ASM	130
12	FORMAT (10SH	M		Y	GOUT		ASM	132
	1 GIN	SB	SA		AB	)	ASM	134
13	FORMAT (7F15.5//)						ASM	136
14	FORMAT (110H	BC		WM11	WM12		WASM	138
	1M1	SB1	WM2		SB2	)	ASM	140
15	FORMAT (1P7E15.4//)						ASM	142
16	FORMAT (50H	MOE		MGS	MGS1	)	ASM	144
17	FORMAT (1P3E15.4//)						ASM	146
18	FORMAT (47H	ASME	CCDE	STRESSES	FOR	BLIND FLANGE //	ASM	148
19	FORMAT (100H	SP		SW1	SOP		SASM	150
	1W2	SGS				)	ASM	152
20	FORMAT (1P5E15.4//)						ASM	154
	END						ASM	156

	SUBROUTINE FLGDW						FLG	2
C	THIS SUBROUTINE IS CALLED ONLY IF MATE = 2,4,6						FIG	4
	IMPLICIT REAL*8 (A-H,C-Z)							01-28-75
	DIMENSION SB(6,18),SC(18)						FLG	4A
	COMMON ITYPE,IEONL,ICODE,MAIE,XA,XB,G,C,PRESS,XGS,AOP,G1,GO,TH,YM,FLG							6
	1AB,QFHF(4),A1,DELTA,XMO,XMCA,QFHGP,QFHGP,QTHGP,BF,GOP,THP,YFP,EFP,FLG							8
	2DELTA,GOUT,GIN,RCG						FLG	10A
	3,SLSO,SLSI,SCSO,SCSI,SLIO,SILI,SCLO,SCLI,STH						FLG	10B
	4,STF,SBH,SFP,ZC,ZC,QFHG,Y0,Y1,T1,THETA,SOFT,SGR,SGI,SCR,SCT,SAP						FLG	10C
	5,W2,W1,SB,MA,IT,XM1,XM2,XM2P						FLG	10D
C	READ 21, BSIZE,YB,SB,IB,XGO,XGI,AB,VO,YG,EG,TG,FACE,PBE,W1,IF,TFP,FIG							12
	1YF2,YFP2,YB2,YG2						FLG	14
	PRINT 22						FLG	16
	PRINT 25, BSIZE,YE,IB,TB,XGO,XGI,AB						FLG	18
	PRINT 23						FLG	20
	PRINT 26, VO,YG,EG,TG,FACE,PBE						FLG	22
	PRINT 24						FLG	24
	PRINT 27, W1,IF,TFP,YF2,YFP2,YB2,YG2						FLG	26
	C=2.*C						FIG	28
	GO TO (1,1,20,2,20,2), MATE						FLG	30
1	QFHR(1)=QFHR(1)/XMCA						FLG	32
	QFHR(2)=QFHR(2)/PRESS						FLG	34
	QFHR(3)=QFHR(3)/DELTA						FLG	36
	QFHGP=QFHR(1)						FLG	38
	QFHG=QFHGP						FLG	40
	QPHGP=QFHR(2)						FLG	42
	QFHG=QPHGP						FIG	44
	QTHGP=QFHR(3)						FLG	46
	QTHG=QTHGP						FLG	48
	BP=XB*2.						FLG	50
	B=BP						FLG	52
	GUP=GO						FLG	54
	THP=TH						FLG	56
	YFP=YM						FLG	58
	YF=YFP						FLG	60
	EFP=AL						FLG	62
	EF=EFP						FLG	64
	DELTA P=DELTA						FLG	66
	XLB=2.*TH+VC+FACE+BSIZE						FLG	68
	TFP=TF						FLG	70
	YFP2=YFP2						FLG	72
	GO TO 3						FLG	74
2	QFHG=QFHR(1)/XMCA						FLG	76

```

QPHG=QFHP (2) / ERESSE
QTHG=QFHS (3) / DELTA
S=XB*2.
YF=YM
EF=EL
XLB=THI+TH+VC+FACI+BSIZE
3 P=PFESS
QB1=XLB/(AB*YE)
QF2=XLE/(A3*YE2)
G=(XGO+XGI)/2.
AG=(XGO-XGI)*1.5708*G
QG1=VO/(AG*YG)
QG2=VO/(AG*YG2)
HG=(C-G)/2.
QF1=QFHG/HG
QF2=QF1*(YF/YF2)
IF (MATE-5) 5,5,4
4 QFP1=QFHG/(HG*HG)
GO TO 6
5 QFP1=QFHGP/HG
6 QFP2=QF1*(YFE/YFE2)
Q1=QB1+QG1+HG*HG*(QF1+QFP1)
Q2=QB2+QG2+HG*HG*(QF2+QFP2)
HT=(C-(G+B)/2.)/2.
HTP=(C-(G+BP)/2.)/2.
HD=(C-B-G)/2.
HDP=(C-EP-GOP)/2.
COFAL=.7854*HG/Q1
W2A=W1+(1./Q1)*(-TB*EB*XLB+TG*EG*VO+TF*EF*TH+TFP*EFP*THP)
IF (MATE-5) 8,8,7
7 W2B=W1+COFAL*((CG1/HG-QF1*(HT-HG))*G*G-QF1*B*B*(HL-HT))*P
GO TO 9
8 W2B=W1+COFAL*((CG1/HG-QF1*(HT-HG)-QFP1*(HTP-HG))*G*G-(QF1*B*B*(HD-FLG
1HT)+QFP1*BP*BP*(HIE-HTP)))*P+PBE
9 W2C=W2B-(QPHG/HG+QFHGP/HG)*P*HG/Q1
IF (MATE-5) 11,11,10
10 W2D=W1-(QTHG/HG)*DELTA*HG/Q1
GO TO 12
11 W2D=W1-(QTHG*DELTA+QTHGP*DELTA*P)/Q1
12 IF (MATE-5) 14,14,13
13 W2=(Q1/Q2)*W1+(1./Q2)*(-TB*EB*XLB+TG*EG*VO+TF*EF*TH+TFP*EFP*THP)*
1Q1/Q2)*COFAL*((CG2/HG-QF2*(HT-HG))*G*G-QF2*B*B*(HL-HT))*P-(QPHG/HG
2G)*(YF/YF2)+(QFHGP/HG)*(YFP/YFP2))*P*HG/Q2-(QTHG/HG)*(YF/YF2)*DELTA
3A*HG/Q2
GO TO 15
14 W2=(Q1/Q2)*W1+(1./Q2)*(-TB*EB*XLB+TG*EG*VO+TF*EF*TH+TFP*EFP*THP)*
1Q1/Q2)*COFAL*((CG2/HG-QF2*(HT-HG)-QFP2*(HTP-HG))*G*G-(QF2*B*B*(HD-FLG
2HT)+QFP2*BP*BP*(HIE-HTP)))*P+PBE-(QPHG/HG)*(YF/YF2)+(QFHGP/HG)*P
3(YFE/YFE2))*P*HG/Q2-(QTHG*DELTA*(YF/YF2)+QTHGP*DELTA*P*(YFE/YFE2))/
4Q2
15 GO TO (20,16,20,17,20,18), MATE
16 PRINT 28
GO TO 19
17 PRINT 29
GO TO 19
18 PRINT 30
19 PRINT 31
PRINT 32, QPHG, QFHG, QTHG, BP, GOP, THP, YFE, YFP2, EFP
PRINT 33
PRINT 32, QPHG, QFHG, QTHG, E, GO, TH, YF, YF2, EF
PRINT 34
PRINT 35, XLB, AB, C, YB, YB2, EB
PRINT 36
PRINT 37, VO, XGO, XGI, YG, YG2, EG
PRINT 40
PRINT 38
PRINT 39, W1, IB, TF, TFP, TG, DELTA, DELTAP, P
PRINT 40
PRINT 41, W2A, W2B, W2C, W2D, W2
DWA=W1-W2A

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FLG 78
FLG 80
FLG 82
FLG 84
FLG 86
FLG 88
FLG 90
FLG 92
FLG 94
FLG 96
FLG 98
FLG 100
FLG 102
FLG 104
FLG 106
FLG 108
FLG 110
FLG 112
FLG 114
FLG 116
FLG 118
FLG 120
FLG 122
FLG 124
FLG 126
FLG 128
FLG 130
FLG 132
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FLG 136
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FLG 142
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FLG 150
FLG 152
FLG 154
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FLG 158
FLG 160
FLG 162
FLG 164
FLG 166
FLG 168
FLG 170
FLG 172
FLG 174
FLG 176
FLG 178
FLG 180
FLG 182
FLG 184
FLG 186
FLG 188
FLG 190
FLG 192
FLG 194
FLG 196
FLG 198
FLG 200
FLG 202
FLG 204
FLG 204A
FLG 206
FLG 208
FLG 210
FLG 212
FLG 214

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DWB=W1-W2B
DWC=W1-W2C
DWD=W1-W2D
DWCO=W1-W2
PRINT 42, DWA,DWB,DWC,DWD,DWCO
RA=W2A/W1
RB=W2E/W1
RC=W2C/W1
RD=W2D/W1
RCO=W2/W1
PRINT 43, RA,RE,RC,RD,RCO
PRINT 47
47 FORMAT (//6X,'INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE',
E,' LOADS.' / )
XM1=W1*HG
XM2A=W2A*HG
XM2L=W2E*HG+.7854*P*(B*B*HD+(G*G-B*B)*HT-G*G*HG)
XM2C=W2C*HG+.7854*P*(B*B*HD+(G*G-B*B)*HT-G*G*HG)
XM2D=W2D*HG
XM2=W2*HG+.7854*P*(B*B*HD+(G*G-B*B)*HT-G*G*HG)
PRINT 44, XM1,XM2A,XM2B,XM2C,XM2D,XM2
XM2BP=W2B*HG+.7854*P*(BP*BP*HDP+(G*G-BP*BP)*HTP-G*G*HG)
XM2CP=W2C*HG+.7854*P*(CP*CP*HDP+(G*G-BP*BP)*HTP-G*G*HG)
XM2P=W2*HG+.7854*P*(B*E*E*HIP+(G*G-BP*BP)*HTP-G*G*HG)
PRINT 45, XM2BP,XM2CP,XM2P
C PRINT 30,QE1,QE2,G,AG,QG1,QG2,HG,QF1,QF2,QFP1,QFP2,Q1,Q2,
C 1 HT,HTP,HD,HIE,COFAL
C 30 FORMAT (//10E12.4// 8E12.4)
C 20 PRINT 46
C 20 CONTINUE
C RETURN
C
21 FORMAT (7E10.5/6E10.5/7E10.5)
22 FORMAT (106H BSIZE YB EB TFIG 274
1B XGO XGI AB )
23 FORMAT (106H VO YG EG TFIG 278
1G FACE FBE )
24 FORMAT (106H W1 TF TFP YFP1 YFP2 )
25 FORMAT (1P7E15.4)
26 FORMAT (1P6E15.4)
27 FORMAT (1P7E15.4//)
28 FORMAT (80H FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOAD
1S, IDENTICAL PAIR //)
29 FORMAT (82H FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOAD
1S, INTEGER TO INTEGER PAIR //)
30 FORMAT (80H FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOAD
1S, BLIND TO INTEGER PAIR //)
31 FORMAT (54H FLANGE JOINT SIDE ONE (PRIMED QUANTITIES) /
1)
32 FORMAT (7H QPHG=1PE12.4,7H QPHG=E12.4,7H QTHG=E12.4,7H XB =E1P
12.4,9H GO=E12.4,12H TH =E12.4/12H YM =E12.4,14H YF1
2 YF2 =E12.4,8H EF =E12.4/)
33 FORMAT (54H FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES) /
1)
34 FORMAT (17H ECLTING/)
35 FORMAT (14H BOLT LENGTH=1PE12.4,12H BOLT AREA=E12.4,14H BOLT CIP
1PCLE=E12.4/12H YB =E12.4,13H YE2 =E12.4,8H EB =E1P
22.4/)
36 FORMAT (16H GASKET/)
37 FORMAT (9H VC =1PE12.4,7H XGO =E12.4,7H XGI =E12.4/12H
1 YG =E12.4,13H YG2 =E12.4,8H LG =E12.4/)
38 FORMAT (18H ICADINGS/)
39 FORMAT (20H INITIAL BOLT LOAD=1PE12.4,13H BOLT TEMP.=E12.4,20H
1 FLANGE ONE TEMP.=E12.4,20H FLANGE TWO TEMP.=E12.4/15H GASKET T
2EMP.=E12.4,9H DELTA=E12.4,10H DELTAT=E12.4,11H PRESSURE=E12.4P
3/)
40 FORMAT (53H RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS/)
41 FORMAT (20H AXIAL THERMAL,W2A=1PE12.4,19H MOMENT SHIFT,W2B=E12.4P
1//21H TOTAL PRESSURE,W2C=E12.4,21H DELTA THERMAL,W2D=E12.4//14H

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2 COMBINED, W2=E12.4)                                FLG 348
42 FORMAT (/9H W1-W2A=1PE12.4,9H W1-W2B=E12.4,9H W1-W2C=E12.4,9H FLG 350
1 W1-W2D=E12.4,9H W1-W2=E12.4)                       FIG 352
43 FORMAT (/9H W2A/W1=1E12.4,9H W2B/W1=E12.4,9H W2C/W1=E12.4,9H FLG 354
1W2D/W1=E12.4,8H W2/W1=E12.4)                       FIG 356
44 FORMAT (/5H M1=1E12.4,6H M2A=E12.4,6H M2B=E12.4,6H M2C=E12.4,6H FLG 358
16H M2D=E12.4,5H M2=E12.4)                           FLG 360
45 FORMAT (/7H M2BP=1PE12.4,7H M2CP=E12.4,6H M2P=E12.4) FLG 362
46 FORMAT (1H1)                                       FLG 364
END                                                    FLG 366

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SUBROUTINE LIN2(A,N,NN,EPS,B,M,MM,LTEMP,IERR,DET,NP1V,P1V,LPR, 3046A001
1 LFC)                                                8046A002
IMPLICIT REAL*8 (A-H,O-Z)                            L IN 2 02A
DIMENSION A(NN,N),B(MM,M)                            3046A003
DIMENSION LTEMP(1),LPR(1),LFC(1)                    8046A004
C                                                    8046A005
C SUBROUTINE LIN2                                    3046A006
C DFCK 8046A                                         8046A007
C                                                    8046A008
C SUBROUTINES CALLED - MCNE                          8046A009
C                                                    3046A010
C THIS ROUTINE SOLVES THE MATRIX EQUATION AX+B=C OVERWRITING B WITH THE 3046A011
C SOLUTION MATRIX X. A MUST BE SQUARE AND NON-SINGULAR. B MUST      8046A012
C HAVE THE SAME NUMBER OF ROWS AS A. THE DETERMINANT OF A IS        3046A013
C COMPUTED. BOTH A AND I ARE DESTROYED.              8046A014
C                                                    8046A015
C THIS ROUTINE IS RECOMMENDED FOR THE SOLUTION OF SIMULTANEOUS LINEAR 3046A016
C EQUATIONS.                                         8046A017
C                                                    8046A018
C THE METHOD CONSISTS OF GAUSSIAN ELIMINATION FOLLOWED BY BACK        3046A019
C SUBSTITUTIONS. THIS IS MORE EFFICIENT THAN SOLUTION BY MATRIX     8046A020
C INVERSION REGARDLESS OF THE NUMBER OF COLUMNS IN B. BOTH ROWS AND 3046A021
C COLUMNS ARE SEARCHED FOR MAXIMAL PIVOTS. INTERCHANGING OF ROWS OR 8046A022
C COLUMNS OF A IS AVOIDED. CHAPTER 1 OF E.L. STIEFLE, INTRODUCTION TO 8046A023
C NUMERICAL MATHEMATICS, ACADEMIC PRESS, N.Y., 1963, SHOULD BE HELPFUL IN 8046A024
C FOLLOWING THE CODE.                                       8046A025
C                                                    3046A026
C THE CALLING PROGRAM MUST SET A,N,NN,EPS,B,M,MM,LTEMP TO-        3046A027
C                                                    8046A028
C A-THE COEFFICIENT MATRIX                                3046A029
C                                                    8046A030
C N-THE ORDER OF A                                       3046A031
C                                                    3046A032
C NN-THE NUMBER OF WORDS OF STORAGE PROVIDED FOR EACH COLUMN OF    8046A033
C A IN THE CALLING PROGRAM                                3046A034
C                                                    8046A035
C EPS-A NON-NEGATIVE NUMBER WHICH EACH PIVOT IN THE ELIMINATION    8046A036
C PROCESS IS REQUIRED TO EXCEED IN ABSOLUTE VALUE (CUSTOMARILY      8046A037
C ZERO)                                                  8046A038
C                                                    3046A039
C B-THE CONSTANT TERM MATRIX                              8046A040
C                                                    8046A041
C M-THE NUMBER OF COLUMNS OF B                          3046A042
C                                                    8046A043
C P IN THE CALLING PROGRAM                                3046A044
C MM-THE NUMBER OF WORDS OF STORAGE PROVIDED FOR EACH COLUMN OF    3046A045
C                                                    8046A046
C LTEMP-A BLOCK OF AT LEAST N WORDS OF TEMPORARY INTEGER STORAGE 8046A047

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C
C IN ADDITION TO OVERWRITING B WITH THE SOLUTION MATRIX X,THE ROUTINE
C SETS IERR,DET,NPIV,PIV,IPF,ANI LPC TO
C
C IERR- 2 IF NO COLUMNS OF X ARE FOUND, THE ELIMINATION PROCESS
C BEING HAILED BECAUSE THE CURRENT PIVOT FAILS TO EXCEED
C EPS IN MAGNITUDE
C
C C IF ALL COLUMNS OF X ARE FOUND, NO TROUBLE BEING DETECTED
C
C DET-PLUS OR MINUS THE PRODUCT OF THE CURRENT AND ALL PRECEDING
C PIVOTS
C
C NPIV-THE NUMBER OF THE CURRENT PIVOT (FIRST,SECOND,ETC.)
C
C PIV-THE CURRENT PIVOT
C
C LPR-THE FIRST NPIV POSITIONS LIST THE PIVOT ROW INDICES IN ORDER
C OF USE,A VECTOR OF LENGTH N
C
C LPC-THE FIRST NPIV POSITIONS LIST THE PIVOT COLUMN INDICES IN
C ORDER OF USE,A VECTOR OF LENGTH N
C
C IF THE ELIMINATION PROCESS IS HAILED PREMATURELY (IERR NEGATIVE),THEN
C THE DATA NPIV,PIV,IERR,LPC,MAY BE HELPFUL IN DIAGNOSING THE UNDERLYING
C CAUSE OF THE TROUBLE. IF THE PROCESS GOES TO COMPLETION THEN NPIV=N,
C DET SHOULD BE THE DETERMINANT OF A,PIV WILL BE THE NTH PIVOT,AND LPR
C AND LPC LIST ALL PIVOT POSITIONS.
C
C DO INITIALIZATIONS
C
C   1 IERR=0
C     DET=1.
C     DO 2 I=1,N
C       LPR(I)=I
C     2 LPC(I)=I
C
C BEGIN ELIMINATION PROCESS
C
C   DO 18 NP=1,N
C     NPIV=NP
C
C SELECT PIVOT
C
C   PIV=0.
C   DO 4 K=NP,N
C     I=LPR(K)
C     DO 4 L=NP,N
C       J=LPC(L)
C       IF( DABS(A(I,J))-DABS(PIV) ) 4,3,3
C     3 KPIV=K
C       LPIV=L
C       IPIV=I
C       JPIV=J
C       PIV=A(I,J)
C     4 CONTINUE
C
C UPDATE DETERMINANT AND PIVOT ROW AND COLUMN LISTS
C
C   DET=DET*PIV
C   ITEMP=LPR(NP)
C   LPR(NP)=LPR(KPIV)
C   LPR(KPIV)=ITEMP
C   ITEMP=LPC(NP)
C   LPC(NP)=LPC(LPIV)
C   LPC(LPIV)=ITEMP
C
C EXIT IF PIVOT TOO SMALL
C
C   IF( EPS-DABS(PIV) ) 8,7,7

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8046A048
8046A049
8046A050
8046A051
8046A052
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LIN2 97A
8046A098
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8046A101
8046A102
8046A103
8046A104
8046A105
8046A106
8046A107
8046A108
8046A109
8046A110
8046A111
8046A112
8046A113
8046A114
8046A115
8046A116
LIN2 117A

```

7	IERR= 2	8046A118
	RETURN	8046A119
C		8046A120
C	MODIFY PIVOT ROW OF A AND B (ELEMENTS IN PRESENT OR PREVIOUS PIVOT	8046A121
C	COLUMNS OF A ARE SKIPPED)	8046A122
C		8046A123
	8 IF (NP-N) 9, 11, 9	8046A124
	9 NNP=NP+1	8046A125
	DO 10 L=NNP, N	8046A126
	J=LPC (I)	8046A127
	10 A (IPIV, J) = -A (IPIV, J) / PIV	8046A128
	11 DO 12 J=1, M	8046A129
	12 B (IPIV, J) = -B (IPIV, J) / PIV	8046A130
C		8046A131
C	MODIFY NON-PIVOT ROWS OF A AND B (ELEMENTS IN PRESENT OR PREVIOUS	8046A132
C	PIVOT ROWS OR COLUMNS ARE SKIPPED)	8046A133
C		8046A134
	IF (NP-N) 13, 18, 13	8046A135
	13 DO 17 K=NNP, N	8046A136
	I=LPR (K)	8046A137
	TEMP=A (I, JPIV)	8046A138
	IF (TEMP) 14, 17, 14	8046A139
	14 DO 15 L=NNP, N	8046A140
	J=LPC (L)	8046A141
	15 A (I, J) = A (I, J) + A (IPIV, J) * TEMP	8046A142
	DO 16 J=1, M	8046A143
	16 B (I, J) = B (I, J) + B (IPIV, J) * TEMP	8046A144
	17 CONTINUE	8046A145
	18 CONTINUE	8046A146
C		8046A147
C	END ELIMINATION PHASE	8046A148
C		8046A149
C	DO BACK SUBSTITUTIONS	8046A150
C		8046A151
	DO 23 J=1, M	8046A152
	DO 21 K=2, N	8046A153
	KK=N-K+1	8046A154
	I=LPR (KK)	8046A155
	DO 21 L=2, K	8046A156
	LL=N-L+2	8046A157
	II=LPR (LL)	8046A158
	JJ=LPC (LL)	8046A159
	21 B (I, J) = B (I, J) + B (II, J) * A (I, JJ)	8046A160
	23 CONTINUE	8046A161
C		8046A162
C	UNSCRAMBLE ROWS OF SOLUTION MATRIX AND ADJUST SIGN OF DETERMINANT	8046A163
C		8046A164
	DO 24 I=1, N	8046A165
	L=LPR (I)	8046A166
	24 LTEMP (I) = IPC (I)	8046A167
	DO 28 I=1, N	8046A168
	25 K=LTEMP (I)	8046A169
	IF (I-K) 26, 28, 26	8046A170
	26 DET=-DET	8046A171
	DO 27 J=1, M	8046A172
	TEMP=B (I, J)	8046A173
	B (I, J) = B (K, J)	8046A174
	27 B (K, J) = TEMP	8046A175
	LTEMP (I) = LTEMP (K)	8046A176
	LTEMP (K) = K	8046A177
	GO TO 25	8046A178
	28 CONTINUE	8046A179
	RETURN	8046A180
	END	8046A181

```

SUBROUTINE COMBIN
IMPLICIT REAL*8 (A-H,O-Z)
DIMENSION S(6,18) , SC(18)
DATA SC/18*0.0/
COMMON ITYPE, IEONI, ICODE, MATE, XA, XB, G, C, PRESS, XGS, XOP, G1, G2, TH, YM, FLA
1 AB, QFHR(4), AL, DELTA, XMO, XMCA, QFHGE, QPHGE, QTHGP, BP, GOP, PHP, YFP, ZFP, FLA
2 DELTAP, GOUT, GIN, ROG, SLSO, SLSI, SC SO, SCSI, SILO, SLLI, SCLO, SCLI, SIH,
3 STF, SRH, SRF, ZG, ZC, QFHG, Y0, Y1, T1, THEIA, SCAT, SGF, SGT, SCA, SCT, SAT,
4 W2, W1, S, MA, IT, XM1, XM2, XM2P, IT2

```

C

```

IC = 0
IF(MATE.LE.2) IT=ITYPE
GO TO( 1, 2, 3 ), IT
1 IC = IC + 1
IF(IC.GT.2) GO TO 99
IF(MATE.GT.1) PRINT 49
PRINT 50
NN = 18
DO 4 MA = 1, 3
GO TO( 5, 6, 7 ), MA
5 PRINT 53
GO TO 8
6 PRINT 54
GO TO 8
7 PRINT 55
8 GO TO( 12, 13 ), IC
12 PRINT 60, (S(MA, I), I=1, NN)
GO TO 4
13 PRINT 60, (S(MA+3, I), I=1, NN)
4 CONTINUE
IF(MATE.EQ.1) GC TC 99
DO 9 I=1, NN
GO TO( 10, 11 ), IC
10 SC(I) = S(1, I)*XM2P/XM1+S(2, I) + S(3, I)
GO TO 9
11 SC(I) = S(4, I)*XM2/XM1+ S(5, I) + S(6, I)
9 CONTINUE
GO TO( 40, 41 ), IC
40 PRINT 56, XM2P
GO TO 42
41 PRINT 56, XM2
42 PRINT 60, (SC(I), I=1, NN)
IF(MATE.EQ.2) GC TC 99
IF(IT.EQ.IT2) GO TO 1
IF(MATE.EQ.4) GC TC 2
IF(MATE.EQ.6) GO TO 99
2 IC = IC + 1
IF(IC.GT.2) GO TO 99
IF(MATE.GT.1) PRINT 49
PRINT 51
NN = 13
DO 14 MA = 1, 3
GO TO( 15, 16, 17 ), MA
15 PRINT 53
GO TO 18
16 PRINT 54
GO TO 18
17 PRINT 55
18 GO TO( 22, 23 ), IC
22 PRINT 61, (S(MA, I), I=1, NN)
GO TO 14
23 PRINT 61, (S(MA+3, I), I=1, NN)
14 CONTINUE
IF(MATE.EQ.1) GC TC 99
DO 19 I=1, NN
GO TO( 20, 21 ), IC
20 SC(I) = S(1, I)*XM2P/XM1+S(2, I) + S(3, I)
GO TO 19
21 SC(I) = S(4, I)*XM2/XM1+ S(5, I) + S(6, I)
19 CONTINUE
GO TO( 43, 44 ), IC

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```

43 PRINT 56, XM2F
GO TO 45
44 PRINT 56, XM2
45 PRINT 61, (SC(I), I=1, NN)
IF(MATE.EQ.2) GC IC 99
IF(IT.EQ.IT2) GO TO 2
IF(MATE.EQ.4) GC IC 1
IF(MATE.EQ.6) GO TO 99
3 IC = IC + 1
IF(MATE.GT.1) PRINT 49
PRINT 52
NN = 7
DO 24 MA=1, 2
GO TO ( 25, 26 ), MA
25 PRINT 57
GO TO 28
26 PRINT 54
28 PRINT 62, (S(MA, 1), I=1, NN)
24 CONTINUE
IF(MATE.EQ.1) GC IC 99
DO 29 I=1, NN
SC(I) = S(1, I)*W2/W1 + S(2, I)
29 CONTINUE
PRINT 56, W2
PRINT 62, (SC(I), I=1, NN)
GO TO ( 1, 2 ), ITYPE
99 PRINT 49
RETURN
49 FORMAT (1H1)
50 FORMAT (/50H TAPERED HUB FLANGE //)
51 FORMAT (/50H STRAIGHT HUB FLANGE //)
52 FORMAT (/50H BLIND FLANGE //)
53 FORMAT(50H CALCULATIONS FOR MOMENT LOADING //)
54 FORMAT(50H CALCULATIONS FOR PRESSURE LOADING //)
55 FORMAT(50H CALCULATIONS FOR TEMPERATURE LOADING //)
56 FORMAT( 36H CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITY
1PE=1 OR 2, W2 FOR ITYPE=3, = 1PE12.4 //)
57 FORMAT(50H CALCULATIONS FOR BOLT LOADING //)
60 FORMAT (7H SLSO=1PE12.4, 7H SLSI=E12.4, 7H SC50=E12.4, 7H SC5I=E1TAP 900
12.4//7H SLL0=E12.4, 7H SLLI=E12.4, 7H SC10=E12.4, 7H SCL1=E12.4//TAP 902
27H STH=E12.4, 7H STF=E12.4, 7H SRH=E12.4, 7H SRF=E12.4//5H ZTAP 904
3G=E12.4, 5H ZC=E12.4, 7H QFHG=E12.4, 5H Y0=E12.4, 5H Y1=E12.4, 8H TAF 906
4THETA=E12.4// TAP 908
61 FORMAT (7H SISO=1PE12.4, 7H SISI=E12.4, 7H SC50=E12.4, 7H SC5I=E1STH 422
12.4//7H STH=E12.4, 7H STF=E12.4, 7H SRH=E12.4, 7H SRF=E12.4//5H 424
25H ZG=E12.4, 5H ZC=E12.4, 7H QFHG=E12.4, 5H Y0=E12.4, 8H THETA=E1STH 426
32.4// STH 428
62 FORMAT (7H SORT=1PE12.4, 7H SGR=E12.4, 7H SGT=E12.4, 7H SCR=E1BLI 362
12.4, 7H SCT=E12.4, 7H SAT=E12.4//9H ZC=E12.4//) BLI 364
END

```

## SUBROUTINE STORE

```

IMPLICIT REAL*8 (A-H, C-Z)
DIMENSION S(6, 18), SC(18)
COMMON ITYPE, IBONI, ICODE, MATE, XA, XB, G, C, PRESS, XGS, XOP, S1, GO, TH, YM, FIA 4
1AB, QFHR(4), AL, DELTA, XMO, XMOA, QFHGE, QFHGI, CT HGE, BP, SOP, FHP, YFP, AFP, FLA 5
2DELTA, GOUT, GIN, RCG, SLSO, SLSI, SC50, SC5I, SILO, SLLI, SCLO, SCLI, STH,
3 SIF, SRH, SRF, ZG, ZC, QFHG, Y0, Y1, T1, THETA, SORT, SGR, SGT, SCR, SCT, SAT,
4 W2, W1, S, MA, IT, XM1, XM2, XM2F

```

```

      GO TO( 4, 4, 4, 5, 4, 5 ), MATE
5 MA = MA + 3
4 GO TO( 1, 2, 3 ), ITYPE
1 S(MA, 1) = SISC
  S(MA, 2) = SISI
  S(MA, 3) = SCSO
  S(MA, 4) = SCSI
  S(MA, 5) = SLLO
  S(MA, 6) = SLII
  S(MA, 7) = SCLO
  S(MA, 8) = SCII
  S(MA, 9) = STH
  S(MA, 10) = STF
  S(MA, 11) = SFE
  S(MA, 12) = SRF
  S(MA, 13) = ZG
  S(MA, 14) = ZC
  S(MA, 15) = QFHG
  S(MA, 16) = YO
  S(MA, 17) = Y1
  S(MA, 18) = I1
  GO TO 50
2 S(MA, 1) = SISC
  S(MA, 2) = SLSI
  S(MA, 3) = SCSC
  S(MA, 4) = SCSI
  S(MA, 5) = STH
  S(MA, 6) = STF
  S(MA, 7) = STH
  S(MA, 8) = SFF
  S(MA, 9) = ZG
  S(MA, 10) = ZC
  S(MA, 11) = QFHG
  S(MA, 12) = YO
  S(MA, 13) = IHETA
  GO TO 50
3 S(MA, 1) = SCRT
  S(MA, 2) = SGR
  S(MA, 3) = SGT
  S(MA, 4) = SCR
  S(MA, 5) = SCT
  S(MA, 6) = SAT
  S(MA, 7) = ZC
50 RETURN
  END

```

STORE

STORE



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